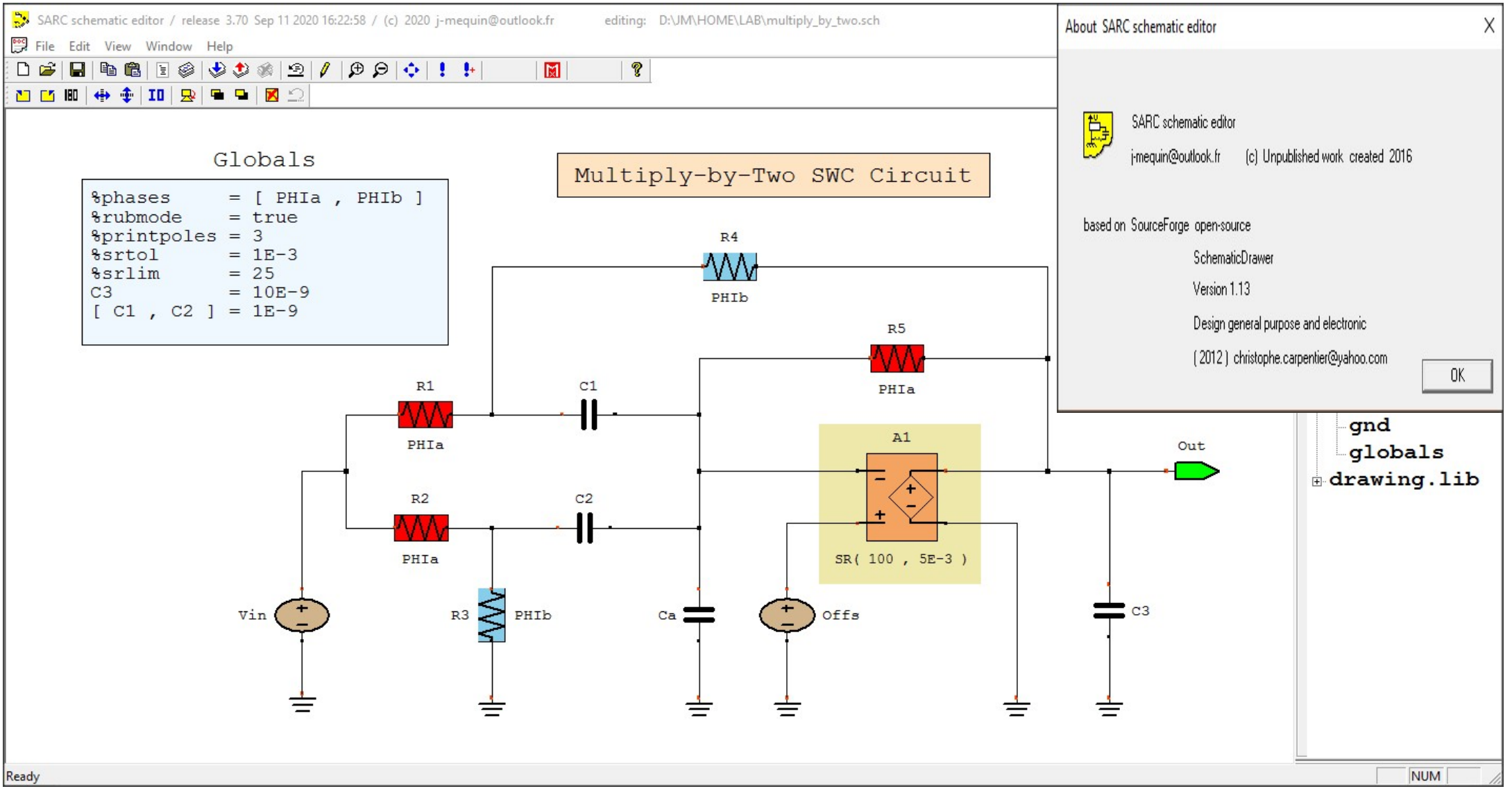


WARNING :

Attempting to change the value of some components during a simulation will not interrupt the execution but its outcome may become ***silently misleading***

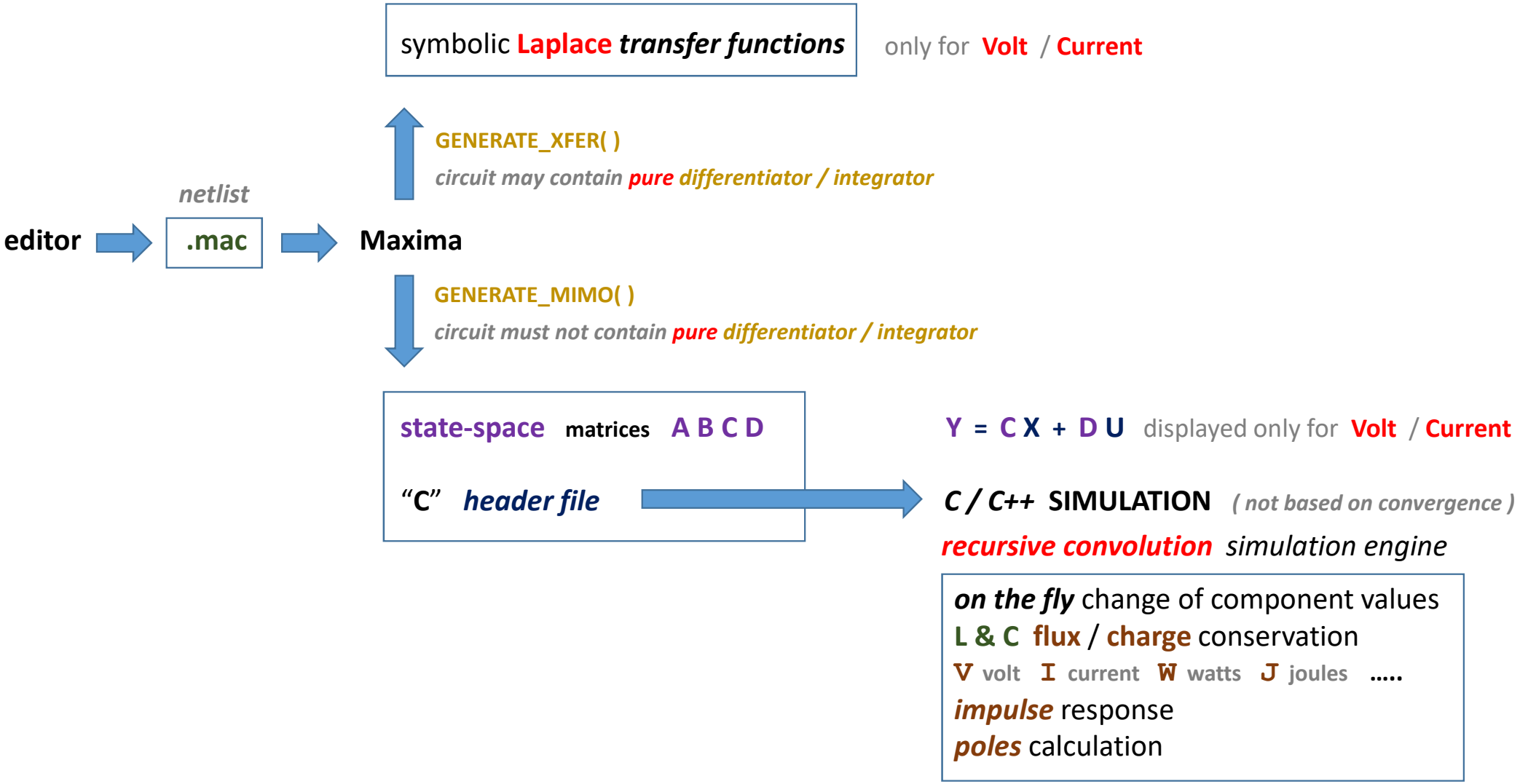
Depending on the* topology *of the circuit, some ***flux*** and/or ***charge*** may have to be partially redistributed on some other components
(trivial example : *changing the value of a capacitor in parallel with another one*)

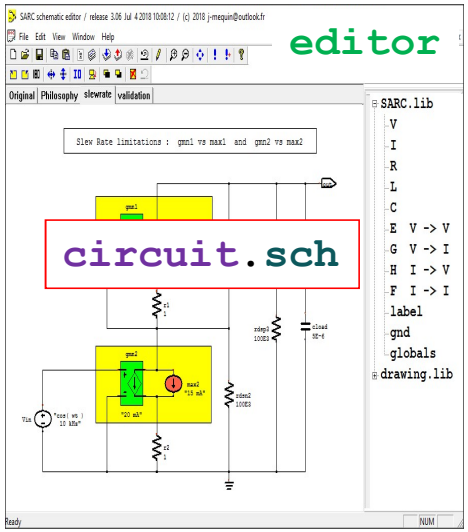
Therefore, simulating accurately component "***percussions***" requires some additional analysis, equations and processing

For ***Laplace transfer function*** (**XFER / ILT**) and ***Z transform*** (**ZTRANS**) such functionality has not been implemented and simulations may turn to be ***silently misleading***

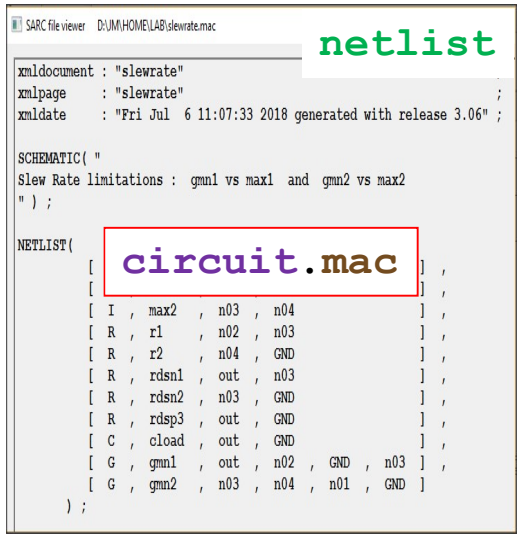
In summary,

only *STATE model* (MIMO) is able to simulate accurately "*on the fly*" component changes

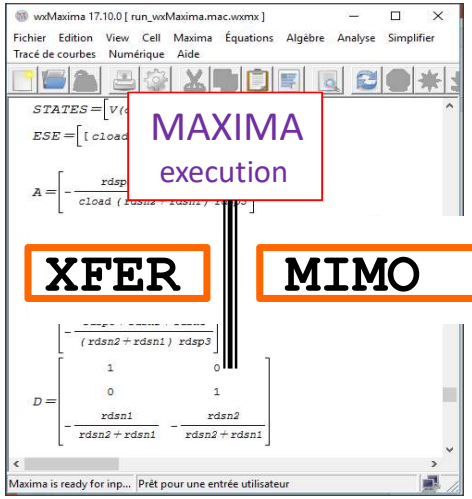

symbolic Laplace transfer functions
only for Volt / Current
GENERATE_XFER( )
circuit may contain pure differentiator / integrator
netlist
editor
.mac
Maxima
GENERATE_MIMO( )
circuit must not contain pure differentiator / integrator
state-space matrices A B C D
"C" header file
Y = C X + D U displayed only for Volt / Current
C / C++ SIMULATION (not based on convergence)
recursive convolution simulation engine
on the fly change of component values
L & C flux / charge conservation
V volt I current W watts J joules .....
impulse response
poles calculation


editor
circuit.sch
SARC.lib
V
I
R
L
C
E V -> V
G V -> I
H I -> V
F I -> I
label
gnd
globals
drawing.lib

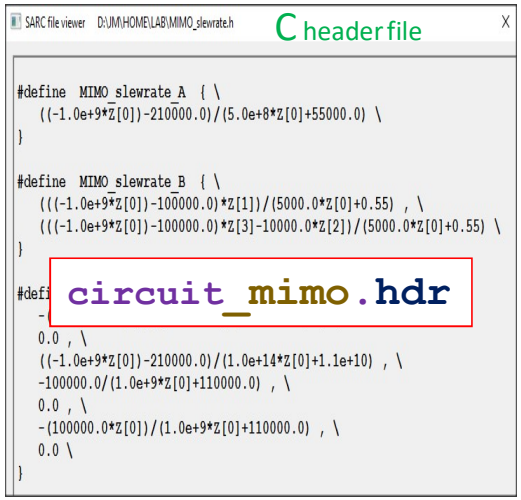
1


SARC file viewer D:\JM\HOME\LAB\slewrate.mac
netlist
xmldocument : "slewrate"
xmlpage : "slewrate"
xmldate : "Fri Jul 6 11:07:33 2018 generated with release 3.06" ;
SCHEMATIC("
Slew Rate limitations : gmn1 vs max1 and gmn2 vs max2
") ;
NETLIST(
circuit.mac
[I , max2 , n03 , n04] ,
[R , r1 , n02 , n03] ,
[R , r2 , n04 , GND] ,
[R , rdsn1 , out , n03] ,
[R , rdsn2 , n03 , GND] ,
[R , rdsp3 , out , GND] ,
[C , cload , out , GND] ,
[G , gmn1 , out , n02 , GND , n03] ,
[G , gmn2 , n03 , n04 , n01 , GND]
) ;

2


wxMaxima 17.10.0 [run_wxMaxima.mac.wxmx]
Fichier Edition View Cell Maxima Équations Algèbre Analyse Simplifier
Tracé de courbes Numérique Aide
MAXIMA
execution
XFER
MIMO
Maxima is ready for inp...
Prêt pour une entrée utilisateur

3


SARC file viewer D:\JM\HOME\LAB\MIMO_slewrate.h
C header file
#define MIMO_slewrate_A { \
((-1.0e+9*Z[0])-210000.0)/(5.0e+8*Z[0]+55000.0) \
}
#define MIMO_slewrate_B { \
(((-1.0e+9*Z[0])-100000.0)*Z[1])/(5000.0*Z[0]+0.55) , \
(((-1.0e+9*Z[0])-100000.0)*Z[3]-10000.0*Z[2])/(5000.0*Z[0]+0.55) \
}
circuit_mimo.hdr
0.0 , \
((-1.0e+9*Z[0])-210000.0)/(1.0e+14*Z[0]+1.1e+10) , \
-100000.0/(1.0e+9*Z[0]+110000.0) , \
0.0 , \
-(100000.0*Z[0])/(1.0e+9*Z[0]+110000.0) , \
0.0 \
}

4

NAPA

A **schematic XML** file is called a **" DOCUMENT "** that can be

displayed on a resizable window

that may contain several **" PAGEs "**

Each **" PAGE "** is a ***" container "***

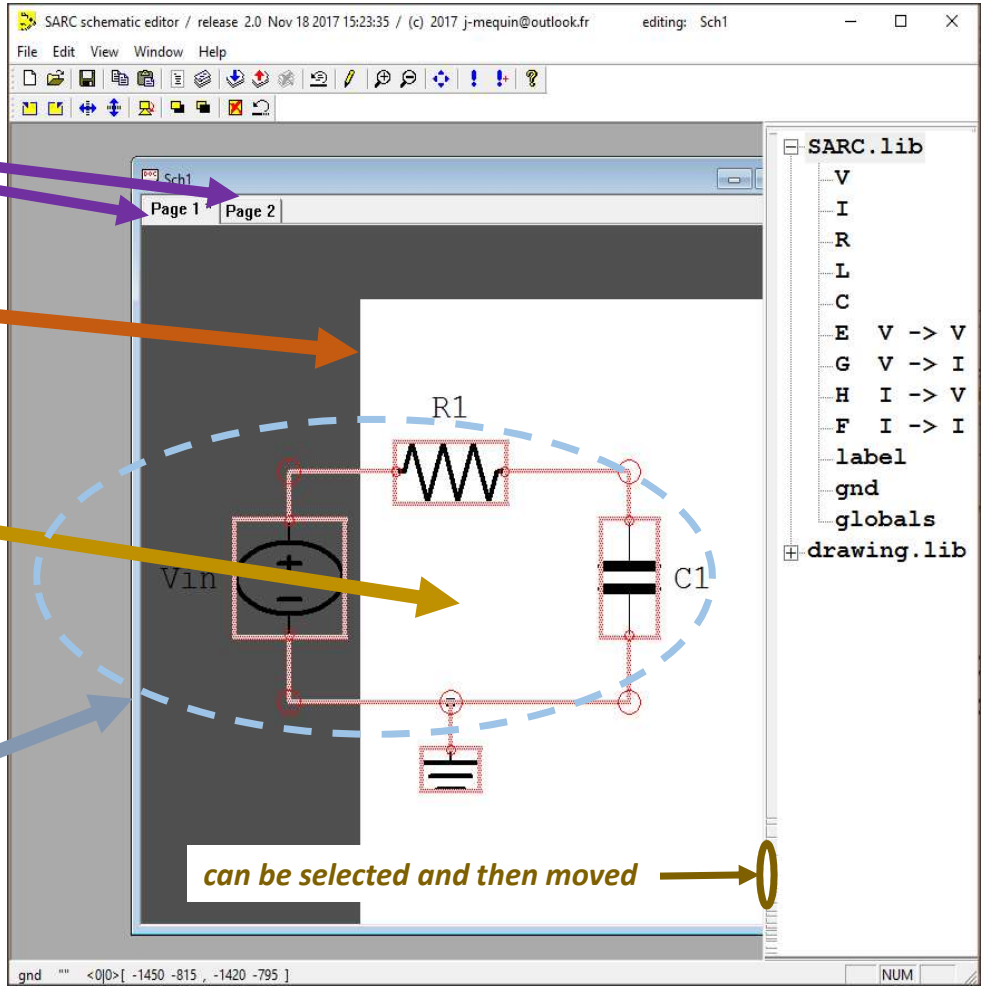
including the

available surface for the drawing

by default **width** = 2970 **height** = 2100

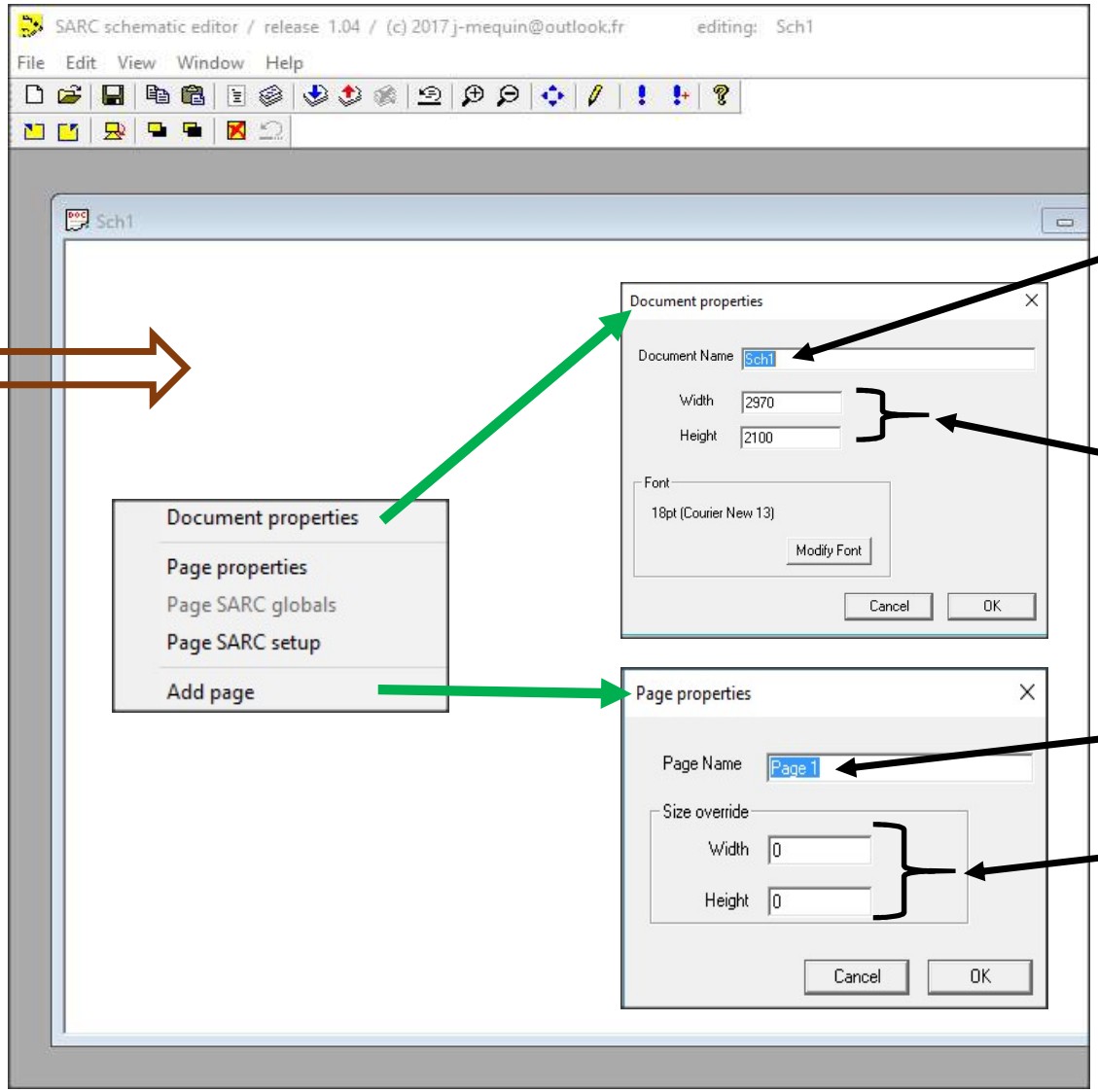
(thus ***landscape***)

this whole schematic needs to be moved to the ***printable area***



click right

on an empty zone



document name
will remain coherent with
the **XML** and **MAC** ***filenames***

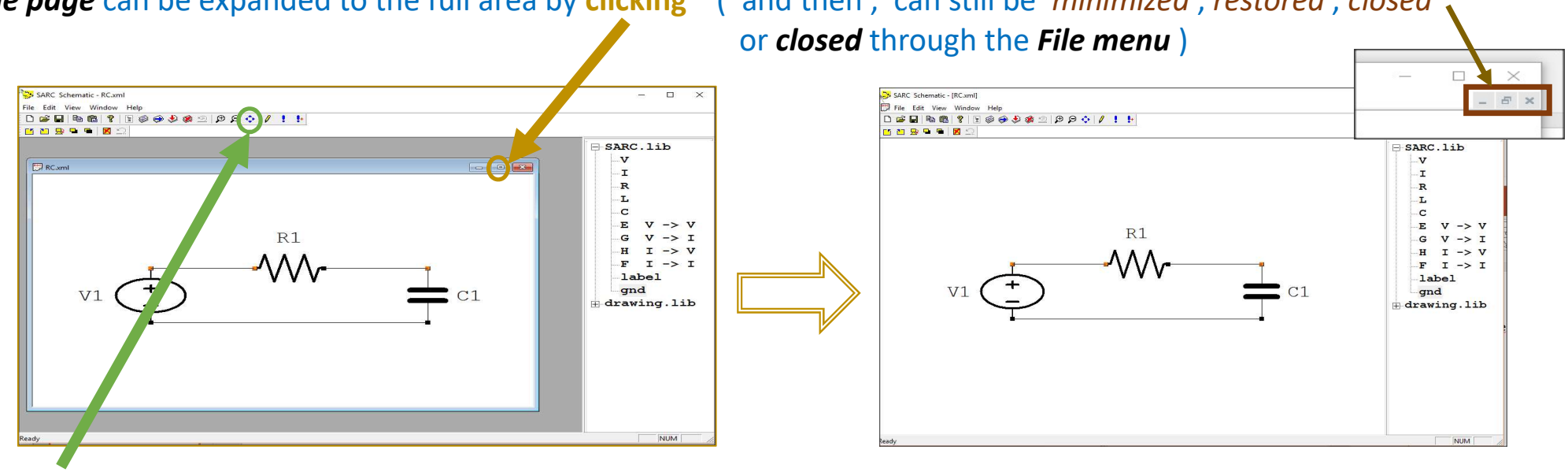
width and ***height***
of the **default** ***printable area***

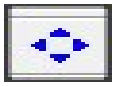
page name

width and ***height***
of **this** ***page area***
(***0*** means same as **document**)

Several **XML** files can be active at the same time, allowing to ***cut*** / ***paste*** selected item(**s**) between them

A ***single page*** can be expanded to the full area by **clicking** (and then , can still be *minimized* , *restored* , *closed* or ***closed*** through the ***File menu***)



The  icon allows **to rescale** the schematic in order to fulfill the visible window area (= ZOOM to fit)

After positioning the mouse, the ***space bar*** **centers** the view ***without modifying the scale***

After positioning the mouse, **Page UP** increases the zoom by **25%**, **Page Down** decreases the zoom by **1/25%**, **around the mouse**
or Ctrl + **or Ctrl -**

The ***mouse wheel*** can be also used to control the zoom

Any object on the " **Page** " can be **selected** by ***clicking left*** on it

Once selected, the objects can be ***copied*** ***deleted*** ***pasted*** ***moved***
ctrl-C ***del key or ctrl-X*** ***ctrl-V*** ***click left***

Objects can be ***deselected*** by clicking on an ***empty area*** or with the ***ESCAPE*** key

Holding **Ctrl** **key** allows **to select** ***all the objects*** that are inside a ***rectangular zone*** ***delimited with the mouse clicking left***

Once selected, the ***area*** can be ***copied*** ***deleted*** ***pasted*** ***moved***
ctrl-C ***del key or ctrl-X*** ***ctrl-V*** holding ***ctrl*** **key** **+** ***click left***

An ***area*** can be ***deselected*** by clicking ***elsewhere*** or with the ***ESCAPE*** key

Holding **both** ***Ctrl*** and ***Alt***, and then **moving the mouse** **clicked left** , allows to move EVERYTHING within the ***page container***

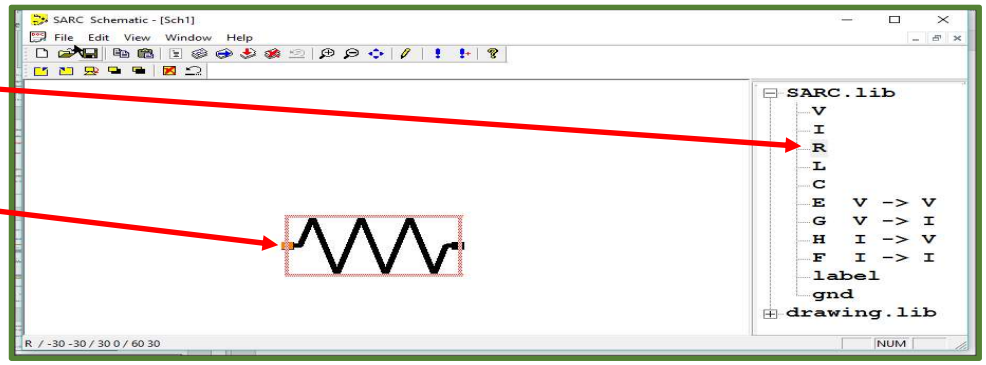
ctrl-Z undo undo last edit operation(**s**) ⟺  **undo** *icon*

ctrl-A	select	***everything*** on the ***page***	**F2**	check page for missing connection diagnostics
ctrl-C	copy	whatever is ***selected*** to the clipboard	**F3**	display net names (after netlist generation)
ctrl-V	paste	the contents of the clipboard	**F4**	playback all LIFO stack undo items

ctrl-F search an ***instance name*** ***(or a*** **NET** ***name)*** in the schematic

To add a ***component***, select it from the ***SARC library***

and ***then double click left*** on the ***page***



The ***component*** will ***remain selected*** until another one is chosen

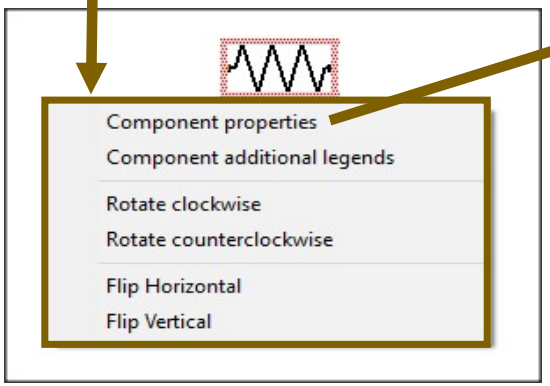
Therefore, ***double clicks*** can be used to place ***multiple instances***

The original software allows to **GROW** *or* **SHRINK** *components with* ***SHIFT + the 4 arrows***

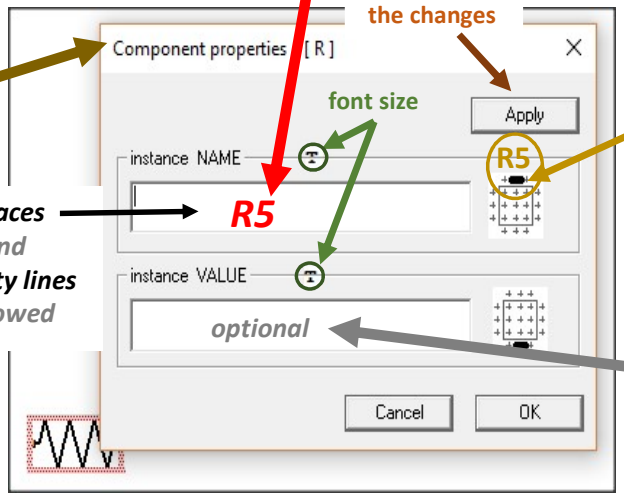
double click left

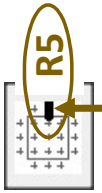
or ***click right*** *on a selected component,*

pop-up



instance name required





click right

allows to see the changes

Selecting another

location and ***orientation***

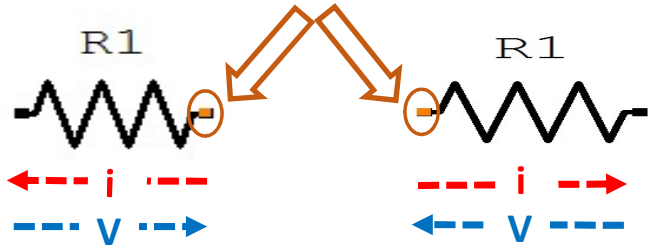
of this ***rectangular mark*** changes

the ***location*** and ***orientation***

of the ***displayed text***

*see the slide about "**globals**"*

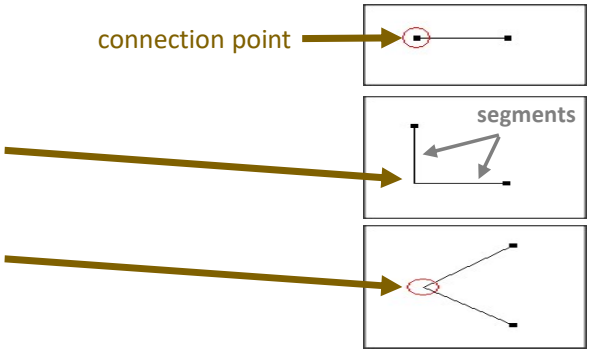
On each ***SARC*** **component**, an ***orange mark*** allows to identify, ***despite possible rotations***, its **SARC** ***netlist pins order***



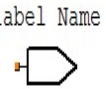
Holding **Alt key** while ***clicking mouse left*** allows to ***draw a*** **WIRE** ***segment***

While holding the **Alt key**, ***toggling*** the ***mouse left*** allows to ***change direction***

Without holding the **Alt key**, ***clicking*** the ***mouse left*** allows to ***drag*** the ***selected location*** of an existing **WIRE**



Pressing **F1** allows to make disappear **BOTH** the ***orange marks*** and the ***connection points*** *(example, for nicer plot)*

The ***SARC*** component **“** ***label*** **”** 

can be used to associate a ***name*** to a **NET** *(overriding its default* **“ nxx ”** *)*

“ *Distant* **label**s **”** *sharing* ***same name*** *are* ***wirelessly*** *connected !!!*

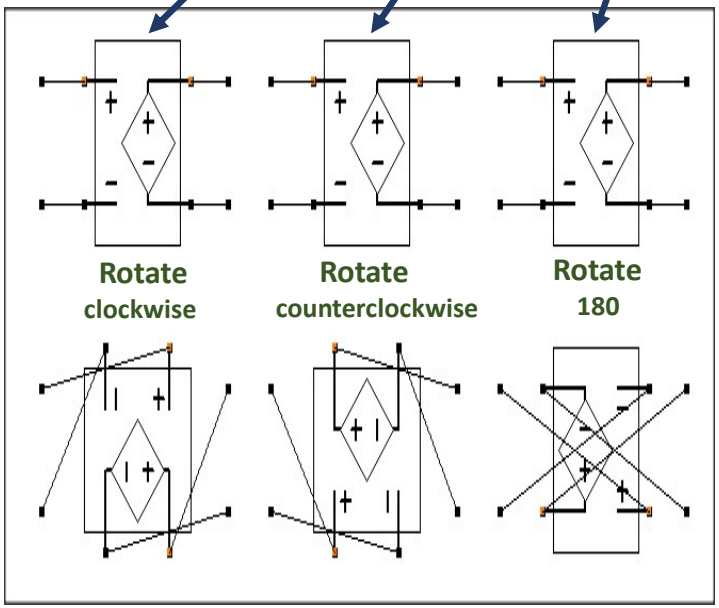
The objects **“ Title “** or **“ Sticker “** of the **”** ***drawing.lib*** **“** can be used to add some ***legends*** to the schematic

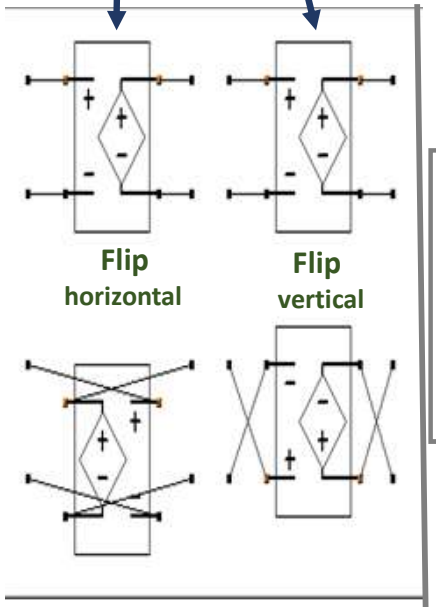
"**undo**" **previous** edit / ctrl-Z

from the *history* queue

delete **selected** object(**s**) / ctrl-X

change component **type**



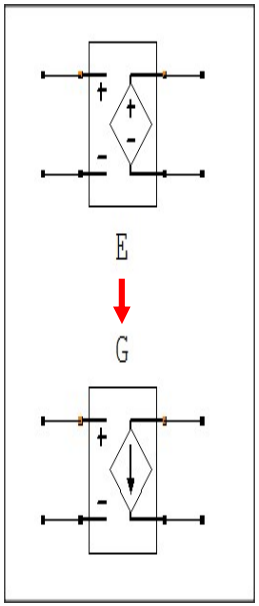


I/O swap can be used

to reverse V I R L C

and only outputs of

E H G F

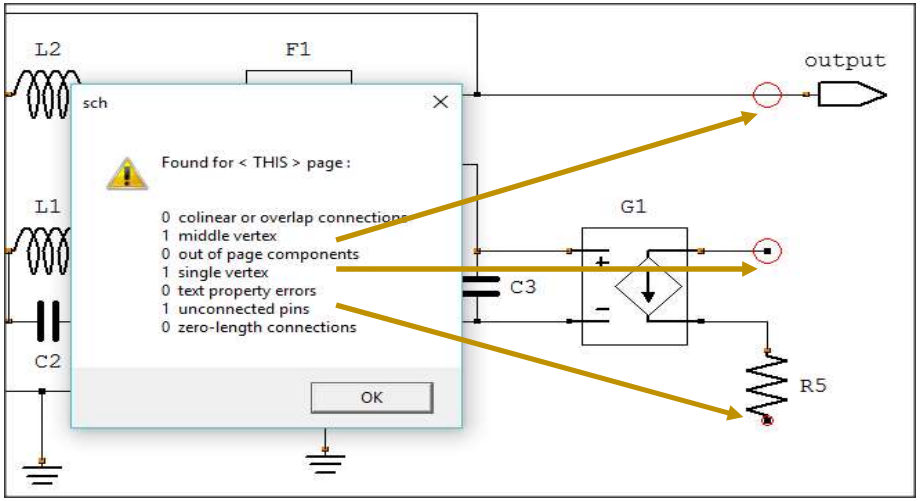


connected nets remain attached

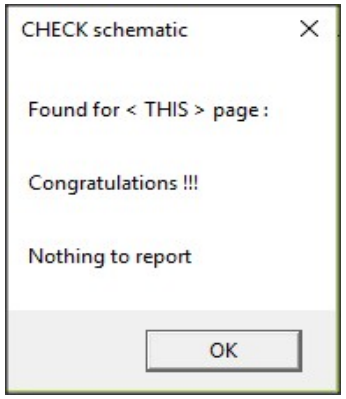
Before the ***netlist generation*** it is **mandatory** to perform some ***sanity checks*** on the schematic(**s**)

Those checks are ***almost the ones of the original software*** and are ***not as exhaustive as*** the ***SARC Maxima*** version

Therefore, even if a netlist is later generated, it can still contains some remaining issues



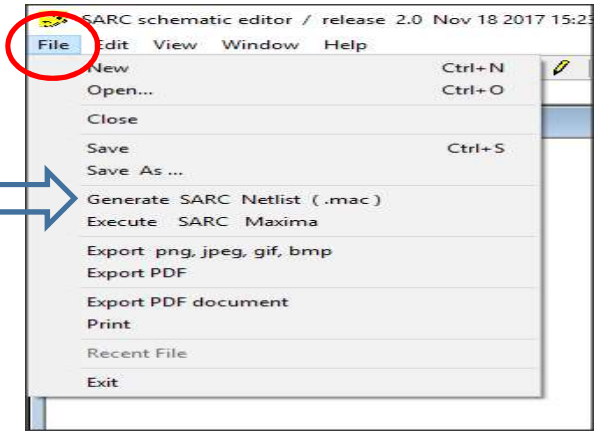
On the current page, it is also possible to display the diagnostics of the checks, ***but without the pop-up window***, by pressing **F2**



Netlist generation

same ***file location*** that the associated ***XML***

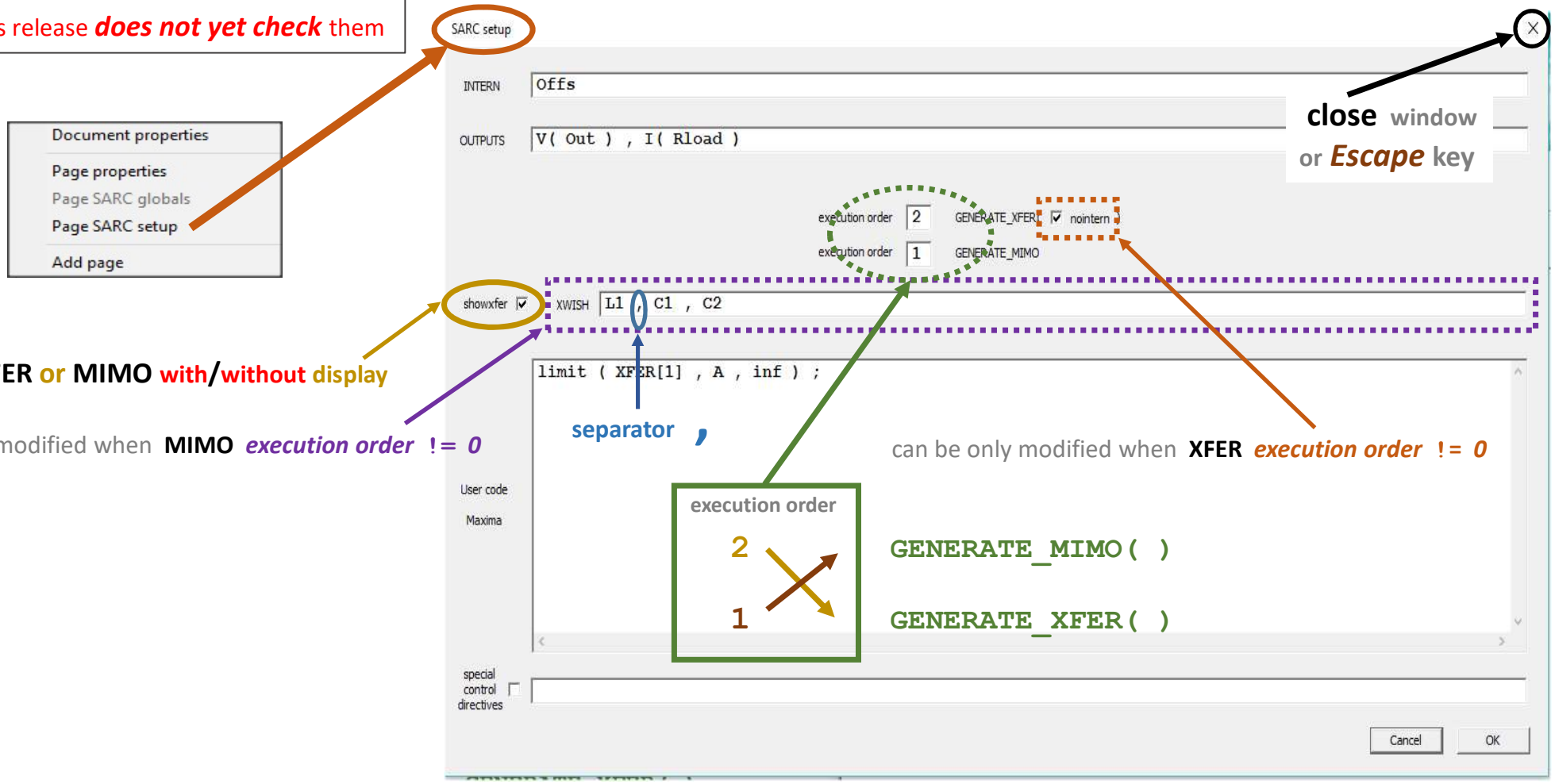
File menu



Maxima **SARC parameters** can be

collected and ***saved*** within the **XML**

However, this release ***does not yet check*** them



generate **XFER** or **MIMO** with/without display

can be only modified when **MIMO** ***execution order*** ***!= 0***

separator ,

can be only modified when **XFER** ***execution order*** ***!= 0***

document property " ***name*** "

(that is related to ***filename***)

page property " ***name*** "

generation date

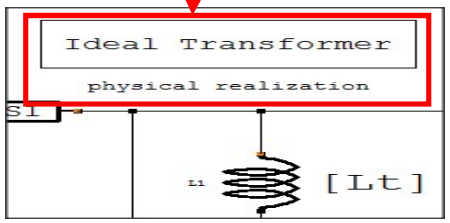
when defined ,

those lines come from

drawing.lib

" **Title** " objects

" ***Component additional legends*** "



SARC netlist mac file D:\JM\HOME\LAB\test.mac

```
xmldocument : "test"                                              ;
xmlpage     : "Page 1"                                            ;
xmldate     : "Sat Nov 18 19:06:28 201                  ease 2.0" ;

SCHEMATIC( "
Ideal Transformer
physical realization
" ) ;

NETLIST(
          [  I  ,  Iin    ,  S1   ,  GND                    ] ,
          [  R  ,  RLOAD  ,  S2   ,  GND                    ] ,
          [  L  ,  L1     ,  S1   ,  n01                    ] ,
          [  L  ,  L2     ,  S2   ,  n02                    ] ,
          [  C  ,  C3     ,  S2   ,  GND                    ] ,
          [  C  ,  C4     ,  S2   ,  GND                    ] ,
          [  E  ,  E1     ,  n01  ,  GND  ,  S2  ,  n02     ] ,
          [  E  ,  E2     ,  n02  ,  GND  ,  S1  ,  n01     ]
        ) ;

/*  nb components =   8          */
/*  nb    nets    =   4 (+GND)   */

/*  instance  Iin  comment:  input  */

BIND(
      B                                  ,
      N                                  ,
      C          = [B]                   ,
```

SARC schematic editor / release 2.0

File Edit View Window Help

New
Open...
Close
Save
Save As ...
Generate SARC Netlist (.mac)
Execute SARC Maxima
Export png, jpeg, gif, bmp
Export PDF
Export PDF document
Print

close window or ***Escape*** key

In case of several **Title** use « ***Bring to front*** » icon to select one of them

Escape-S can be used to view the ***current*** schematic **".sch"** file

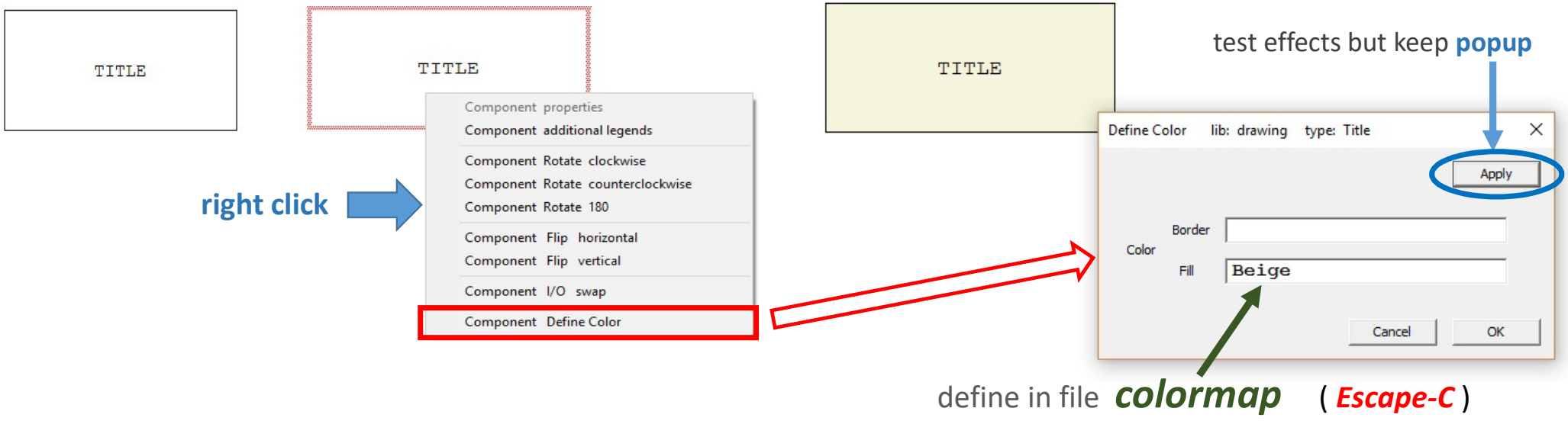
Escape-P can be used to view (**AFTER** ***schematic Save / Save as***) the ***latest*** generated **".pdf"** file

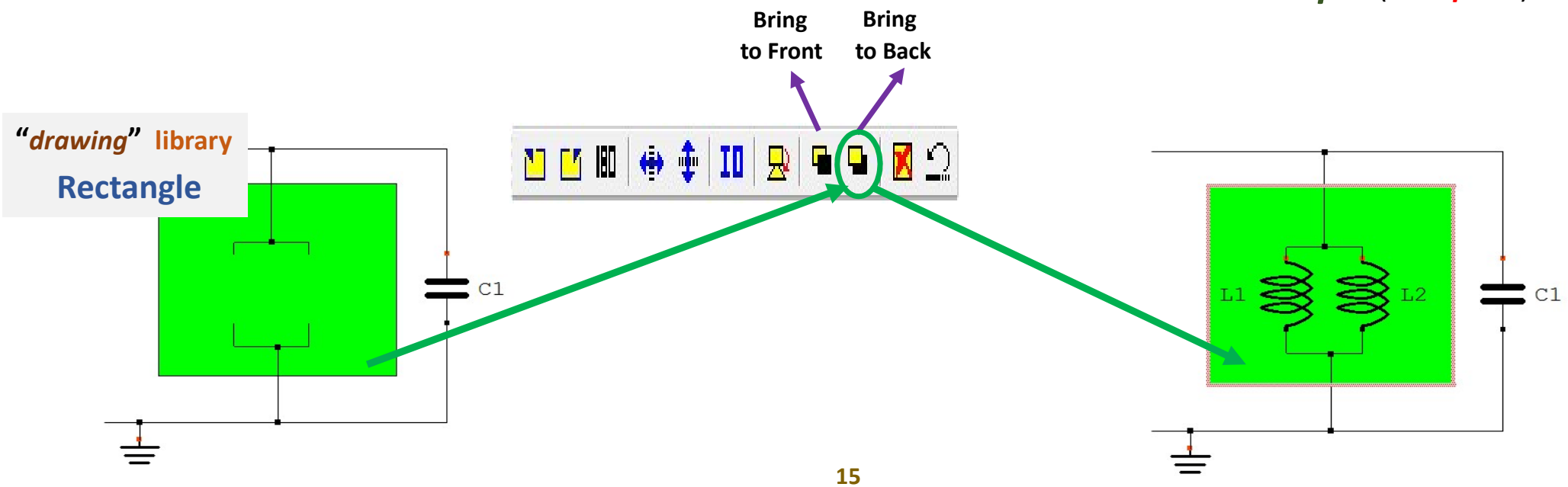
Escape-M can be used to view (**AFTER** ***generate SARC Netlist***) the ***latest*** generated **".mac"** file

Escape-H can be used to view (**AFTER** ***GENERATE_MIMO( )***) the ***latest*** generated **".hdr"** file

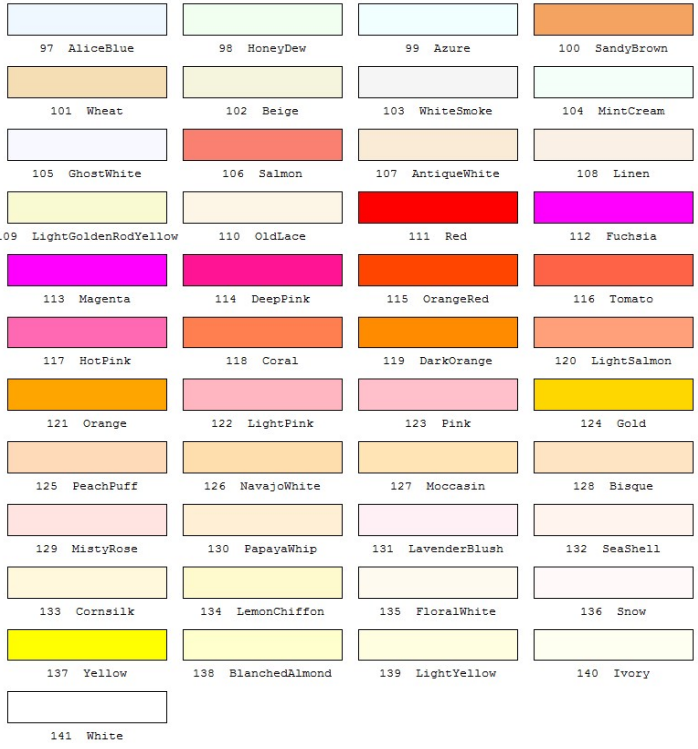
Escape-Z can be used to view (**AFTER** ***GENERATE_Z( )***) the ***latest*** generated **".hdr"** file

Escape-C can be used to view the **colormap**

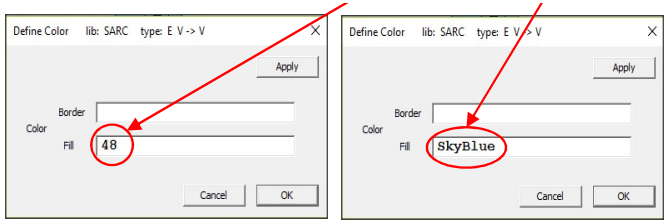

TITLE
TITLE
TITLE
Component properties
Component additional legends
Component Rotate clockwise
Component Rotate counterclockwise
Component Rotate 180
Component Flip horizontal
Component Flip vertical
Component I/O swap
Component Define Color
right click
test effects but keep popup
Define Color lib: drawing type: Title
Apply
Border
Color
Fill
Beige
Cancel
OK
define in file colormap (Escape-C)


"drawing" library
Rectangle
Bring to Front
Bring to Back
C1
L1
L2
C1

ESC - C

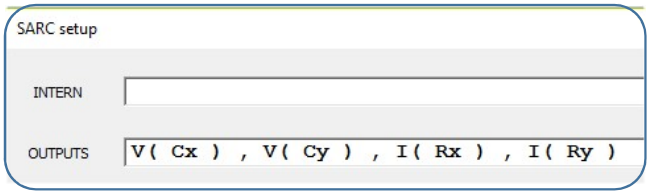


COLORS can be defined



by **index** or by **name** (***case insensitive***)

OUTPUT syntax examples :



`V( label )`	label : netlist node
`V( label1:label2 )`	voltage between 2 labels (note: **GND** is a label)
`V( component )`	components : **U I R L C** and **E G H F** outputs
`I( component )`	components : **U I R L C** and **E G H F** outputs
`W( component )`	components : **U I R L C** and **E G H F** outputs
`cV( voltage control )`	control side of **E G**
`cI( current control )`	control side of **H F**

. . .

note : *the* **Y[ ]** *vector* ***displayed*** *by* ***wxMAXIMA*** *only contains* **V( ) cV( ) I( ) cI( )**

component parameters

- **string** — « hello world » — *comments are ignored by **Maxima***
- **symbolic** — 3*gain; k*sqrt(gain); 0.8 / gain

  *substituted **at the start** of **Maxima** analysis*

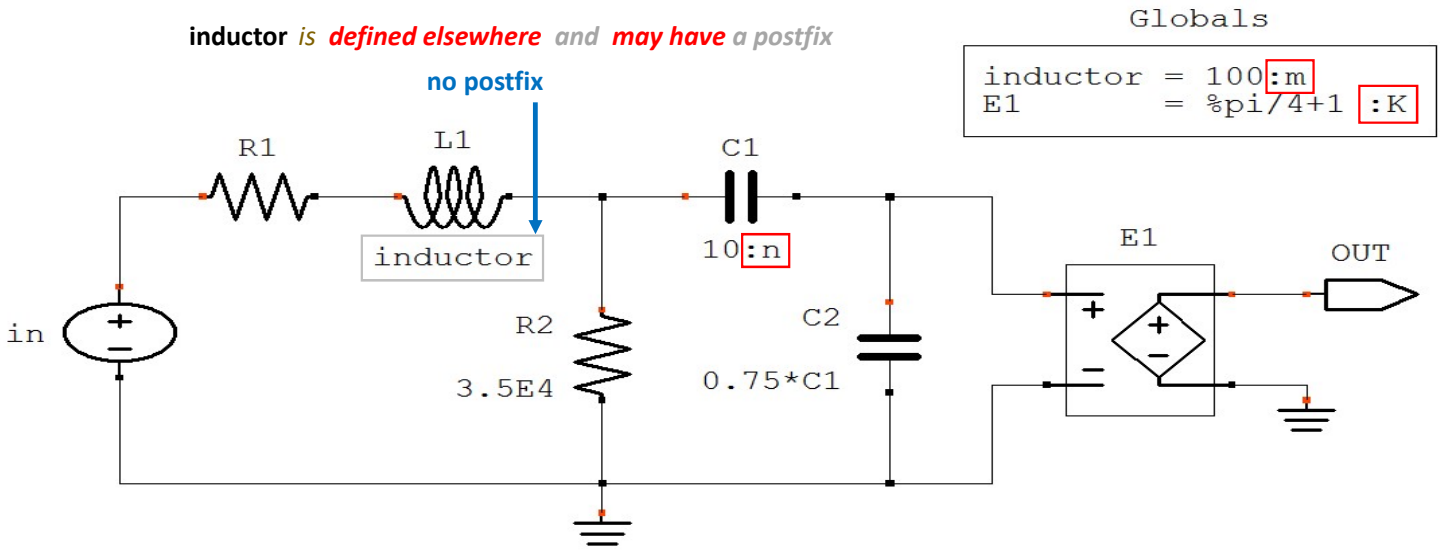
  symbolic definitions must reference at least one variable

NOTE : *special syntax* [1] [+1] [-1] *(1 is the only accepted « value »)*

- **numeric** — 0.4; 12E-3; sqrt(%pi)

  *substituted **at the end** of **Maxima** analysis*

  numeric definitions must not reference any variable



schematic instance ***numeric values*** can be ***postfixed*** with a multiplicative unit

:P	*peta*	10^+15
:T	*tera*	10^+12
:G	*giga*	10^+9
:M	*mega*	10^+6
:K	*kilo*	10^+3

uppercase

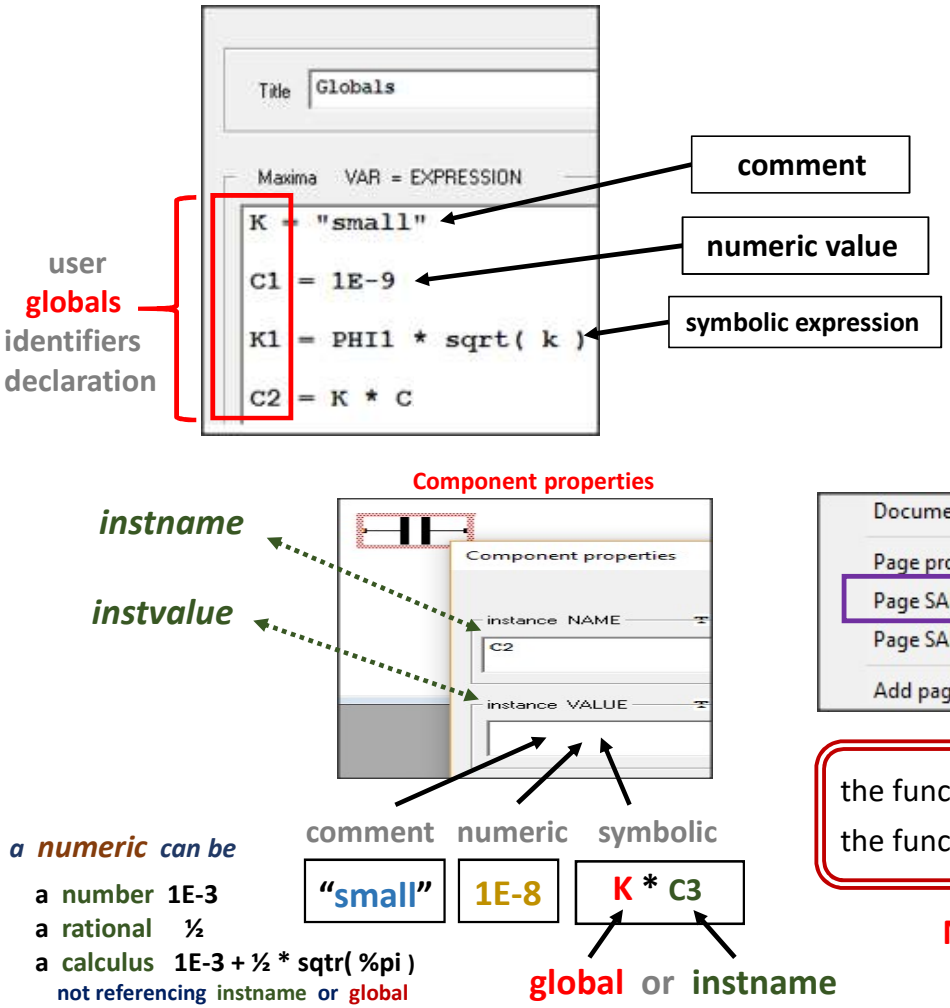
:m	*mili*	10^-3
:u	*micro*	10^-6
:n	*nano*	10^-9
:p	*pico*	10^-12
:f	*femto*	10^-15

lowercase

Globals

A *special SARC component* named « *globals* » can be instantiated on the page

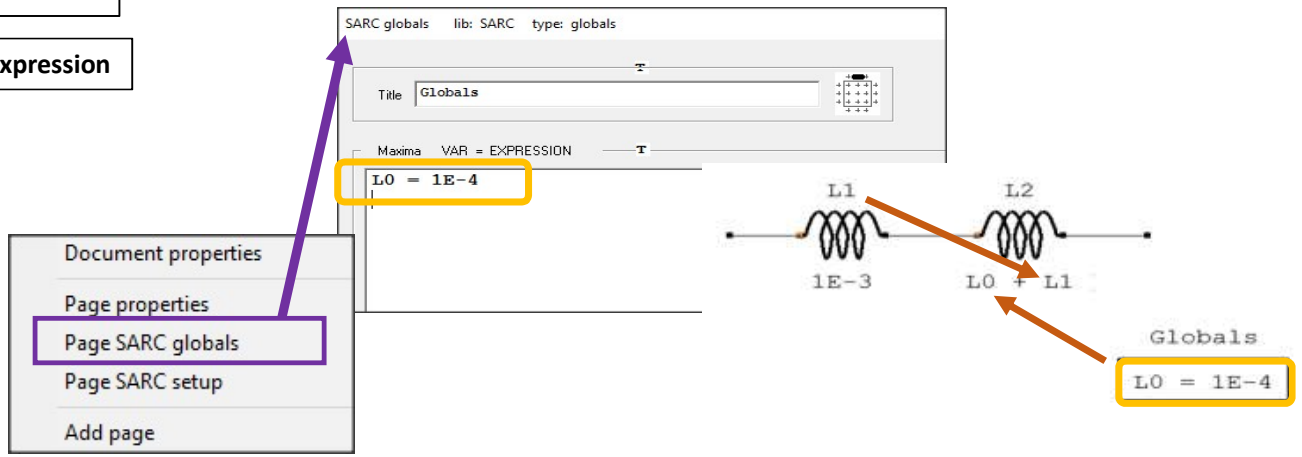
Its purpose is to define *circuit global parameters*
referenced by *instance values* or other *globals*



a numeric can be

- a number 1E-3
- a rational ½
- a calculus 1E-3 + ½ * sqtr(%pi)
  not referencing instname or global

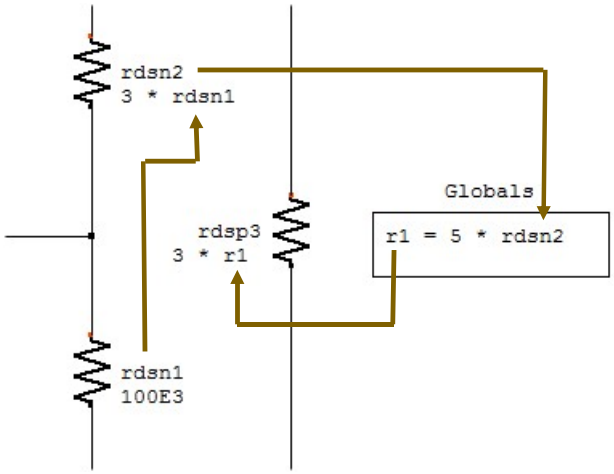
After placing the *globals* component, the *global menu* can be
accessed by right click on an *empty area* of the screen
or double click left on the *globals* component



the function **XFLOAT(expr)** can be used to replace **all F%nn** with their **numerical values**
the function **XNUM(expr)** can be used to replace **all Globals** with their **numerical values**

NOTE : any *symbolic constant* value of the form **[1234]** are **not allowed**
except **[1] [+1] [-1]** that are reserved for **E , H , G , F** components

- **instnames** and **GLOBALS** variables can both be used in equations

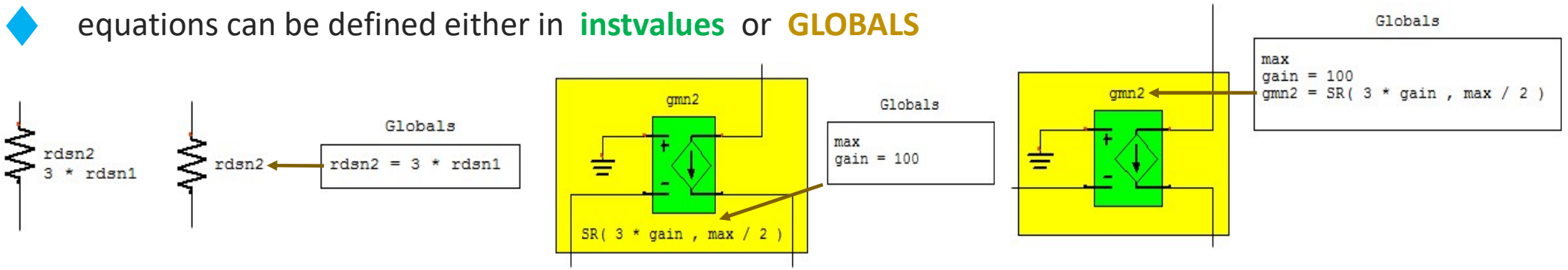


- **instnames** are by definition « **declared** » **and** « **used** »

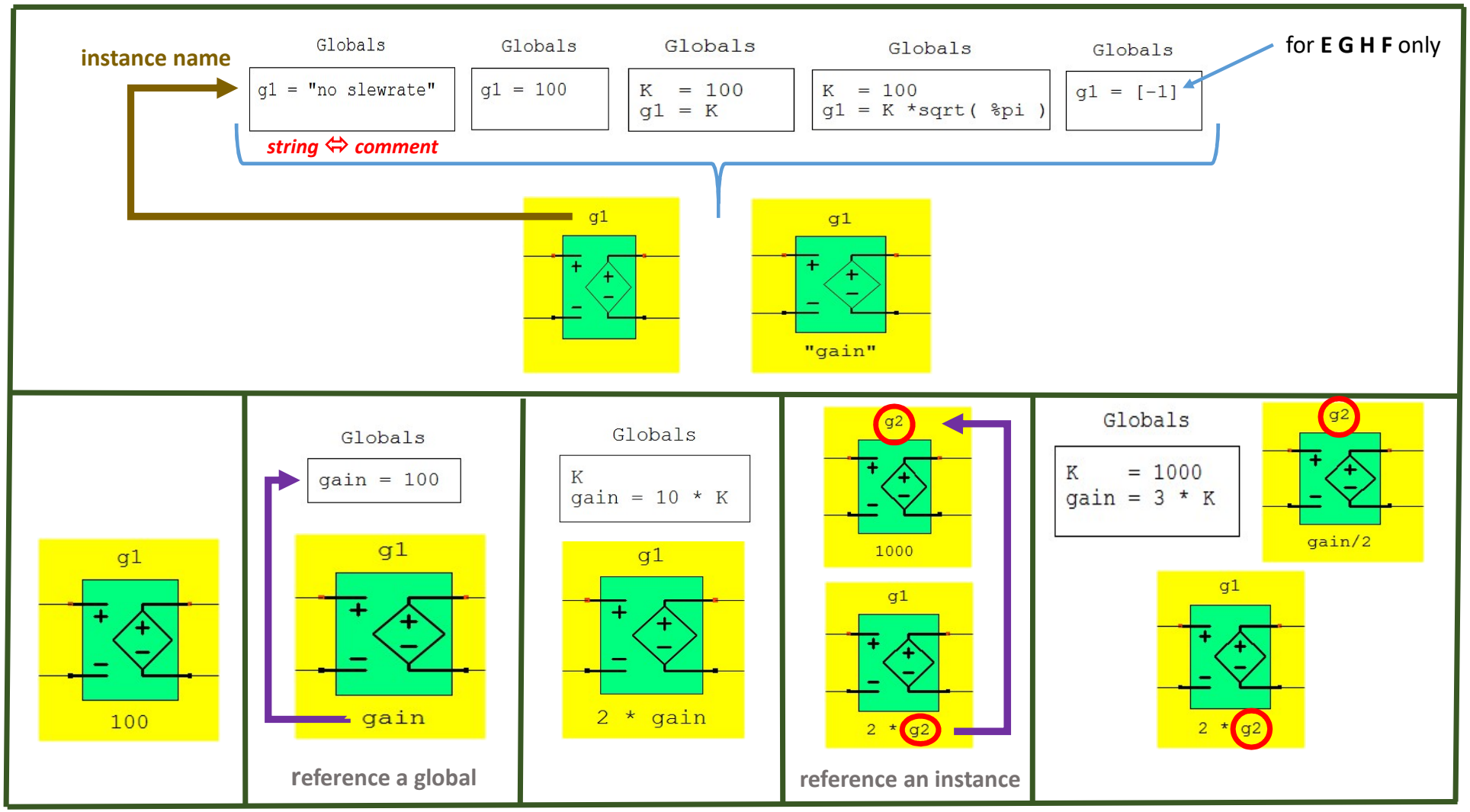
- **GLOBALS** variables must be also « **declared** » **and** « **used** » (in **instvalues** or **GLOBALS**)

R1 **R1 = « load »** **R1 = 100** **R2 = 2 * R1**

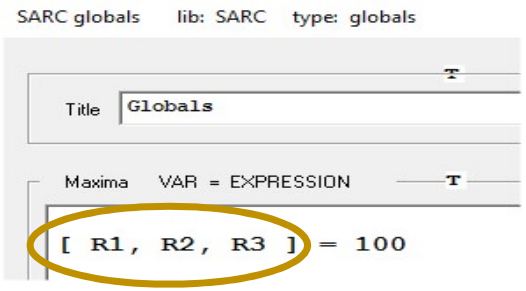
- equations can be defined either in **instvalues** or **GLOBALS**



« xxx » **ignored string**	xxxx **symbolic** expressions substituted at **build time**	33.5 or 3E-8 **numeric** substituted at **run time**



declarations can be grouped



runtime directives can also be defined with **GLOBALS**

%rubmode = true	do not plot ***instantaneous*** **percussion spikes** (*simulation remains unchanged*)	(*default* **false**)
%printpoles = 3	report the computations of the poles **due to the first 3 BOM** changes	(*default* **0**)
%srtol = 1E-3	***saturation rendering*** computation ***tolerance***	(*default* **1E-4**)
	roughly, dividing %strol *by 10 increases the number of iterations by +4*	
%srlim = 25	***saturation rendering*** computation ***iteration limit***	(*default* **50**)
%phases = [Phi1 , Phi2]	**mandatory** for ***Z transform*** but can be declared for **XFER** / **MIMO**	(*no default*)
%zopen = Gds	*component '**Gds**' will be **ignored** by **GENERATE_Z( )***	
%zopen = [Gds1 , Gds2]		
%zshort = Rds	*component '**Rds**' will be **shorted** by **GENERATE_Z( )***	
%zshort = [Rds1 , Rds2]		

In electronic, ***slew rate*** is defined as the *maximum change of* ***current*** *or* ***voltage*** *per unit of time* (***max(di / dt)*** or ***max(dv / dt)***)

but, *rather than this* ***« slope control »*** , **SARC** ***slew rate*** simulates the ***OP amp*** ***« clipping »*** effect on ***current*** sources

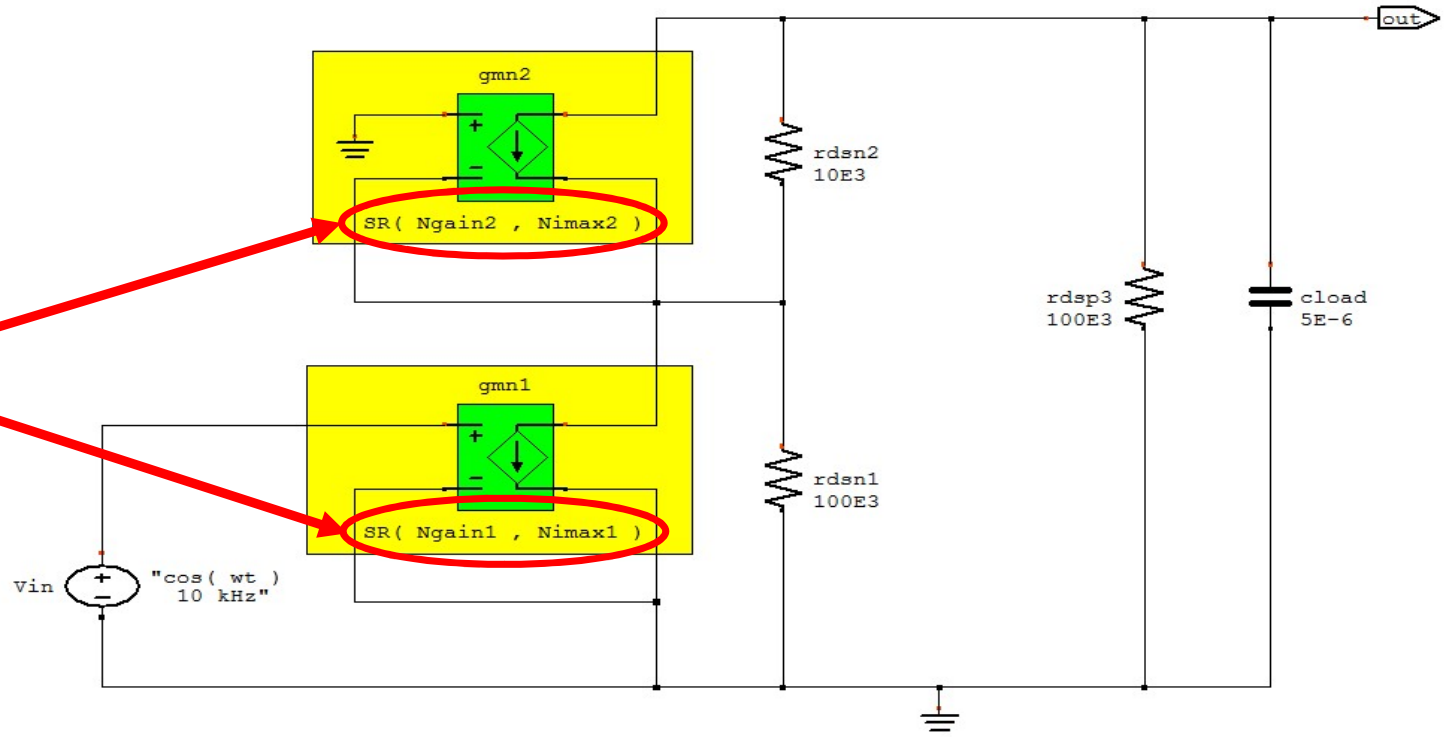
In other words, **for G and F** `SR( gain , imax )` ⟺ **clipping current = imax**

gmn1 and gmn2

will both simulate

Saturation Rendering

« OP amp SLEWRATE »



Globals

```
%srtol = 1E-3
%srlim = 25
```

targetted tolerance = **fabs(** (maxOUTPUT – currentOUTPUT) / maxOUTPUT **)**

max iterations

Norton - Thévenin previous slide

by duality,

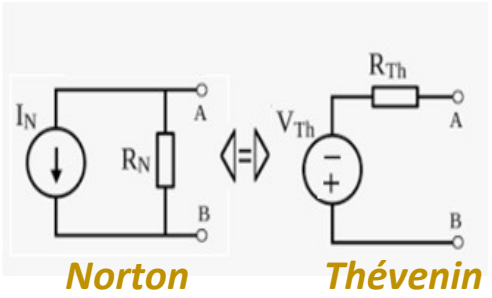
a *similar* *« saturation effect »*

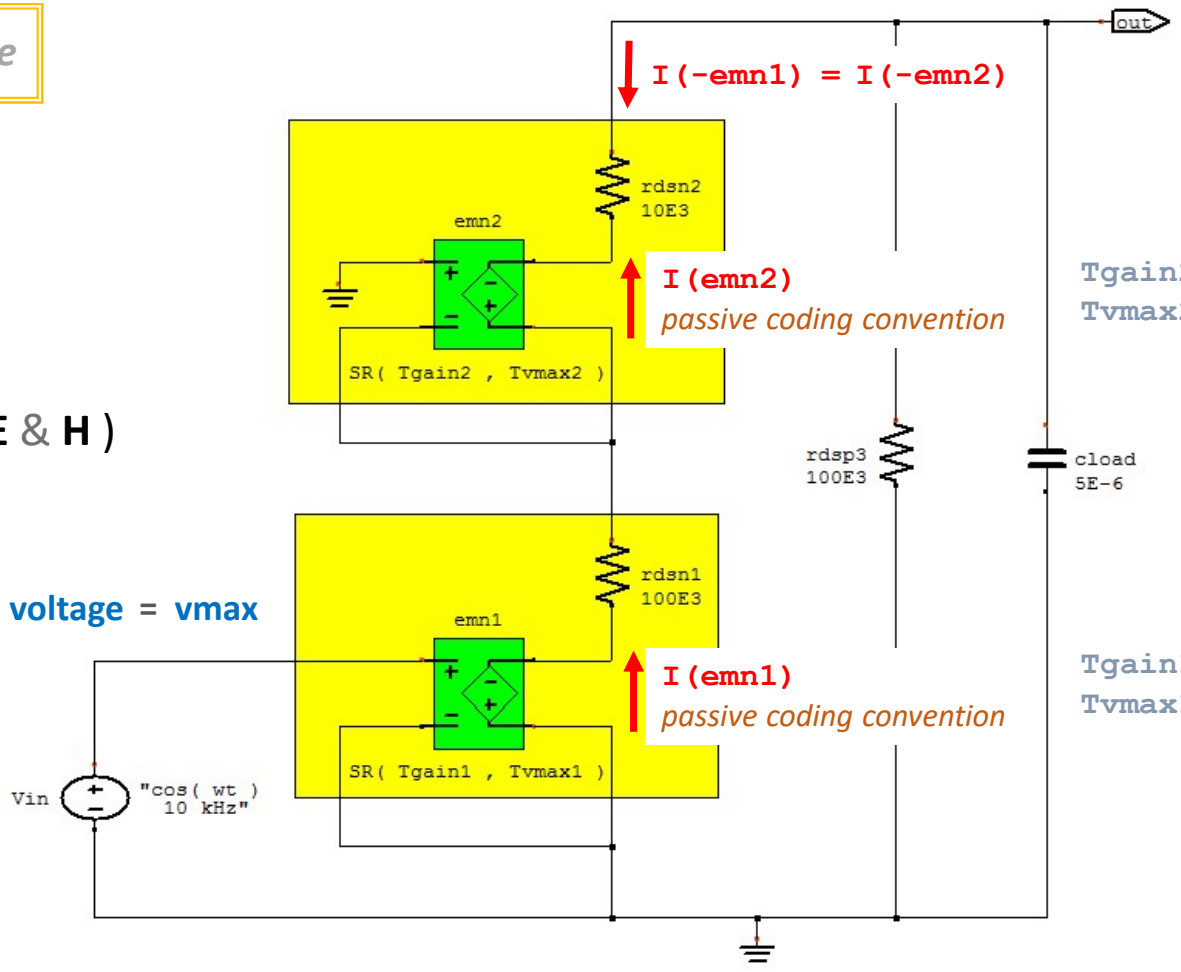
can also be defined

for *controlled voltage source* (**E** & **H**)

In other words, for **E** and **H**

`SR( gain , vmax )` ⟺ clipping **voltage** = **vmax**



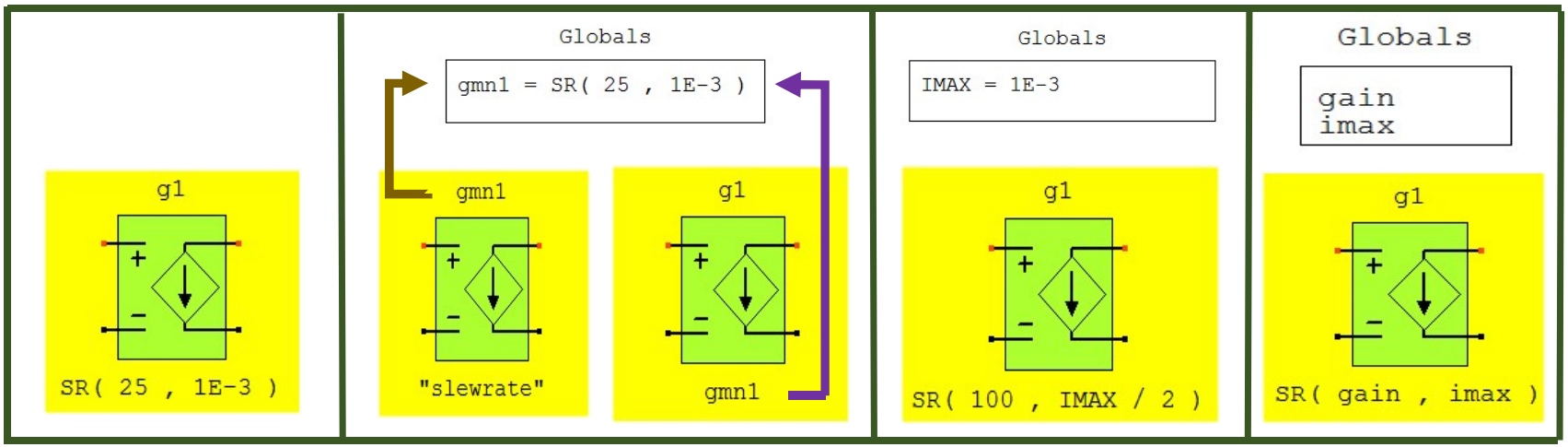


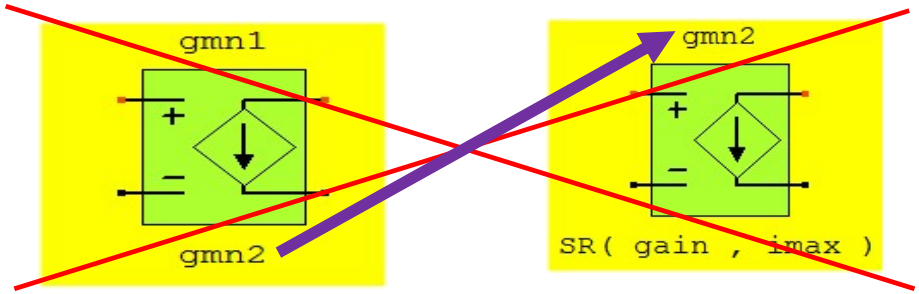

```
Tgain2 = rdsn2 * Ngain2
Tvmax2 = rdsn2 * Nimax2
```

```
Tgain1 = rdsn1 * Ngain1
Tvmax1 = rdsn1 * Nimax1
```

SR(gain , maxout) syntax

maxout		
	Imax for G and F	maxout = 0 ➔ linear mode
	Vmax for E and H	maxout sign ignored



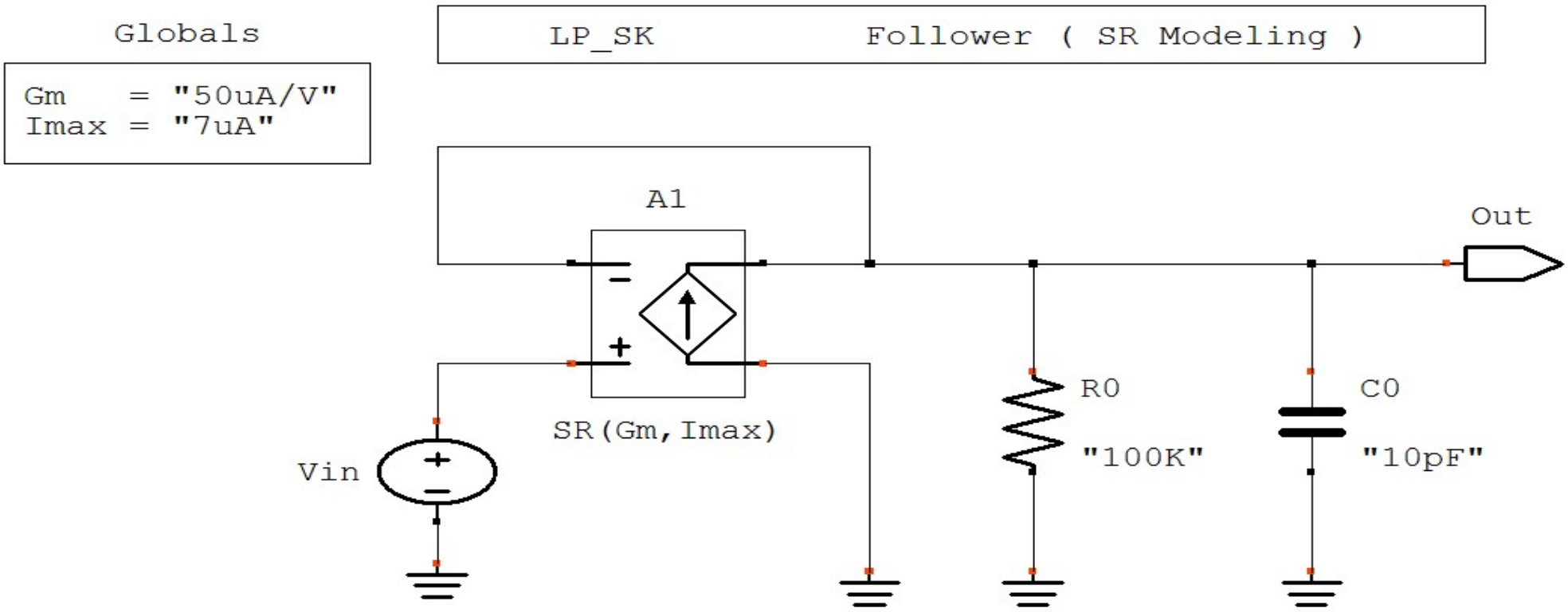


gmn1 gain cannot depend on ***SR( )*** of **gmn2**

There is no need to have several schematics : GENERATE_XFER and GENERATE_Z ignore ***SR( )*** declarations

GENERATE_XFER and GENERATE_MIMO ignore ***%phases*** declarations

MIMO ***SR( )*** simulations can be performed LINEAR by setting `maxout` = 0



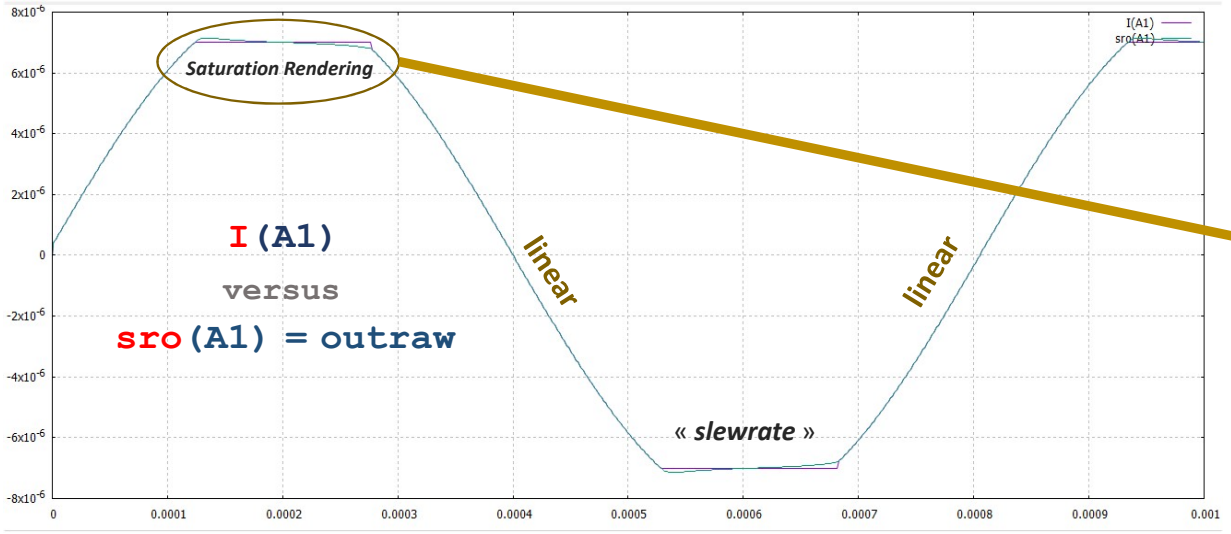
3 special outputs can be plotted to observe the Saturation Rendering convergence

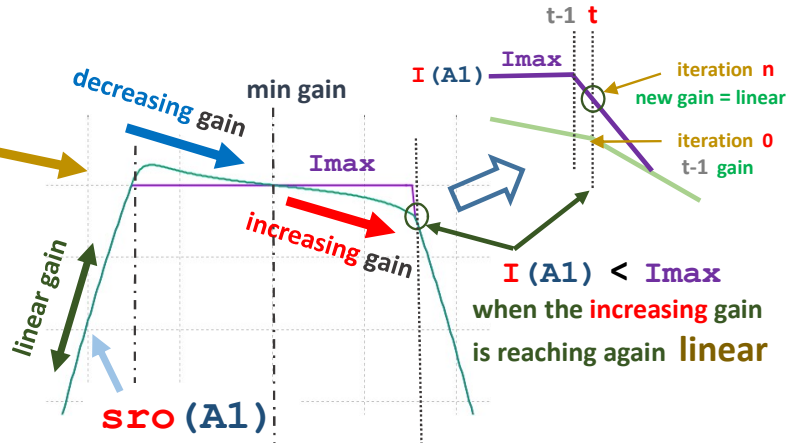
srn(A1) number of recalculations

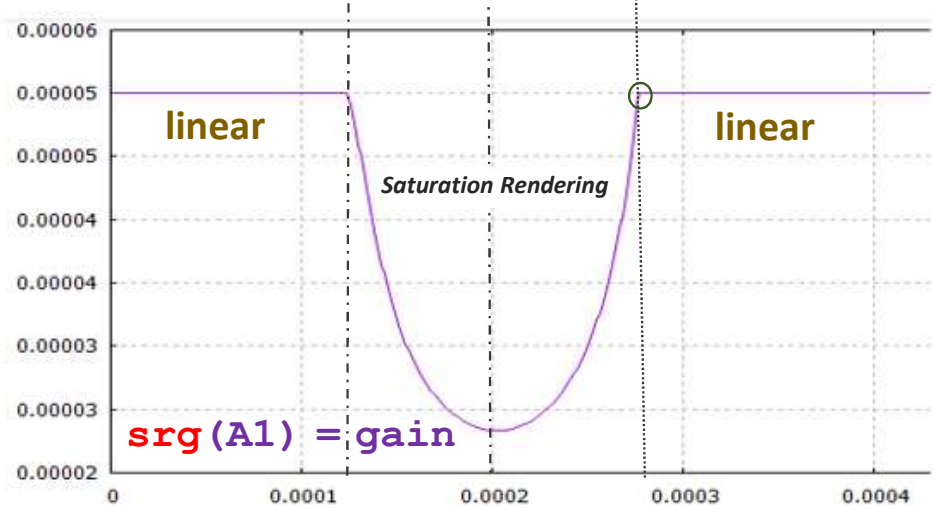
sro(A1) raw output before relaxation

srg(A1) effective reduced gain necessary to sustain max output

CONVERGENCE







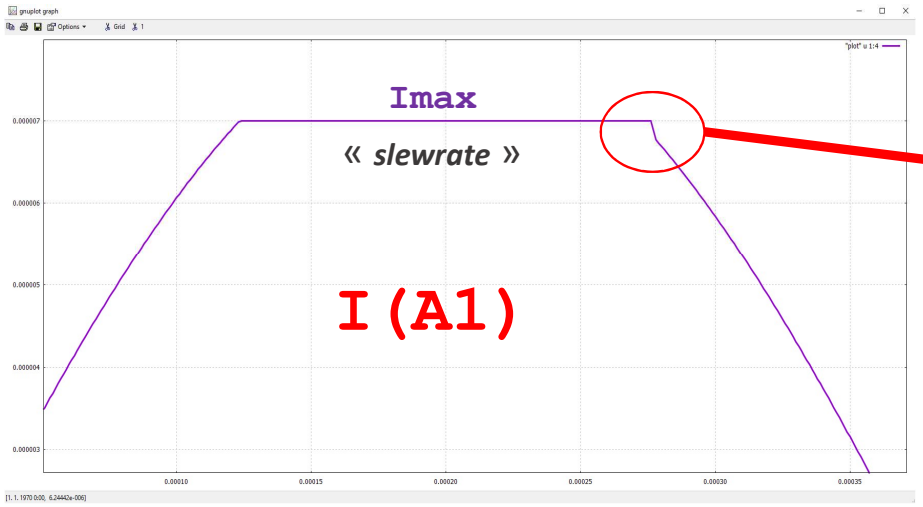
effective reduced gain necessary to sustain max output

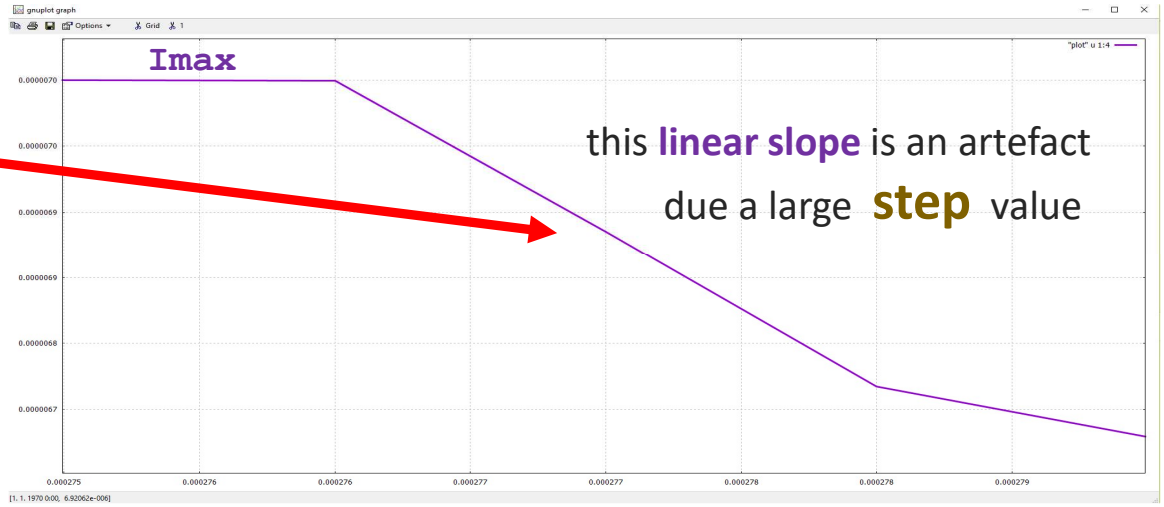
SARC is dedicated to ***Linear Time Invariant*** analog circuits

However,

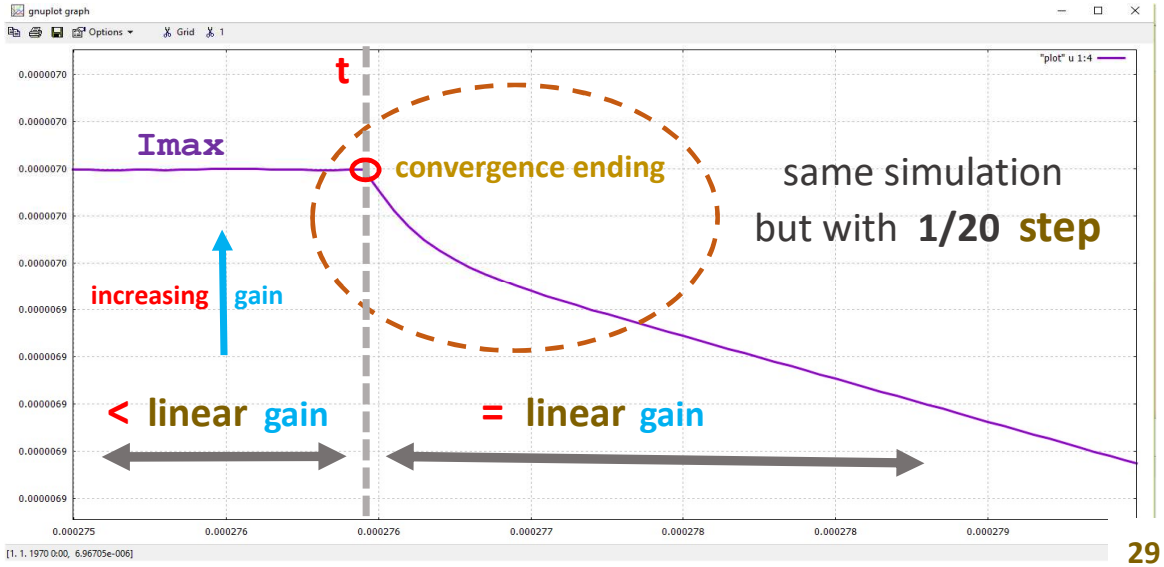
SARC supports « ***Saturation Rendering*** » that is a **nonlinear behavior**

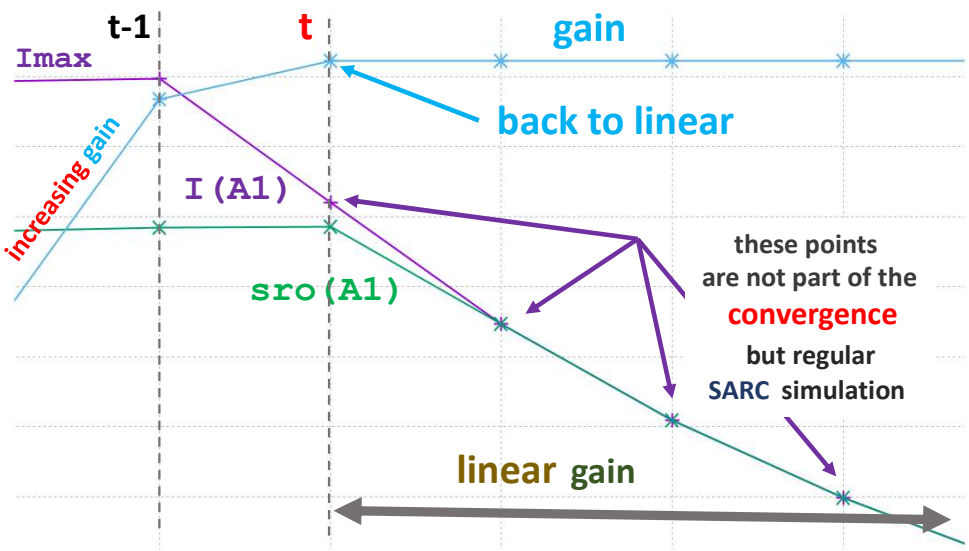
This can be only simulated through a ***convergence process***

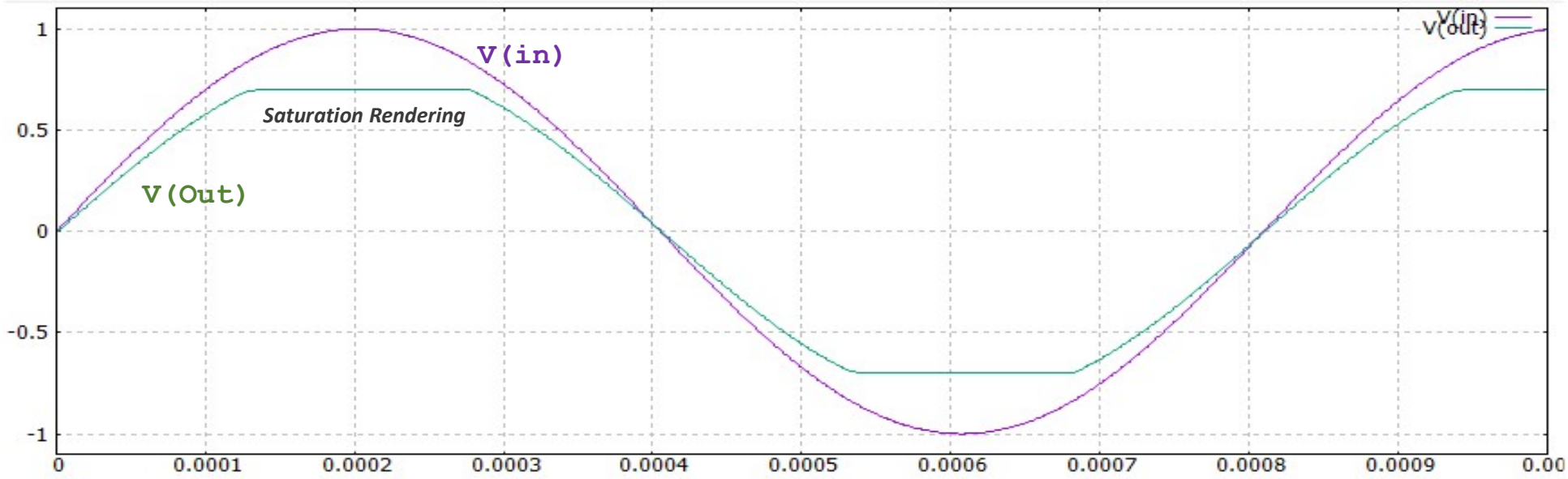


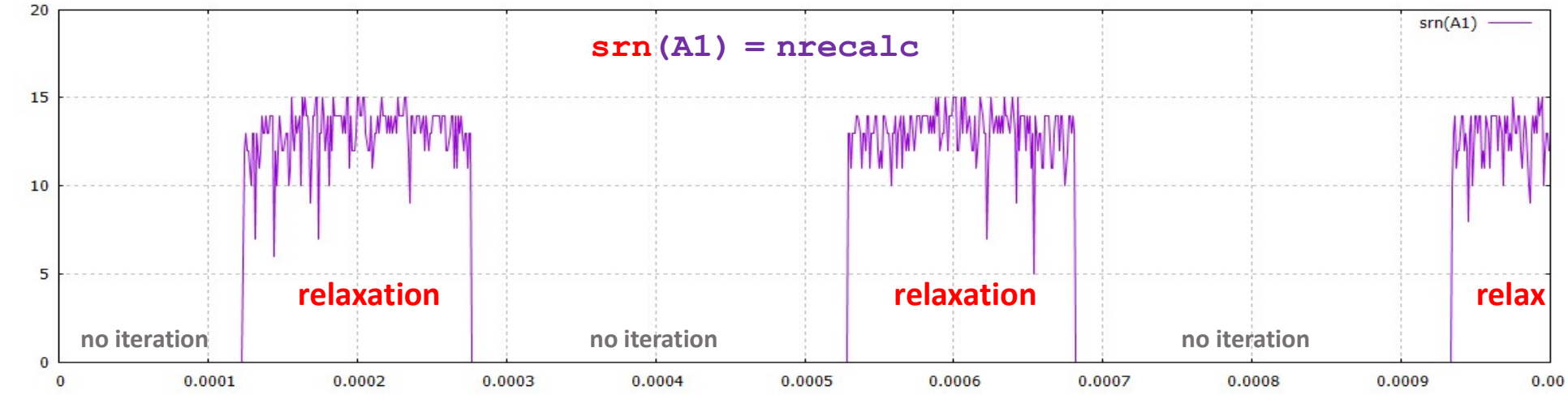


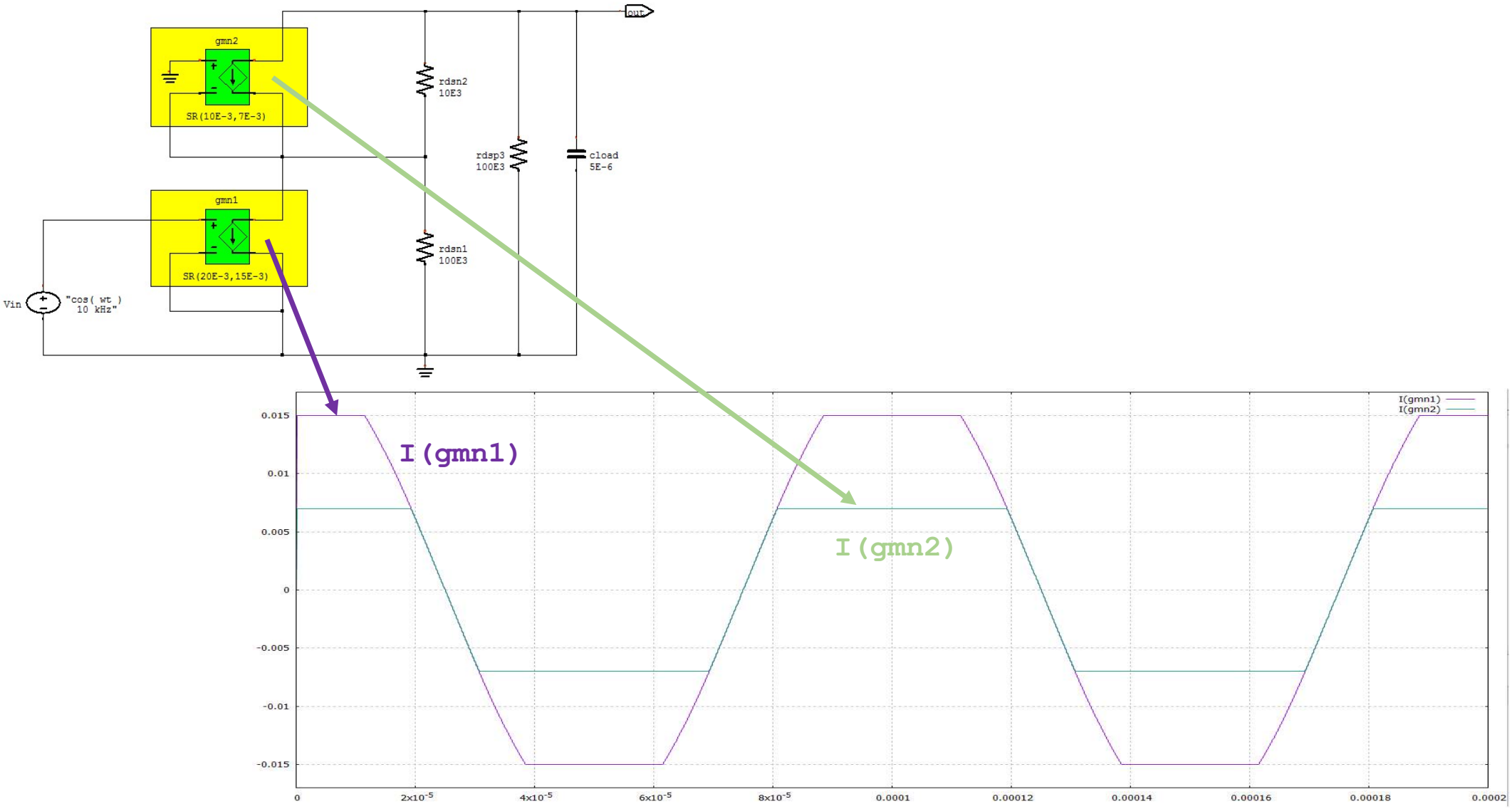
CONVERGENCE ENDING

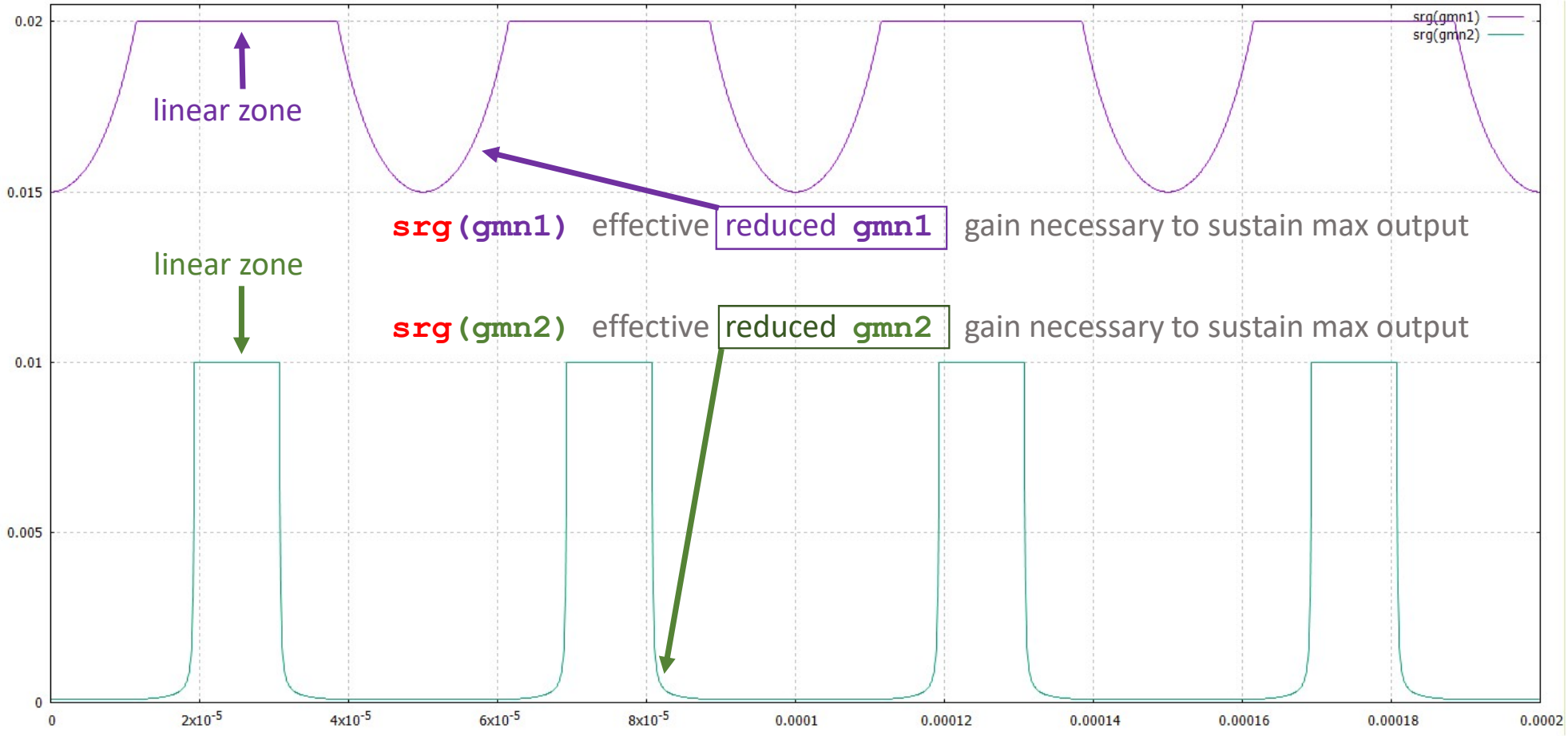




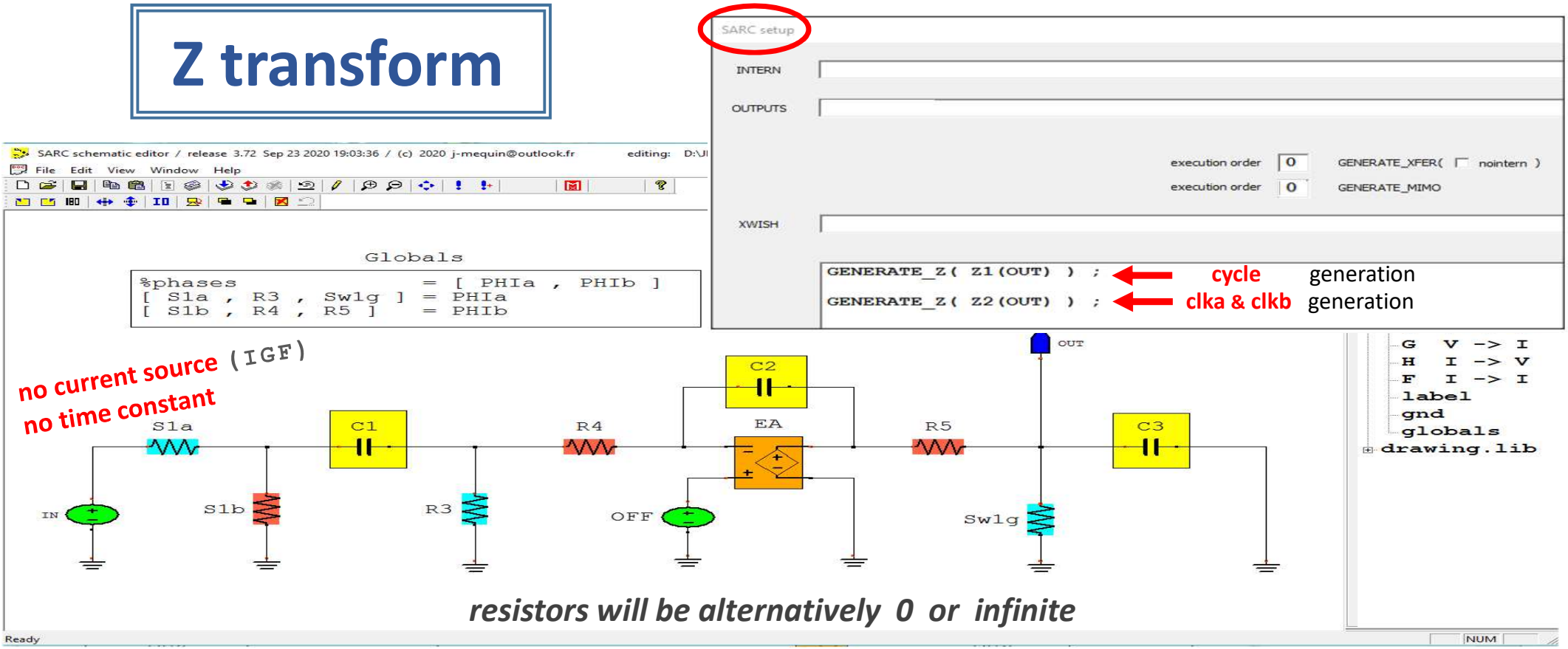

V(in)
V(Out)
Saturation Rendering
V(in)
V(out)
1
0.5
0
-0.5
-1
0
0.0001
0.0002
0.0003
0.0004
0.0005
0.0006
0.0007
0.0008
0.0009
0.00


srn(A1) = nrecalc
srn(A1)
relaxation
relaxation
relax
no iteration
no iteration
no iteration
20
15
10
5
0
0
0.0001
0.0002
0.0003
0.0004
0.0005
0.0006
0.0007
0.0008
0.0009
0.00


out
gmn2
SR(10E-3,7E-3)
rdsn2
10E3
rdsp3
100E3
cload
5E-6
gmn1
SR(20E-3,15E-3)
rdsn1
100E3
Vin
"cos(wt)
10 kHz"
I(gmn1)
I(gmn2)
0.015
0.01
0.005
0
-0.005
-0.01
-0.015
0
2x10-5
4x10-5
6x10-5
8x10-5
0.0001
0.00012
0.00014
0.00016
0.00018
0.0002


srg(gmn1)
srg(gmn2)
linear zone
srg(gmn1) effective reduced gmn1 gain necessary to sustain max output
linear zone
srg(gmn2) effective reduced gmn2 gain necessary to sustain max output
0.02
0.015
0.01
0.005
0
0
2x10-5
4x10-5
6x10-5
8x10-5
0.0001
0.00012
0.00014
0.00016
0.00018
0.0002

Z transform

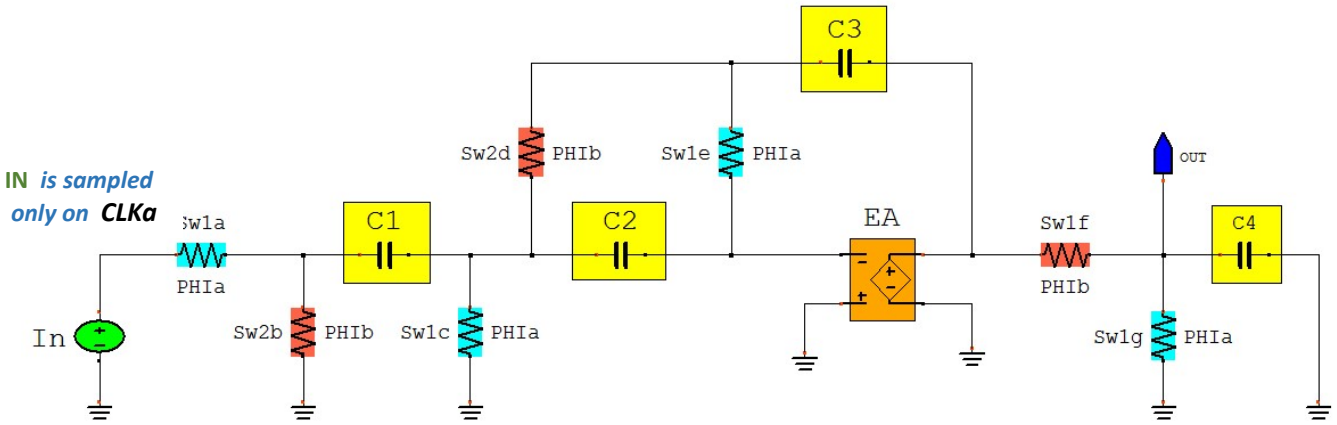


« *cycle mode* » means « *single sampling of the inputs per cycle* »

Therefore,

it only makes sens to request « *cycle model generation* » for *physical designs* structurally *insensitive to intracycle stimuli*

(otherwise this can also be achieved by externally « latch » the inputs within cycle)



... time response (when CLKb)

$$OUT_0 = \frac{nbIn_2\, In_{-1} + nbIn_0\, In_{-3} - db_1\, OUT_{-2}}{db_3}$$

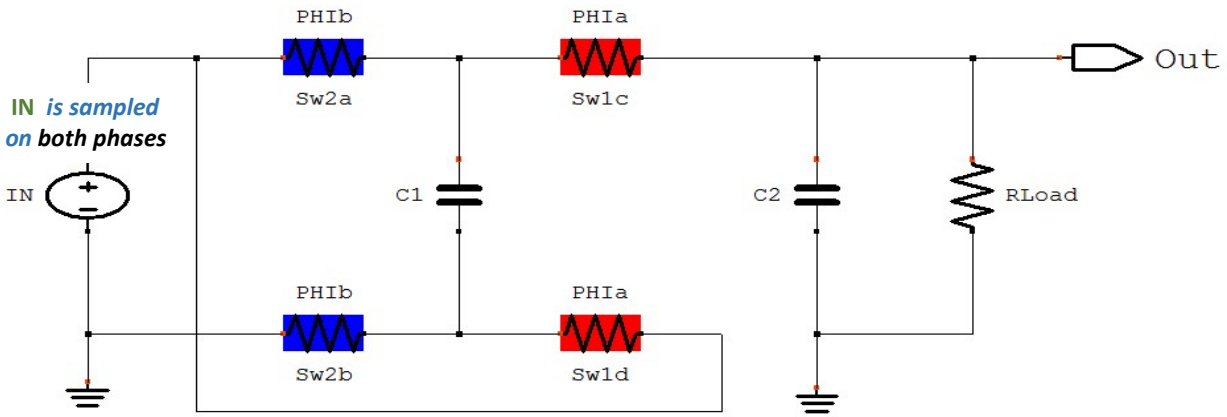
only odd indexes

➔ CLKa

... time response (cycle)

$$OUT_0 = \frac{nIn_1\, In_0 + nIn_0\, In_{-1} - d_0\, OUT_{-1}}{d_1}$$

=== NOTE: CYCLE mode will remain exact even in case of intracycle INPUT changes



... time response (when CLKb)

$$Out_0 = \frac{nbIN_1\, IN_{-1} + nbIN_0\, IN_{-2} - db_0\, Out_{-2}}{db_2}$$

intracycle
even index

➔ CLKb

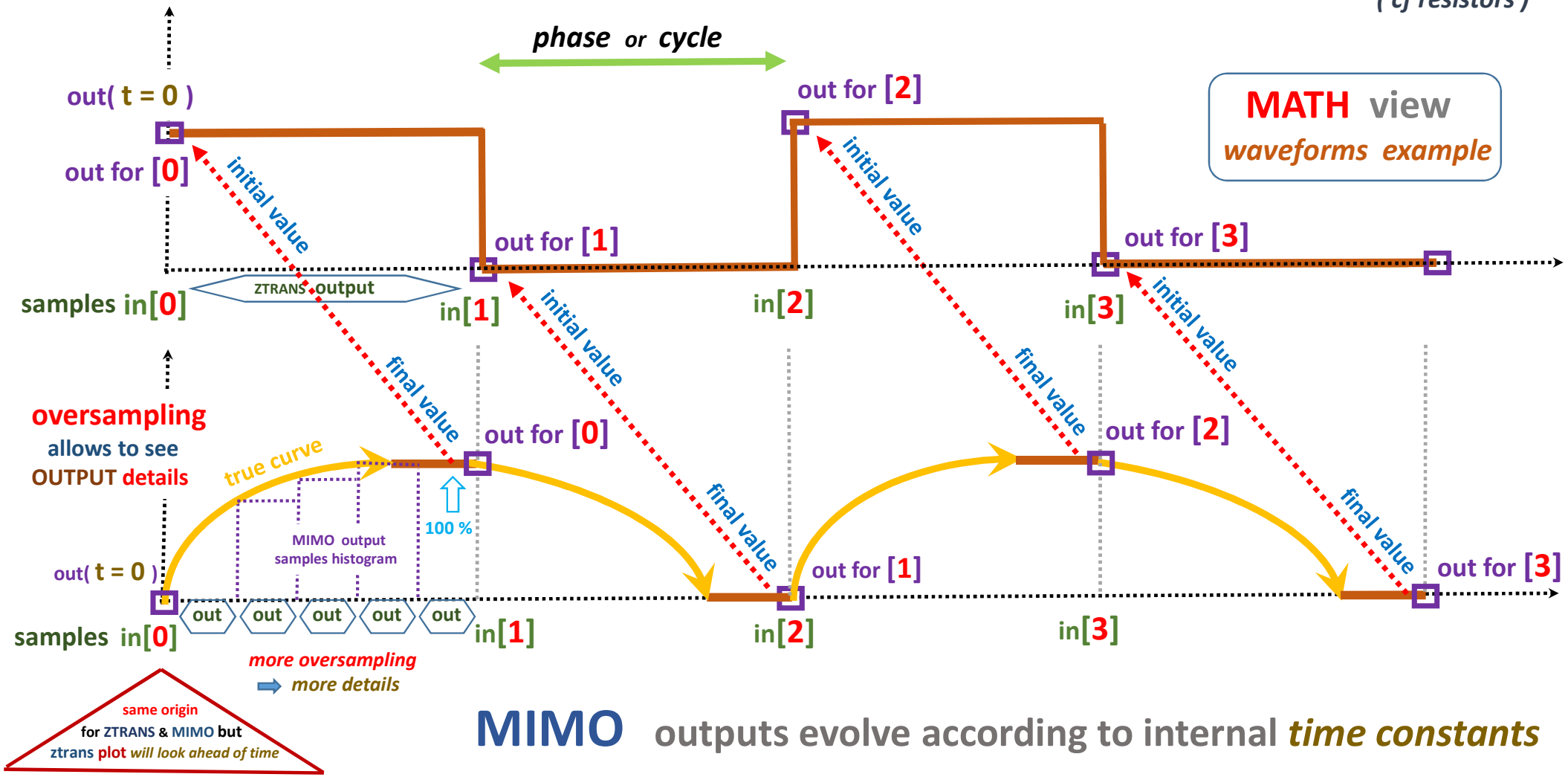
... time response (cycle)

$$Out_0 = \frac{nIN_1\, IN_0 + nIN_0\, IN_{-1} - d_0\, Out_{-1}}{d_1}$$

=== NOTE: CYCLE mode will not remain exact in case of intracycle INPUT changes due to CLKb coefficients = [IN_{-2}]

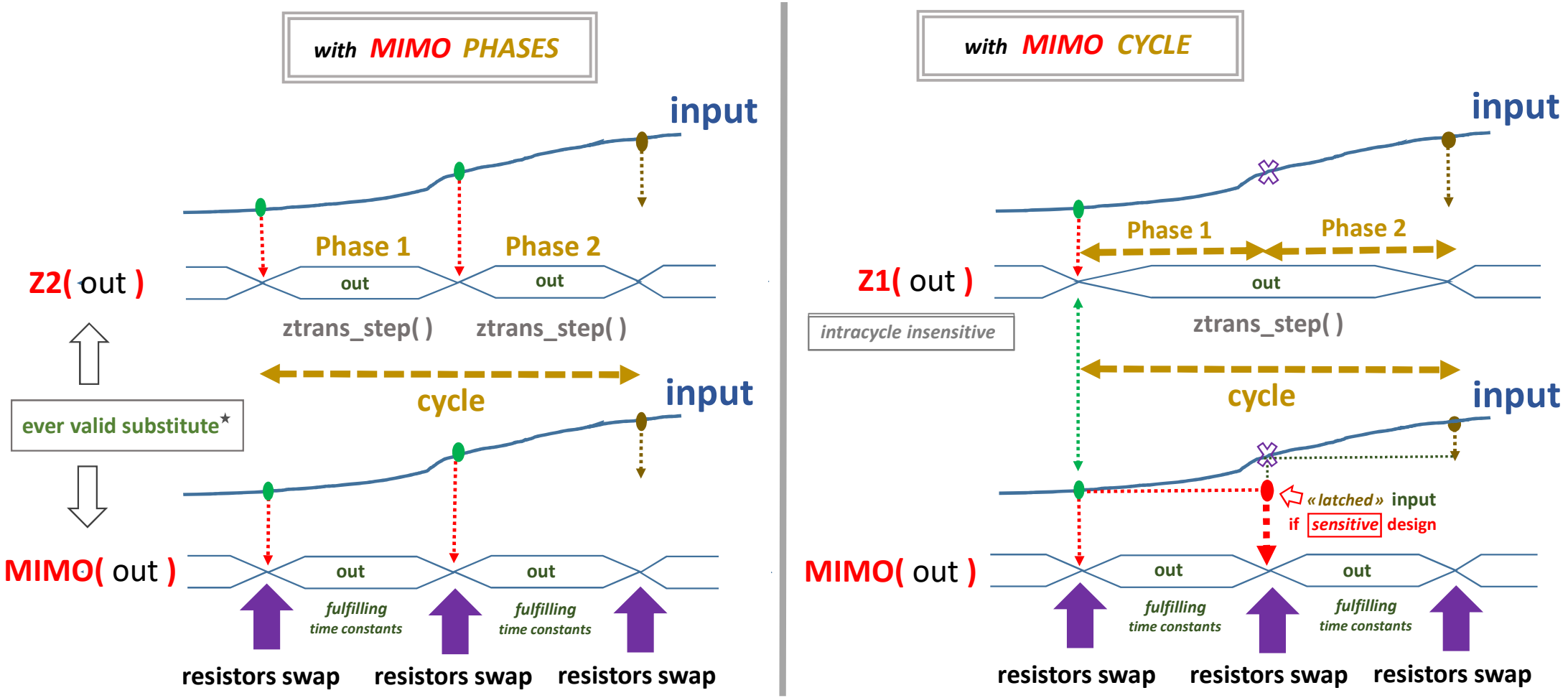
ZTRANS outputs evolve like MIMO would do if the time constants were removed

(cf resistors)



MIMO outputs evolve according to internal *time constants*

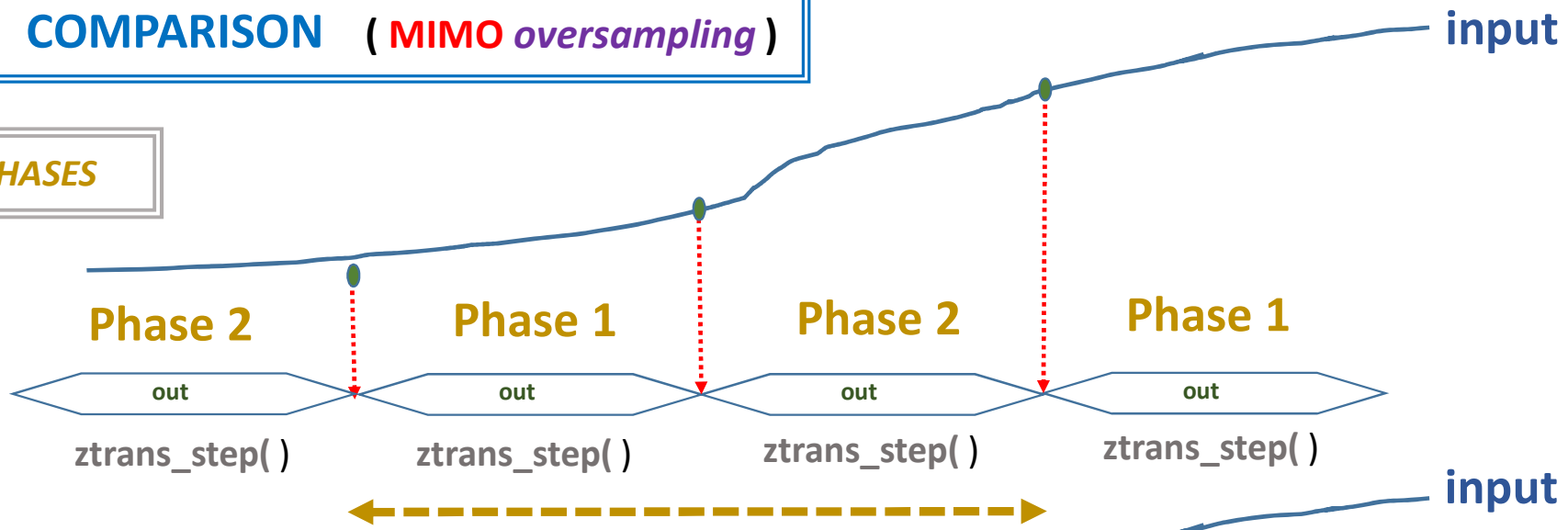
ZTRANS / MIMO COMPARISON (*basic case :* cycle = 2 steps)



★ *but possibly not identical due the MIMO analog time constants (and/or slewrate)*

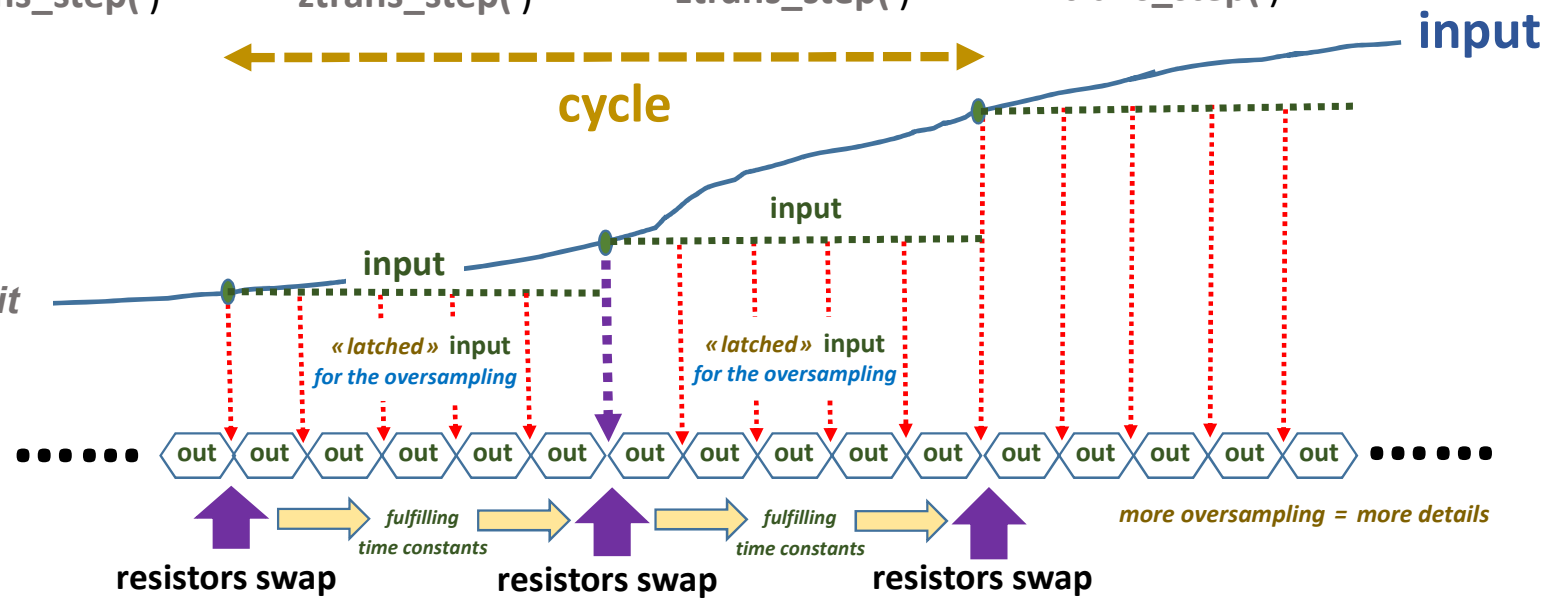
Z2 / MIMO COMPARISON (MIMO *oversampling*)

with ***MIMO PHASES***



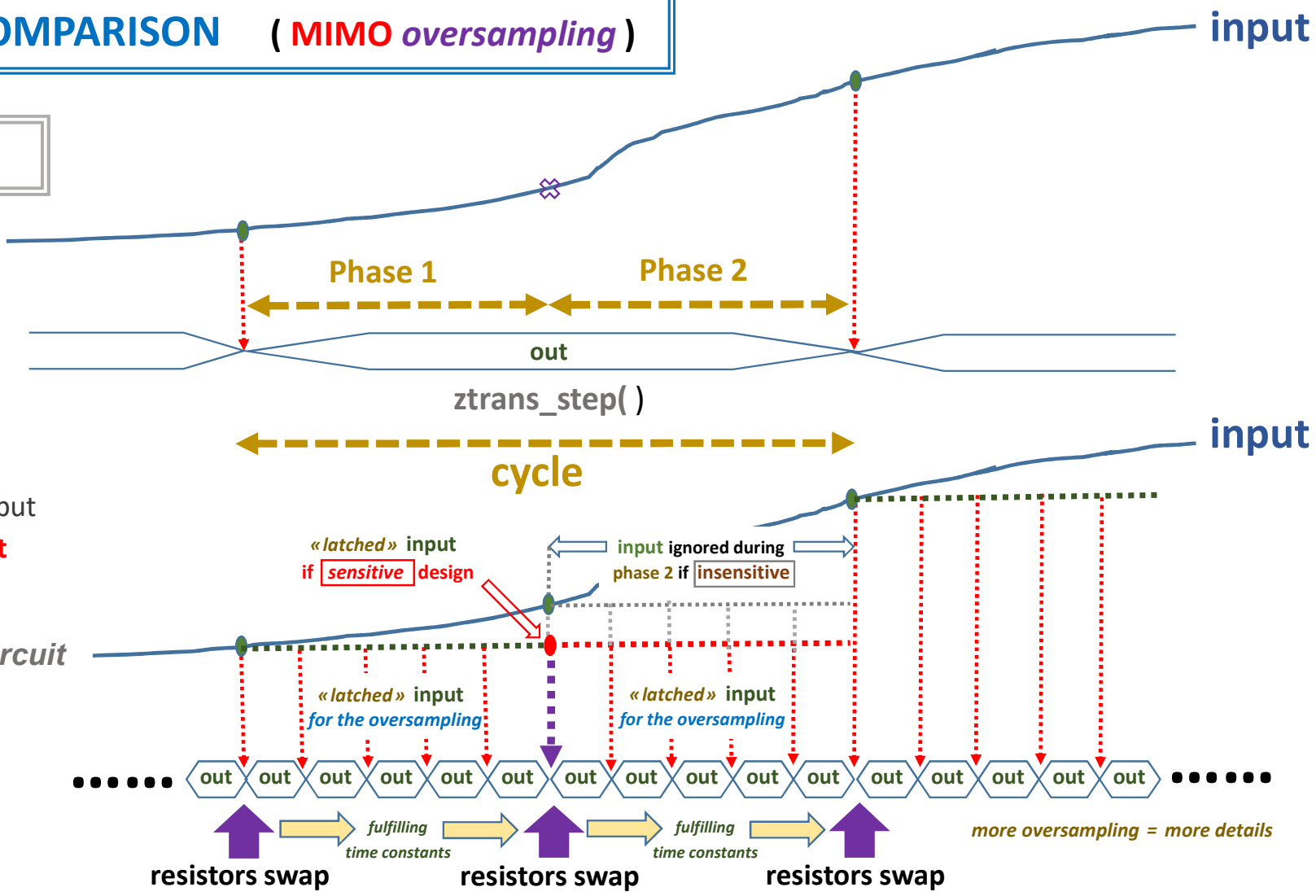
MIMO detailed curved line output
modelized by **Z squared output**

« INTEGRATOR » *type of circuit*



Z1 / MIMO COMPARISON (MIMO *oversampling*)

with ***MIMO CYCLE***



Z1(out)

intracycle insensitive

MIMO detailed curved line output
modelized by **Z squared output**

« INTEGRATOR » *type of circuit*

MIMO(out)

OVERSAMPLING

Comparison Z1(Out) versus Z2(Out)

... time response (cycle) — one sampling and one output value per cycle

Z1(Out)

$$Out_0 = \frac{nOffs_1\ Offs_0 + nVC2_1\ VC2_0 + nOffs_0\ Offs_{-1} + nVC2_0\ VC2_{-1} + nVin_0\ Vin_{-1} - d_0\ Out_{-1}}{d_1}$$

... time response (when CLKa) — irrelevant : cycle unique value masks any clka transient output

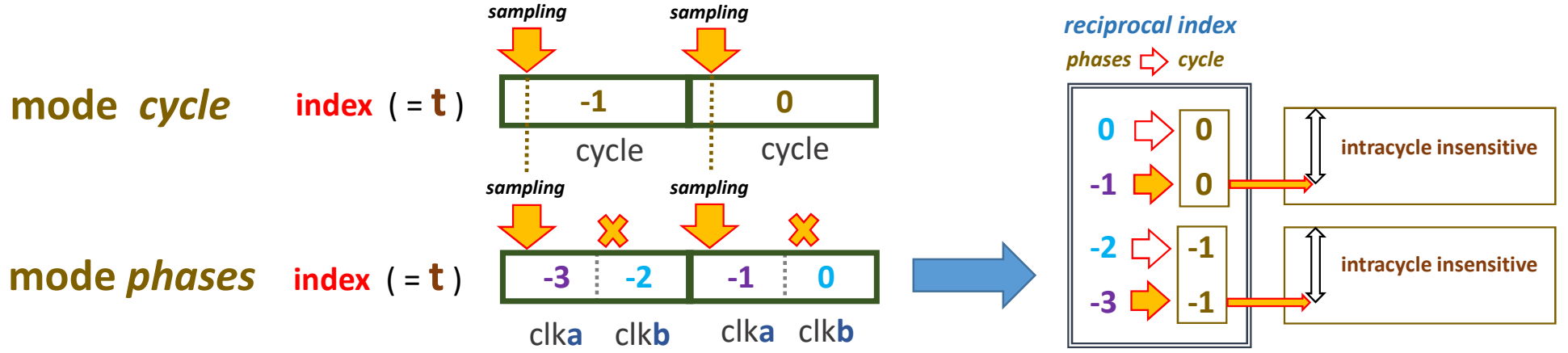
Z2(Out)

$$Out_0 = \frac{naOffs_2\ Offs_0 + naVC2_2\ VC2_0 + naVin_1\ Vin_{-1} + naOffs_0\ Offs_{-2} + naVC2_0\ VC2_{-2} - da_0\ Out_{-2}}{da_2}$$

... time response (when CLKb) — equation of clkb output calculates by construct the final [clka clkb] output value

$$Out_0 = \frac{nbOffs_2\ Offs_0 + nbVC2_2\ VC2_0 + nbOffs_1\ Offs_{-1} + nbVC2_1\ VC2_{-1} + nbOffs_0\ Offs_{-2} + nbVC2_0\ VC2_{-2} + nbVin_0\ Vin_{-2} - db_0\ Out_{-2}}{db_2}$$

this expression plotted all along the cycle = Z1(Out)



Comparison Z1(Out) versus Z2(Out)

... time response (cycle) — one sampling and one output value per cycle — **Z1(Out)**

$$Out_0 = \frac{nOffs_1\ Offs_0 + nVC2_1\ VC2_0 + nOffs_0\ Offs_{-1} + nVC2_0\ VC2_{-1} + nVin_0\ Vin_{-1} - d_0\ Out_{-1}}{d_1}$$

... time response (when CLKa) — irrelevant : cycle unique value masks any clka transient output — **Z2(Out)**

$$Out_0 = \frac{naOffs_2\ Offs_0 + naVC2_2\ VC2_0 + naVin_1\ Vin_{-1} + naOffs_0\ Offs_{-2} + naVC2_0\ VC2_{-2} - da_0\ Out_{-2}}{da_2}$$

... time response (when CLKb) — equation of clkb output calculates by construct the final [clka clkb] output value

$$Out_0 = \frac{nbOffs_2\ Offs_0 + nbVC2_2\ VC2_0 + nbOffs_1\ Offs_{-1} + nbVC2_1\ VC2_{-1} + nbOffs_0\ Offs_{-2} + nbVC2_0\ VC2_{-2} + nbVin_0\ Vin_{-2} - db_0\ Out_{-2}}{db_2}$$

this expression plotted all along the cycle = Z1(Out)

intracycle insensitive

internal cycle

cycle / cycle shift

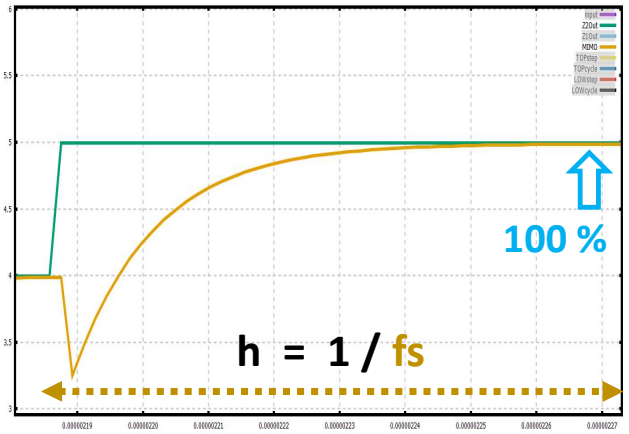
$Offs_{-1} \rightarrow Offs_0$	$VC2_{-1} \rightarrow VC2_0$	Vin_{-1} not present in above expression	
$Offs_{-2} \rightarrow Offs_{-1}$	$VC2_{-2} \rightarrow VC2_{-1}$	$Vin_{-2} \rightarrow Vin_{-1}$	$Out_{-2} \rightarrow Out_{-1}$

by construction there is no possible Out_{-1} coefficient

clkb is not using clka output as one of its inputs

$$Out_0 = \frac{(nbOffs_2 + nbOffs_1)\ Offs_0 + (nbVC2_2 + nbVC2_1)\ VC2_0 + nbOffs_0\ Offs_{-1} + nbVC2_0\ VC2_{-1} + nbVin_0\ Vin_{-1} - db_0\ Out_{-1}}{db_2}$$

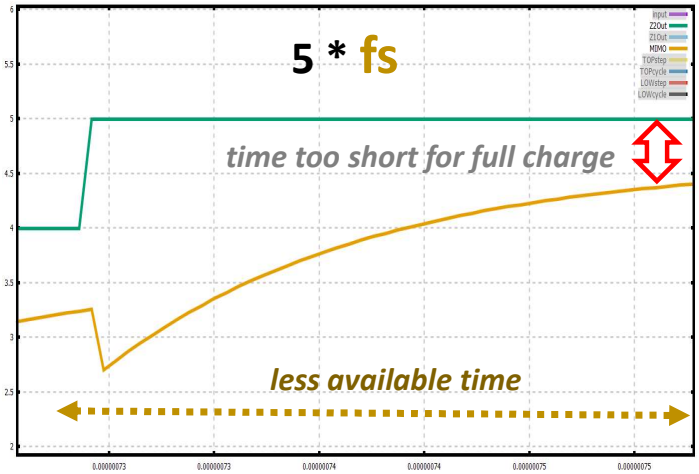
fs ≈ function(*rate of decay*)



charge MIMO < ZTRANS = *100 %*

when fs ↗

charge < 100 %

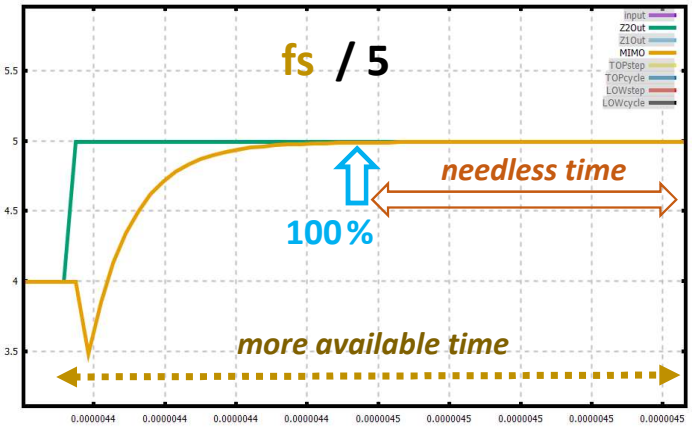


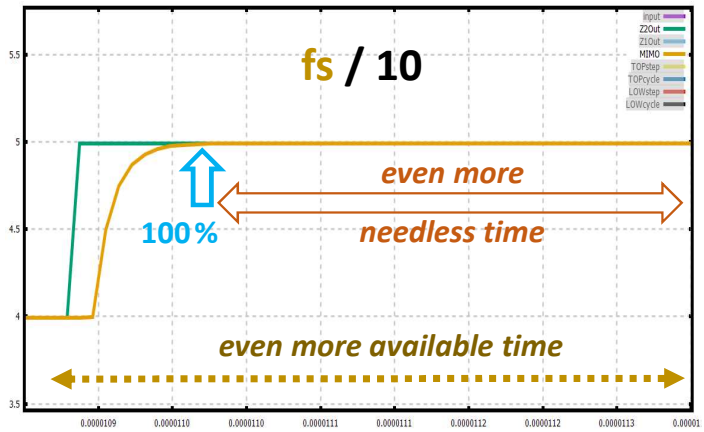
when fs ↘

visual aspect

ZTRANS

MIMO





Globals

```
%phases     = [ PHIa , PHIb ]
%zshort     = RDS
%printpoles = 2
k
AV
Vmax
```

rate of decay **a**

```
>>> SARC  Z_Integrator -> i1 -> POLES
POLES : matrix(
[ -1.67226124659431225154548883438110E+04   , +0.00000000000000000000000000000000E+00   ] ,
[ -8.01445909870613068342208862304688E+07   , +0.00000000000000000000000000000000E+00   ] ,
[ -2.00000000000000000000000000000000E+20   , +0.00000000000000000000000000000000E+00   ] ,
[ -5.00499980004099138519040000000000E+23   , +0.00000000000000000000000000000000E+00   ] ) ;
```

REAL part *frequency part*


```
>>> SARC  Z_Integrator -> i1 -> POLES
POLES : matrix(
[ -1.67226124659431225154548883438110E+04   , +0.00000000000000000000000000000000E+00   ] ,
[ -8.01445909870613068342208862304688E+07   , +0.00000000000000000000000000000000E+00   ] ,
[ -2.00000000000000000000000000000000E+20   , +0.00000000000000000000000000000000E+00   ] ,
[ -5.00499980004099138519040000000000E+23   , +0.00000000000000000000000000000000E+00   ] ) ;
```


$$e^{-at} = e^{-t/\tau}$$

$$\tau = \frac{1}{a} \approx 35\ \%\ \textit{full charge time}$$

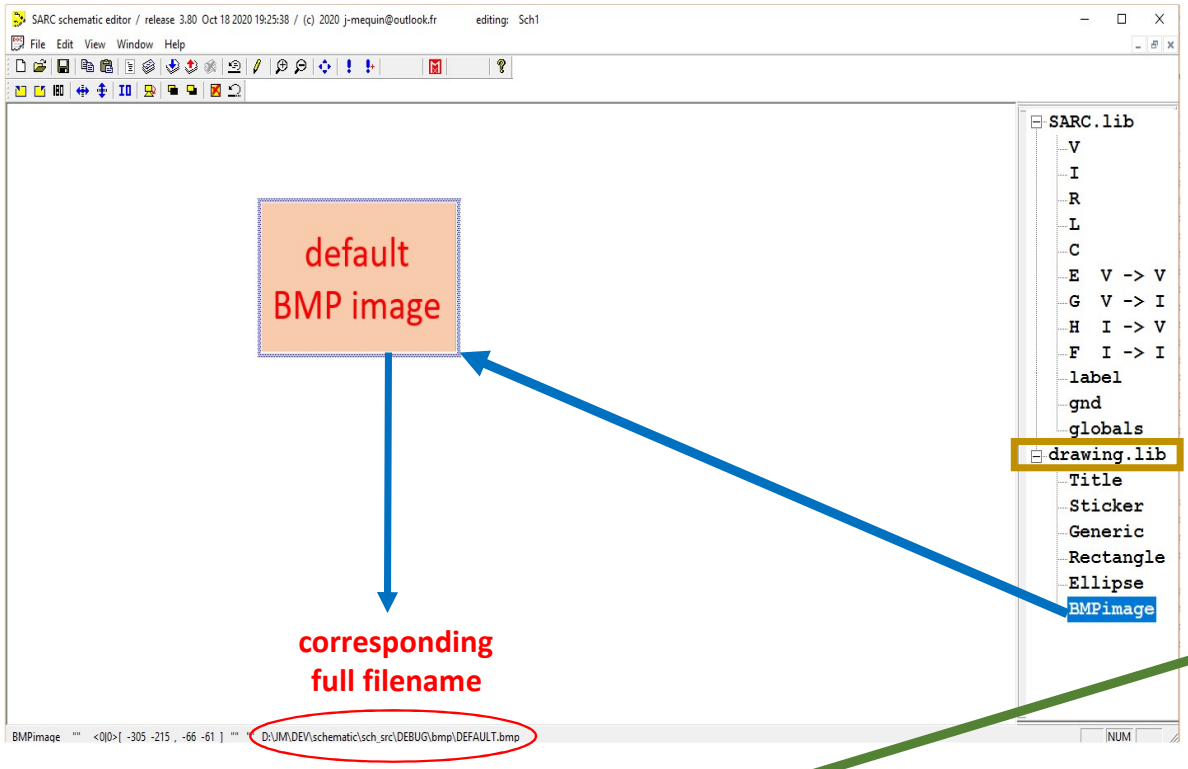
$$10\ \tau \Rightarrow e^{-1/10} \approx 90\ \%$$

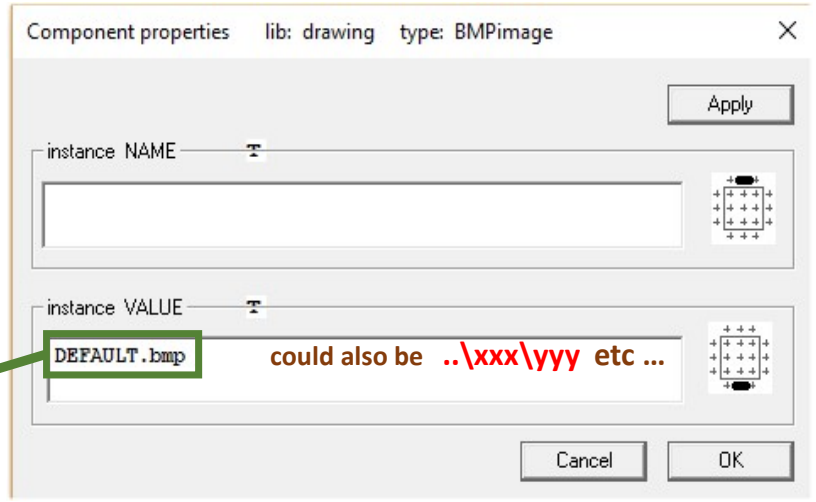
$$fs \approx \frac{a}{10} \quad \text{for } 90\ \%$$

$n = -1 / \ln(\%)$

5 *is a recommended rule of thumb*

BMP image insertion



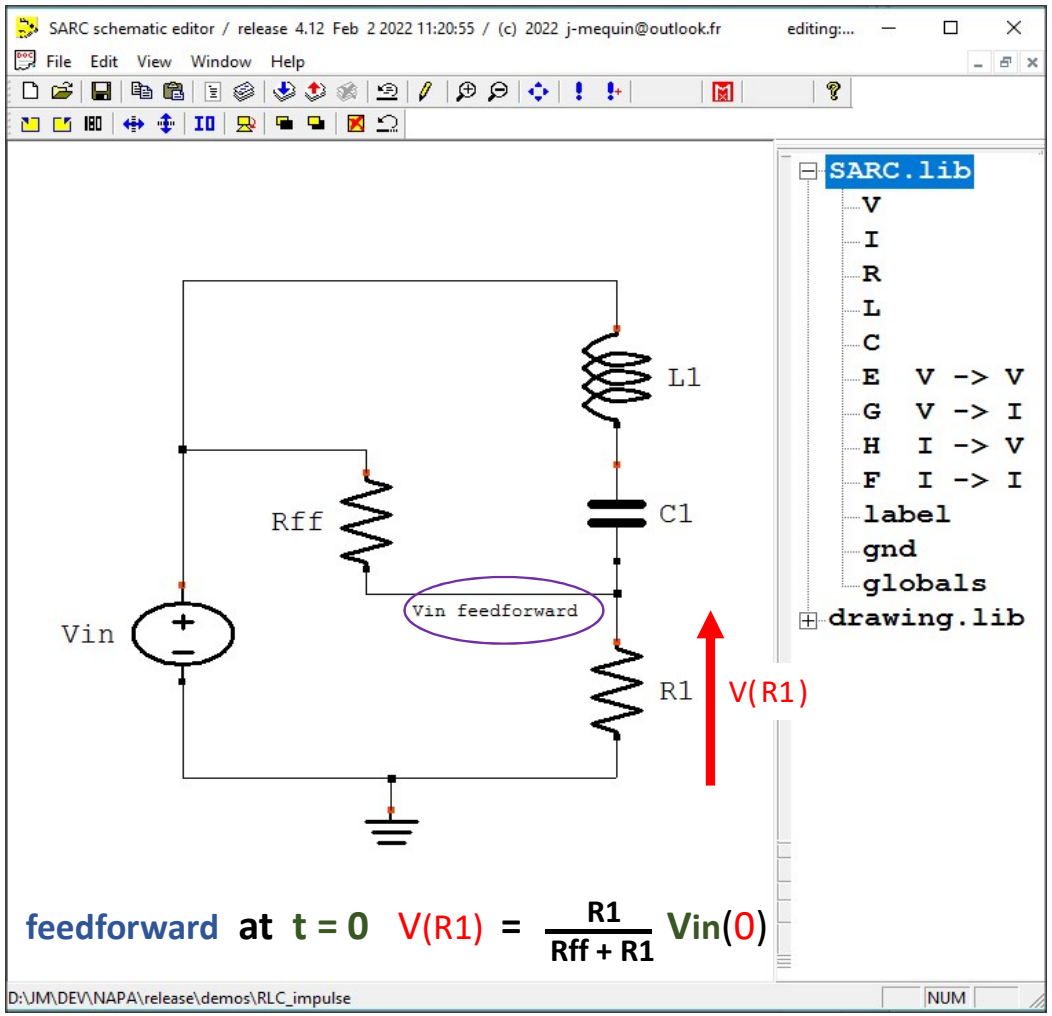


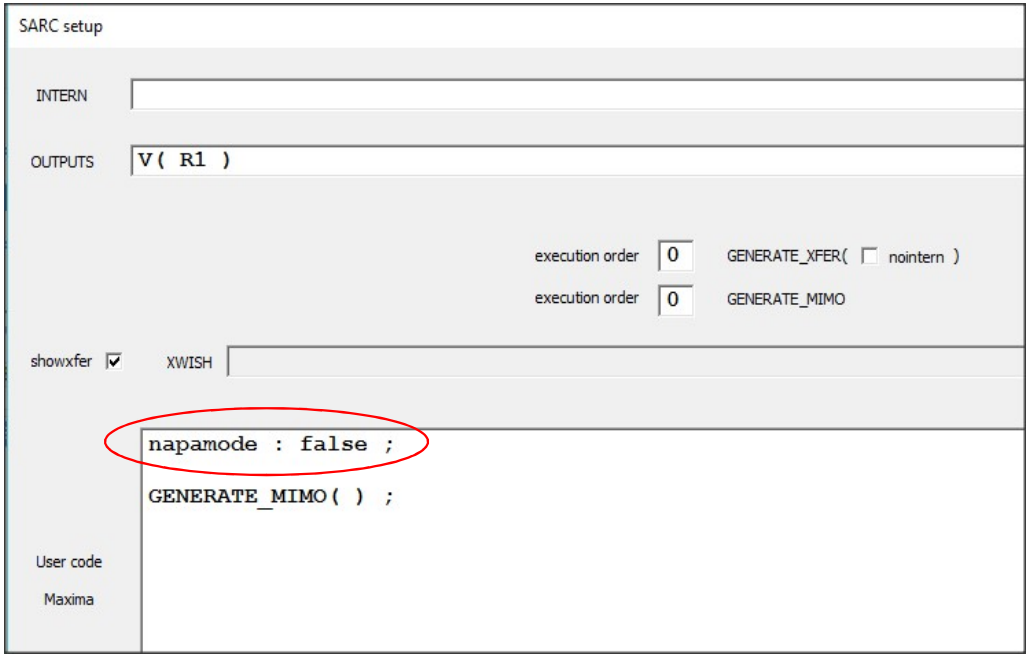
can be replaced with

- a **filename** that can be found in the **document folder** (*document must have been already saved at least once*)
- a **filename** that can be found in the **schematic editor installation bmp/ folder** (*= visible by all documents*)
- a **full filename**

impulse response

standalone « C » validation model





RLC_impulse.c

ANALOG_VIEW : false ⇨ **MATH**

$$A=\begin{bmatrix} -\frac{R1\,Rff}{L1\,(Rff+R1)} & -\frac{1}{L1} \\ \frac{1}{C1} & 0 \end{bmatrix}$$

$$B=\begin{bmatrix} \frac{Rff}{L1\,(Rff+R1)} \\ 0 \end{bmatrix}$$

$$C=\begin{bmatrix} \frac{R1\,Rff}{Rff+R1} & 0 \end{bmatrix}$$

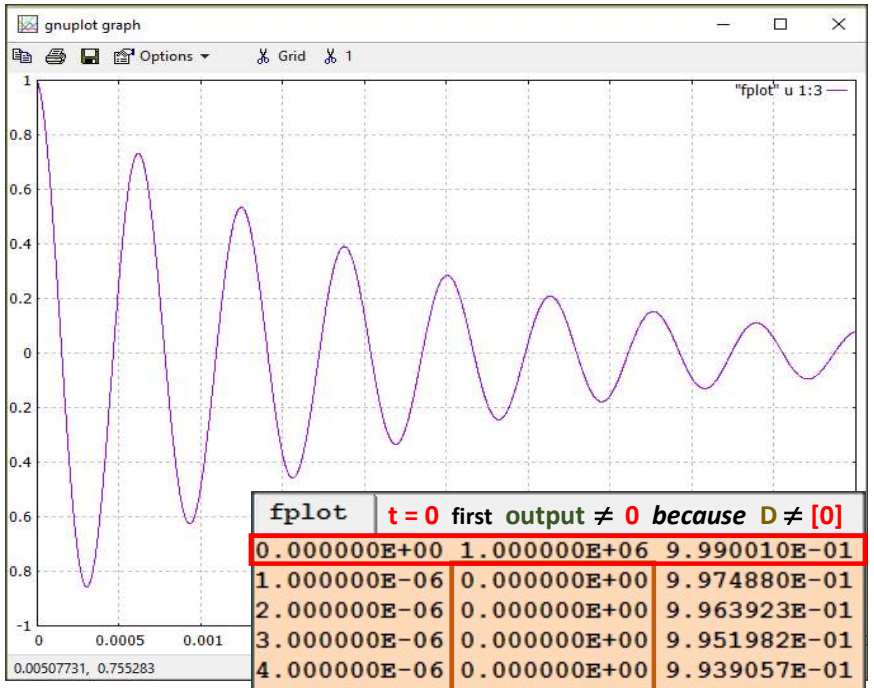
$$D=\begin{bmatrix} \frac{R1}{Rff+R1} \end{bmatrix}$$

feedforward

```
#include             <stdio.h>
#include           "SARC_api.h"
#include  "RLC_impulse_mimo.h"

/*-------------------------*/
double   L1          =  100E-3 ;
double   C1          =  100E-9 ;
double   R1          =  100    ;
double   Rff         =  1E5    ;
/*-------------------------*/
double   dirac       =  1E6    ;
int      samples     =  5000   ;
/*-------------------------*/

int main( )
{
   FILE   *fgnuplot = fopen( "fplot" , "w" ) ;

   double  t   =  0          ;
   double  h   =  1 / dirac  ;
   double  Vin =  0          ;  double normalize = R1 / L1 ;  /* max output */

   pSARC psarc =  SARC_ALLOC( MIMO_RLC_impulse( ) , "i1" ) ;

   double  U[ 1 ]  ;  double  *lookup_INPUTS[ ] = { &U[0] }                    ;
   double  Y[ 1 ]  ;  double *lookup_OUTPUTS[ ] = { &Y[0] }                    ;
                      double     *lookup_BOM[ ] = { &L1 , &C1 , &R1 , &Rff } ;

   psarc->lookup_h        =  &h                    ;
   psarc->lookup_INPUTS   =  &lookup_INPUTS[ 0 ]   ;
   psarc->lookup_OUTPUTS  =  &lookup_OUTPUTS[ 0 ]  ;
   psarc->lookup_BOM      =  &lookup_BOM[ 0 ]      ;

   for ( int n = 0 ; n < samples ; n++ )
   {
       if ( t == 0 ) Vin = dirac ;
             else    Vin =  0    ;

                     SARC_STEP_Tminus( psarc ) ;
       U[ 0 ] =  Vin  ;  SARC_STEP_Tplus( psarc ) ;

       fprintf( fgnuplot , "%E %E %E\n" , t , U[0] , Y[0] / normalize ) ;

       t = t + h ;
   }

   return 0 ;
}
```

⇦ dirac *(single step)*


```
gnuplot
File  Plot  Expressions  Functions  General  Axes  Chart  Styles  3D  Help
Replot  Open  Save  ChDir  Print  PrtSc  Prev  Next  Options

        G N U P L O T
        Version 5.0 patchlevel 6    last modified 2017-03-18

        Copyright (C) 1986-1993, 1998, 2004, 2007-2017
        Thomas Williams, Colin Kelley and many others

        gnuplot home:     http://www.gnuplot.info
        faq, bugs, etc:   type "help FAQ"
        immediate help:   type "help"  (plot window: hit 'h')

Terminal type set to 'windows'
gnuplot> cd "/jm/dev/napa/release/demos/RLC_impulse"
gnuplot> plot "fplot" u 1:3 w l
gnuplot>
```



fplot	t = 0 first output ≠ 0 *because* D ≠ [0]	
0.000000E+00	1.000000E+06	9.990010E-01
1.000000E-06	0.000000E+00	9.974880E-01
2.000000E-06	0.000000E+00	9.963923E-01
3.000000E-06	0.000000E+00	9.951982E-01
4.000000E-06	0.000000E+00	9.939057E-01
5.000000E-06	0.000000E+00	9.925152E-01
t	**input**	**output**

APPENDIX

The **wxPAUSE( )** function can be used to force a **pause** during the execution of a **wxMaxima** script

default SARC *environment variables*

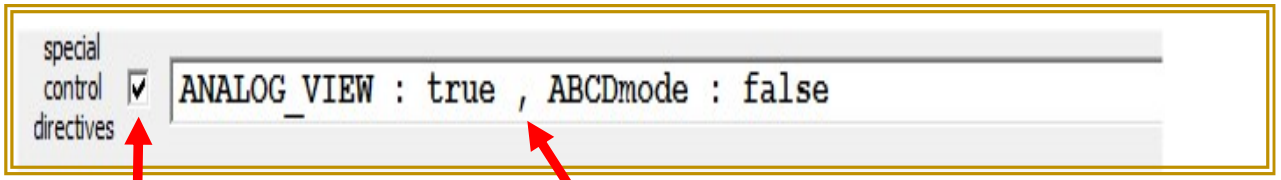
default

napamode	:	false	;	true / false
ANALOG_VIEW	:	false	;	true / false
convention	:	"PSC"	;	"PSC" / "GLC"
ABCDmode	:	true	;	true / false

or GCC *compile option*
-DGCC_ANALOG_VIEW=0/1

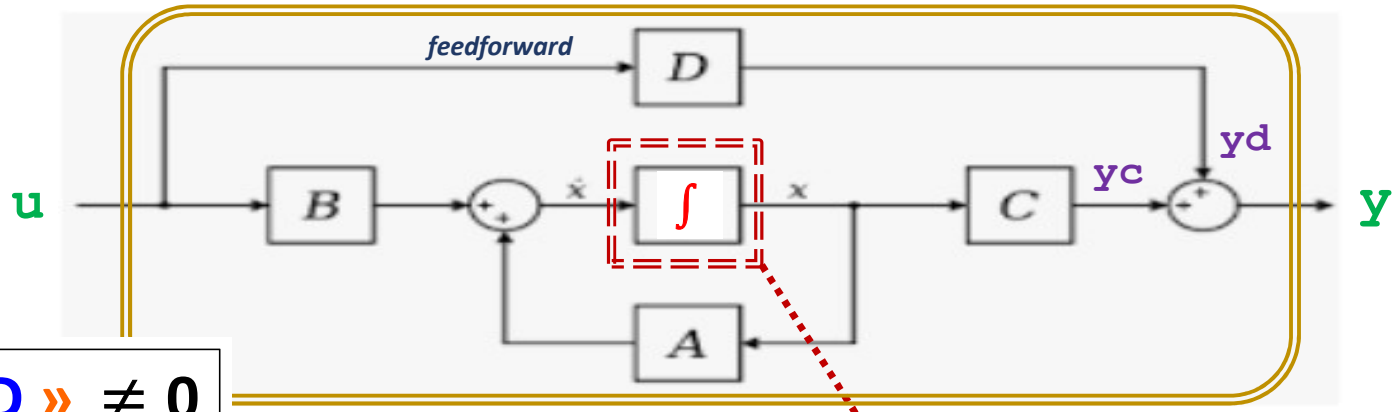
could be *redefined* in the **Maxima** *initialisation environment file*

or **in a *SARC setup* *pop up* menu**



enable **or** ***disable*** **these directives**

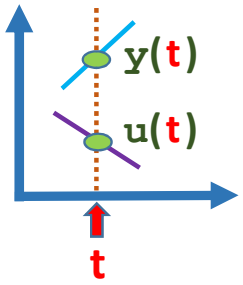
comma



when « D » ≠ 0

mathematical response $y(t) = yc(t) + yd(t) = fc(u(t-1)) + fd(u(t))$

zero delay dependency



This is not an issue for the SARC validation environment that simulates standalone « C » model **individually**

---

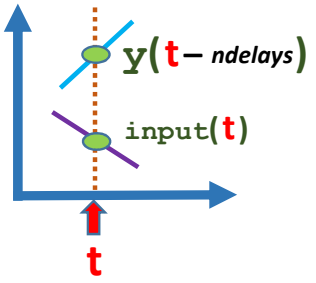
but, *independently of* ***SARC*** *, zero delay blocks are almost always* ***delayed**** *by simulators* *(including* **NAPA** *)*

simulator response $y(t) = fc(u(t-2)) + fd(u(t-1))$

this is ok

but implies ***plots***

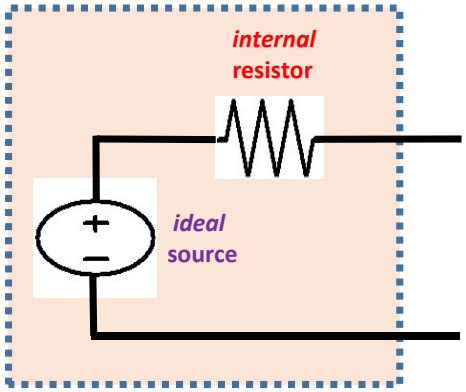
(imperceptible with small steps)

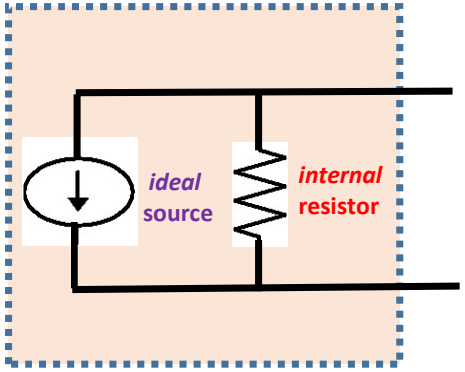


* *to* **prevent** *the* **eventuality** *of a* **zero delay** **assembly** *building* **a snake biting its own tail**

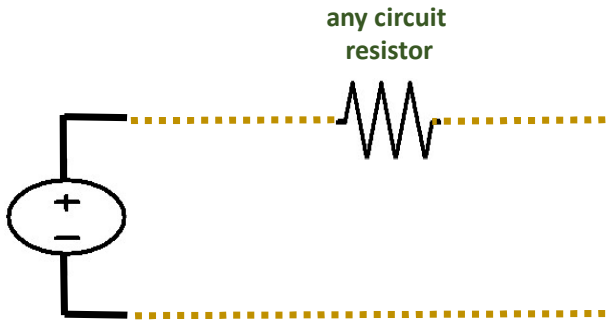
(regarding **SARC** *the fact that* **D** *could be* **≠ 0** *should not qualify the block as "zero delay" since the feedforward is handled internally only once per step)*

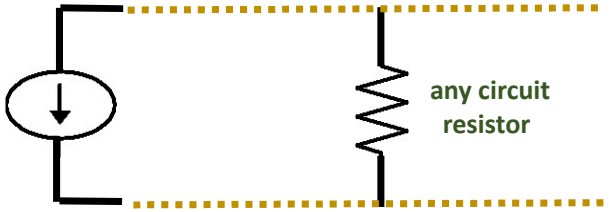
academic *physical* source





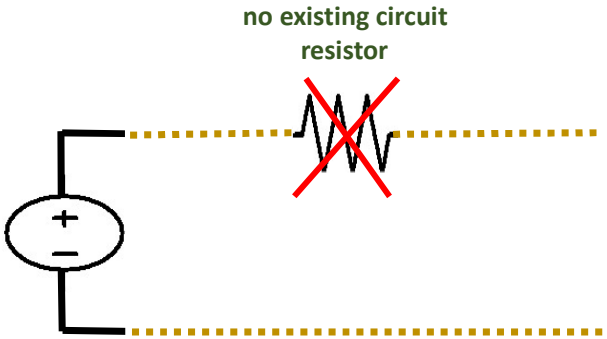
SARC *proper* source

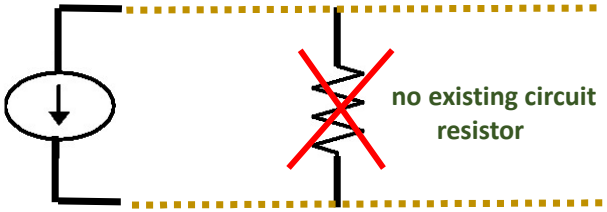




SARC *boundless* source

NO RESISTOR ➡ ***NO TIME CONSTANT***



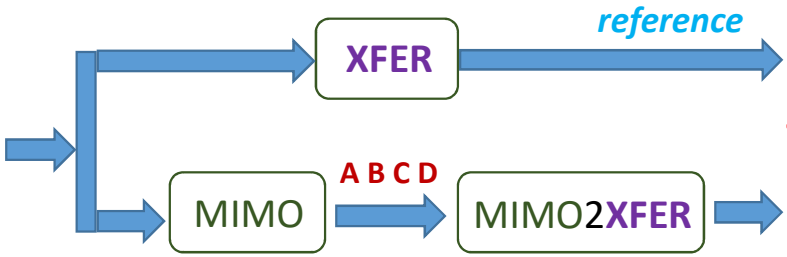


QC methods

for « *healthy* » outputs (without *Warnings*)

1)

circuit

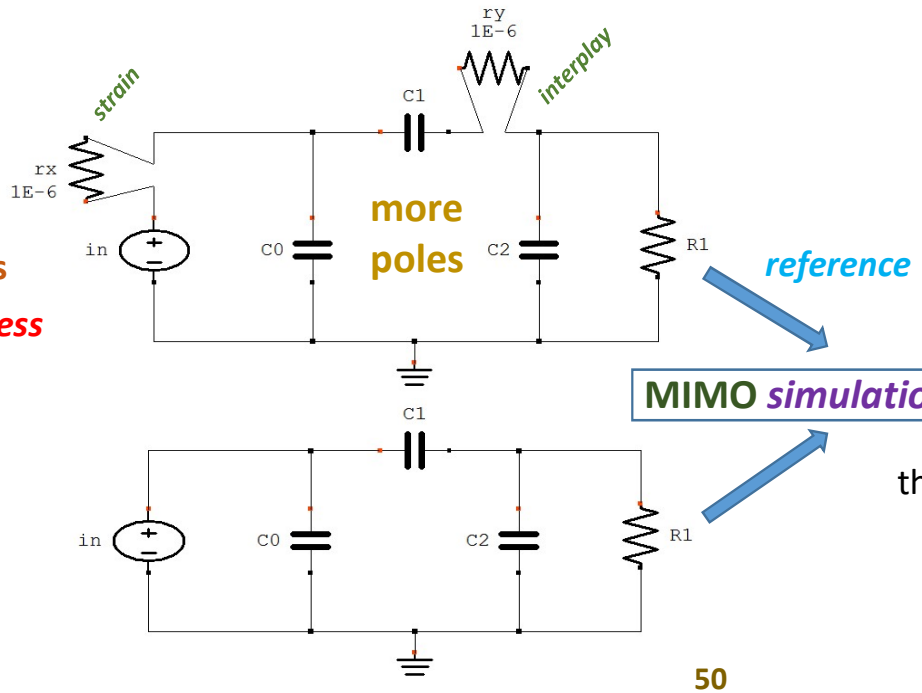


??? *transfer functions* *should be* *the same*

this verifies that **A B C D** are the **correct ones**

2)

updated circuit
with **small** resistors
to eliminate **ALL** ***boundless***
(*strain* *and* *interplay*)

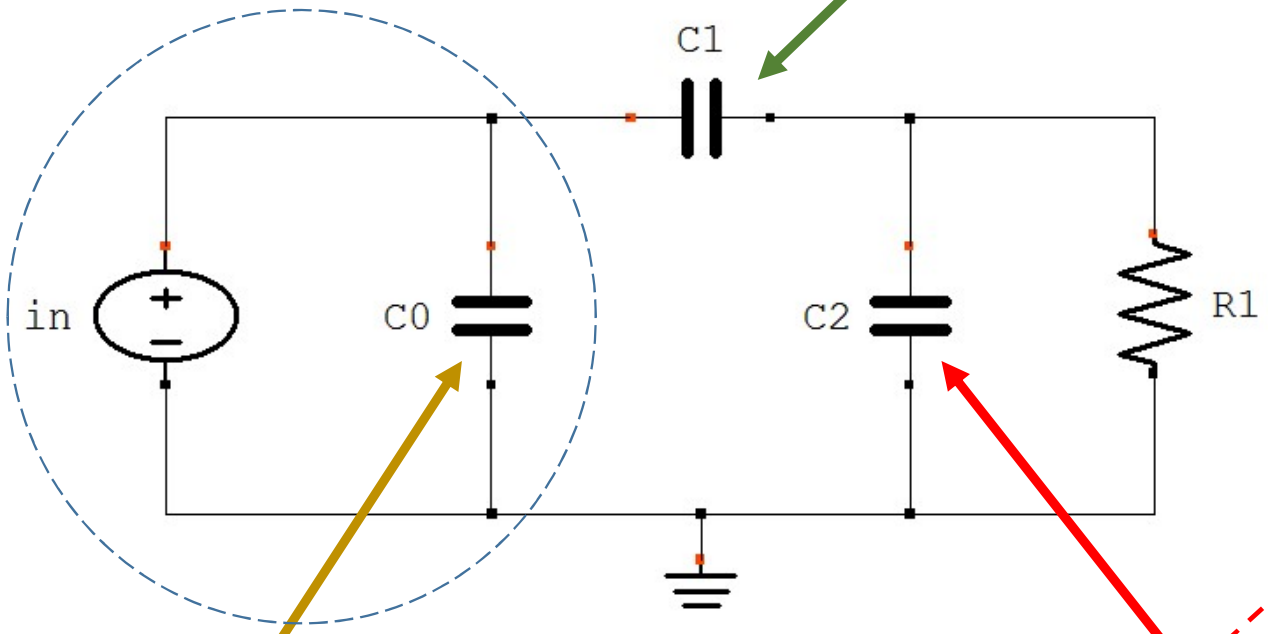


??? *plots* *should be* *the same*

this verifies that the "***boundless***" are **well handled**

boundless circuit
under QC

```
MIMO status variables
=====================

  NULL      =  DEGEN + AKIN  ( degenerated states are toxic for circuit state matrix invertibility )

  DEGEN     "degenerated" states

                * when several C are forming a mesh

                          one C voltage is therefore enslaved to the others  ( KVL )

                * when several L have their respective current converging to an ISOLATED node

                          one L current is therefore enslaved to the others  ( KCL )

              In those configurations, it should be noted that a voltage source can also play
              the role of a C or a current source the role of a L

  AKIN      simplest kind of "degenerated" states :  parallel C  or  serial L

                   same voltage for C    ( ==>> redundant states )
                     or current for L    ( ==>> redundant states )

  COX       collinear states resulting from ISOLATED   serial C  or  parallel L
                   same current for C    ( I = C dV/dt = C dX/dt ==>> prorated states )
                     or voltage for L    ( V = L dI/dt = L dX/dt ==>> prorated states )
              thus they cannot be counted as "degenerated" BUT they must be also discarded for
              state matrix invertibility

  U2X       boundless INPUT sources            ( no R limiting maximum source throughput )

  CS2X      boundless controlled sources       ( no R limiting maximum source throughput )

  P2X       PERCUSSION states reciprocal contribution
```



degenerated

cannot be a state

unique remaining state

```
... NLC                : 3
... NESE               : 3
... NSTATES            : 1
... XWISH              : [C0,C2]
 SERIAL   []
PARALLEL [[C2,R1]]
```

$$STATES = \left[V(C2) \right]$$

$$ESE = \begin{bmatrix} [C0] \\ [C1] \\ [C2] \end{bmatrix}$$

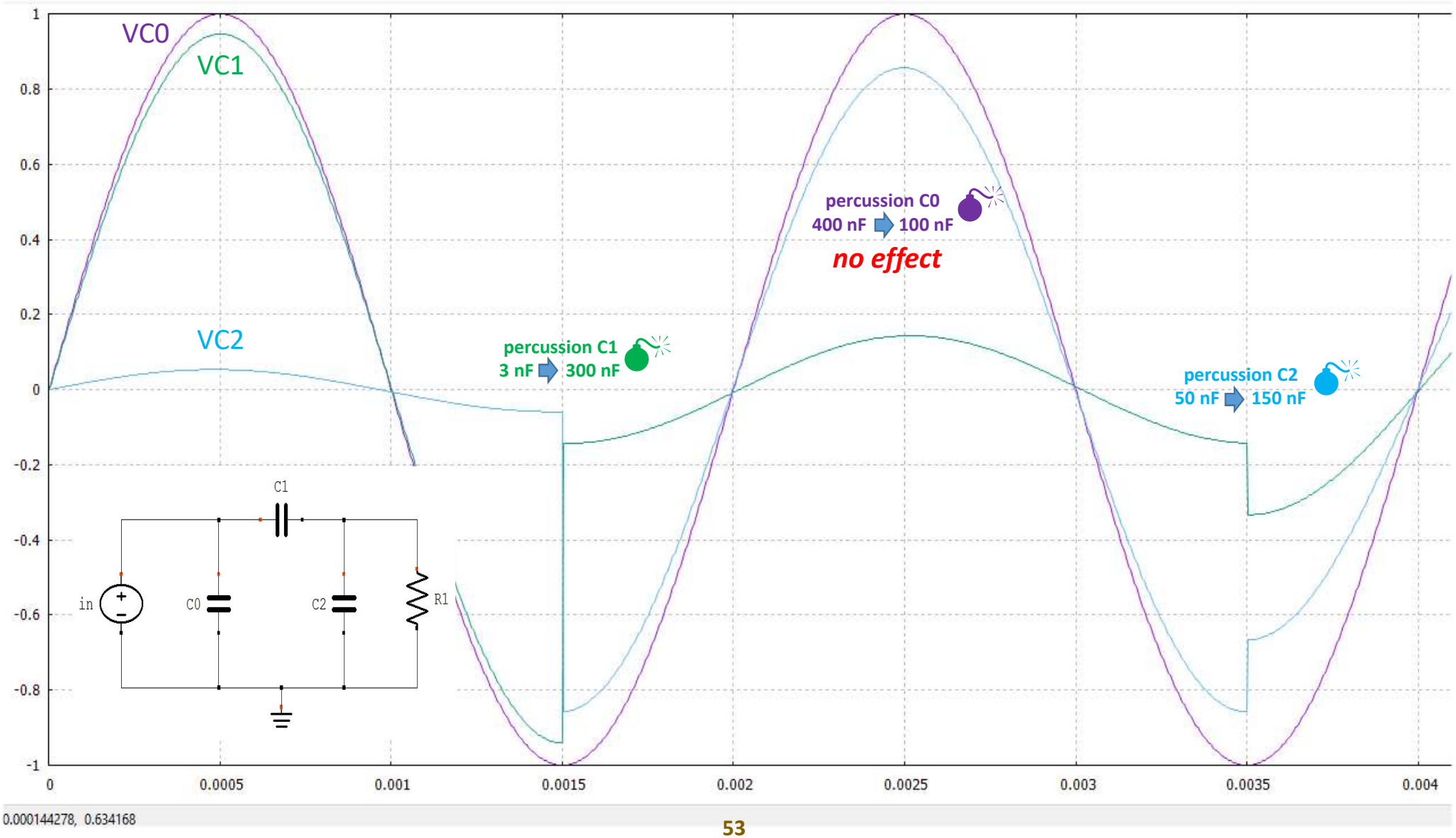
$$A = \left[-\frac{1}{(C2+C1)\,R1} \right]$$

$$B = \left[-\frac{C1}{(C2+C1)^{2}\,R1} \right]$$

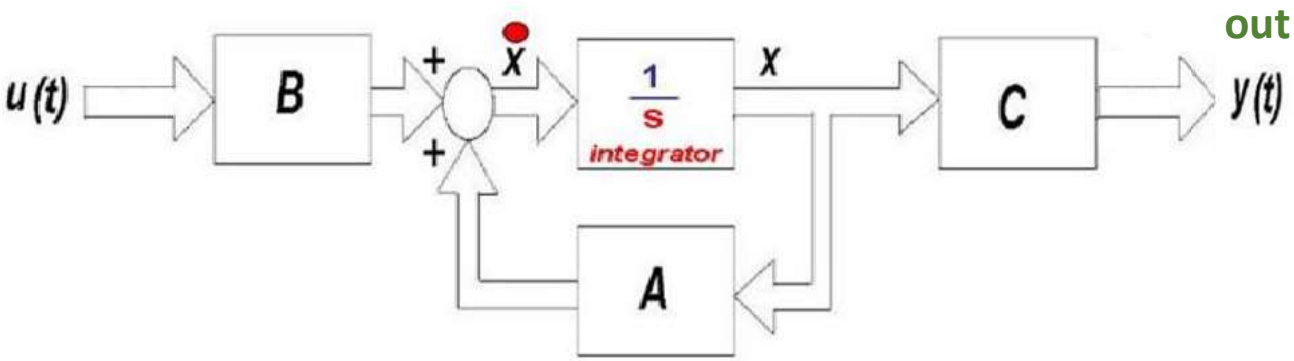
$$C = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 1 \\ \frac{C2}{C2+C1} \\ \frac{C1}{C2+C1} \end{bmatrix}$$

OUTPUTS `V( C0 ) , V( C1 ) , V( C2 )`

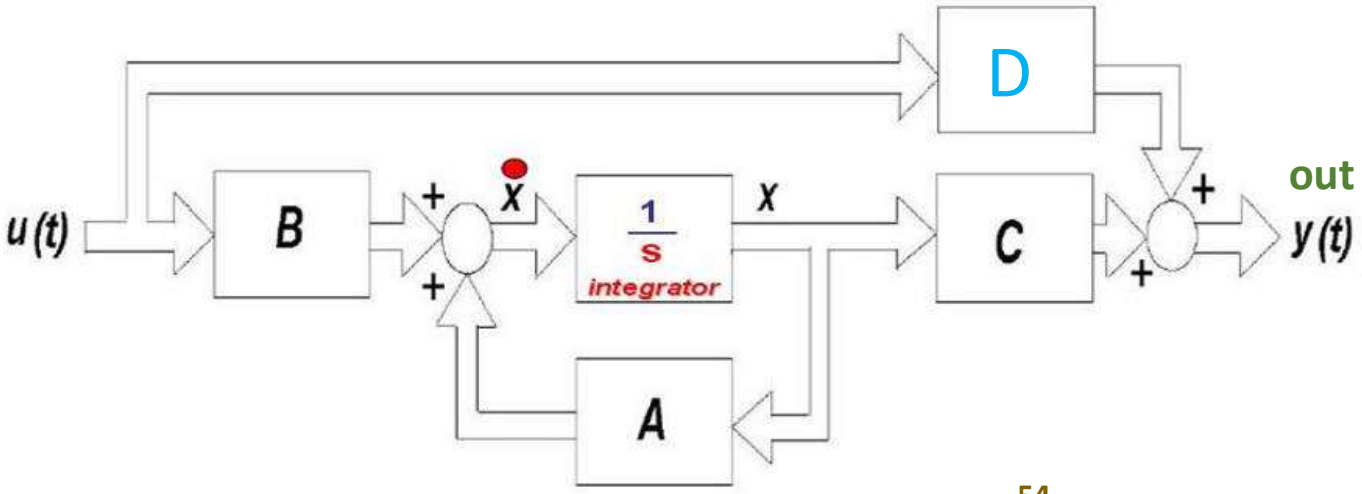

VC0
VC1
VC2
percussion C0
400 nF 100 nF
no effect
percussion C1
3 nF 300 nF
percussion C2
50 nF 150 nF
C1
in
C0
C2
R1
1
0.8
0.6
0.4
0.2
0
-0.2
-0.4
-0.6
-0.8
-1
0
0.0005
0.001
0.0015
0.002
0.0025
0.003
0.0035
0.004
0.000144278, 0.634168

MIMO2XFER



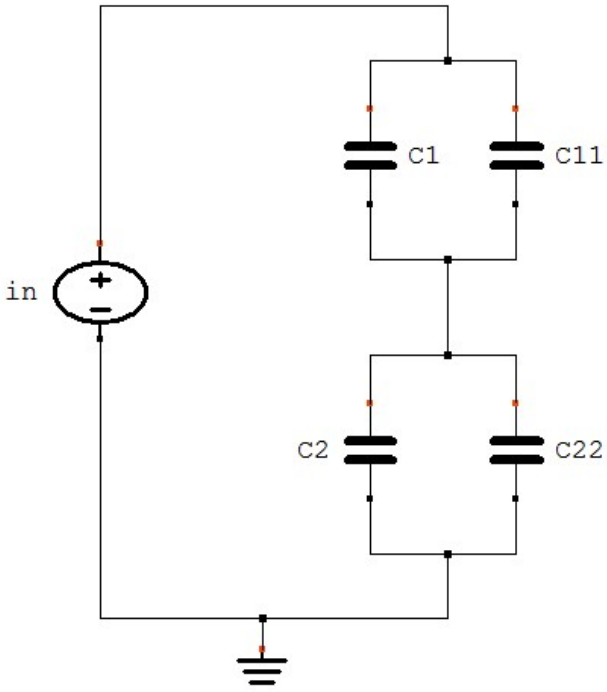
PROPER *transfer function*

$D[\text{out}] = 0$



BIPROPER *transfer function*

$D[\text{out}] \neq 0$



OUTPUTS V(C1) , V(C2)

GENERATE_XFER

SERIAL []
PARALLEL [[C1,C11],[C2,C22]]

$$1 \quad V(C1)/in = \frac{C22+C2}{C22+C2+C11+C1}$$

$$2 \quad V(C2)/in = \frac{C11+C1}{C22+C2+C11+C1}$$

no |s| term ⟺ no pole

GENERATE_MIMO

SERIAL []
PARALLEL [[C1,C11],[C2,C22]]
STATES=none

$$ESE = \begin{bmatrix} [C1, C11] \\ [C2, C22] \end{bmatrix}$$

$$D = \begin{bmatrix} \frac{C22+C2}{C22+C2+C11+C1} \\ \frac{C11+C1}{C22+C2+C11+C1} \end{bmatrix}$$

no state ⟺ no eigenvalue

only D *feedforward* matrix

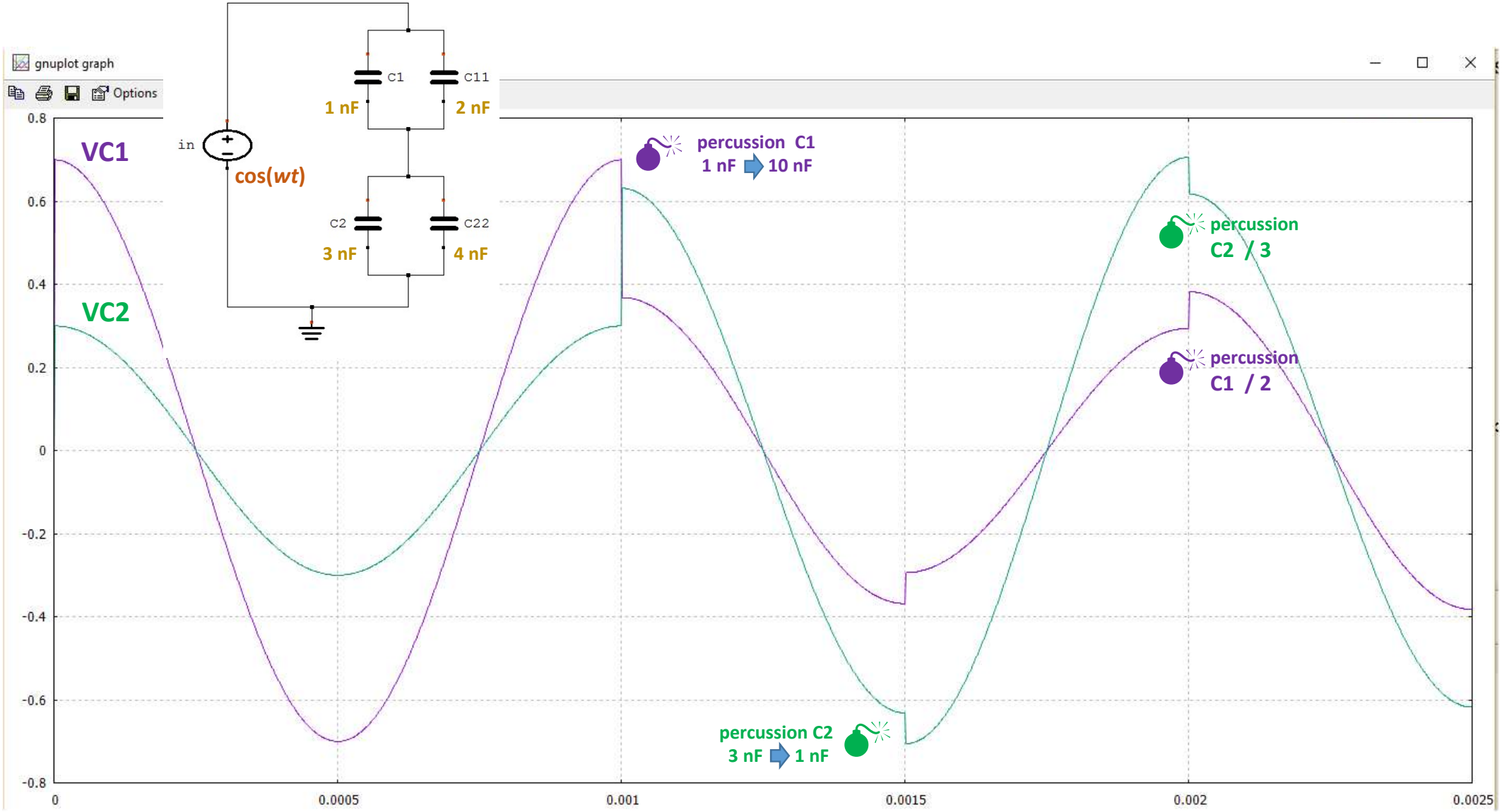
MIMO2XFER

$$XFER = C\,(\,|s|\,I - A\,)^{-1}\,B + D$$

... INPUTS : [in] OMITTED : n/a
... OUTPUTS : [V(C1),V(C2)]

$$1 \quad V(C1)/in = \frac{C22+C2}{C22+C2+C11+C1}$$

$$2 \quad V(C2)/in = \frac{C11+C1}{C22+C2+C11+C1}$$

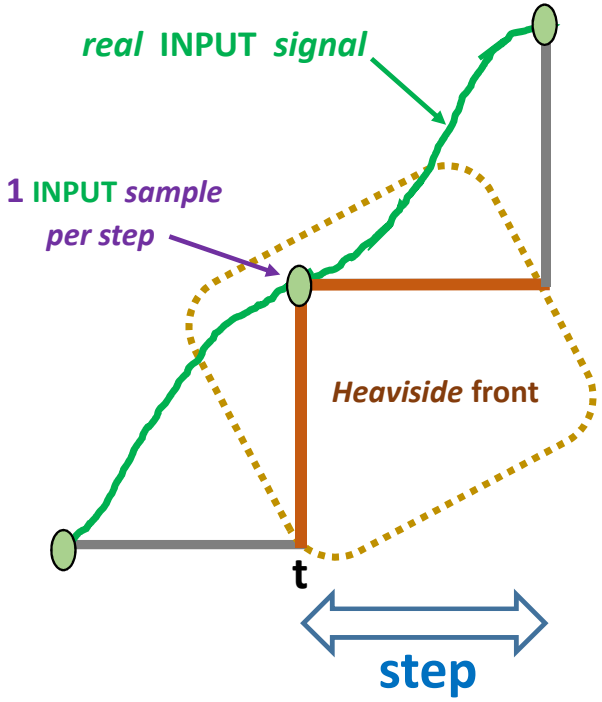

gnuplot graph
Options
VC1
VC2
in
cos(wt)
C1
C11
1 nF
2 nF
C2
C22
3 nF
4 nF
percussion C1
1 nF 10 nF
percussion
C2 / 3
percussion
C1 / 2
percussion C2
3 nF 1 nF
0.8
0.6
0.4
0.2
0
-0.2
-0.4
-0.6
-0.8
0
0.0005
0.001
0.0015
0.002
0.0025

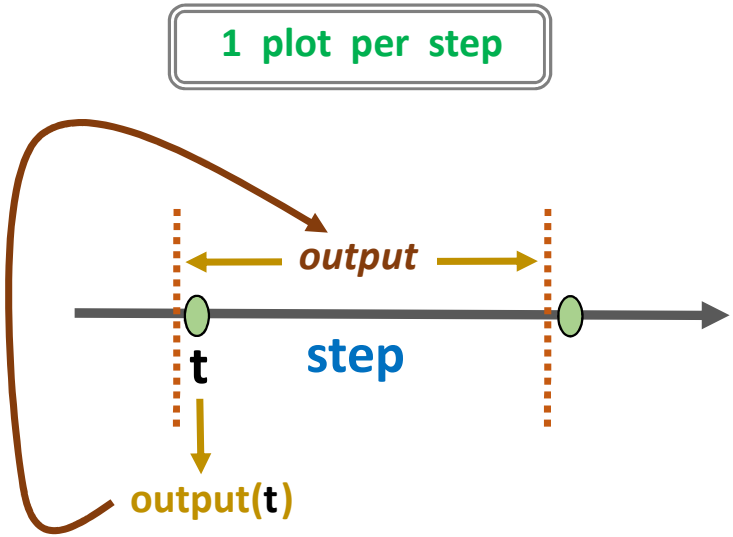
MATH／ANALOG VIEW

CLASSICAL SIMULATION

(almost always not accepting "on fly" component value change)

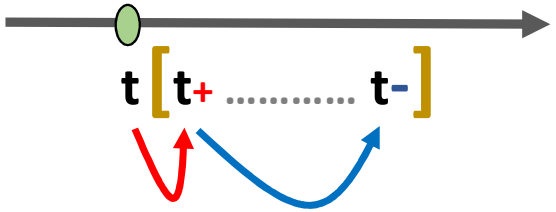
1 INPUT sample ⇨ 1 OUTPUT data



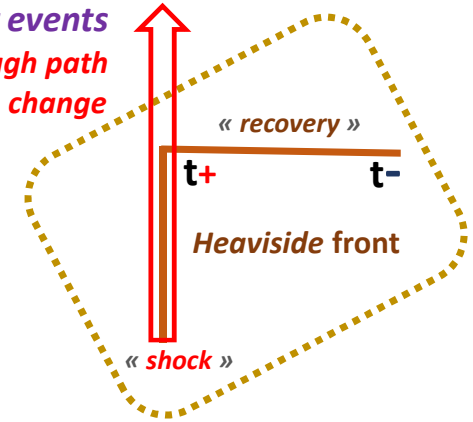


SARC SIMULATION

1 INPUT sample ⇒ 2 OUTPUT data

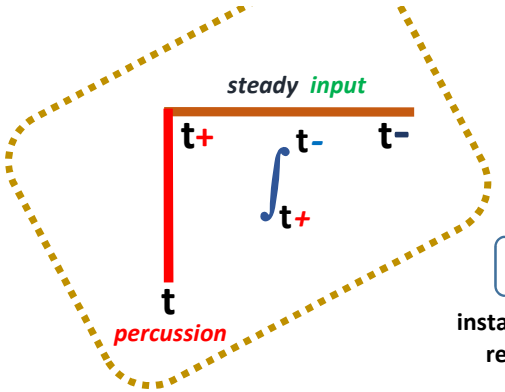


singular events
direct feedthrough path
or / and component(s) value change



step

2 consecutive algorithms

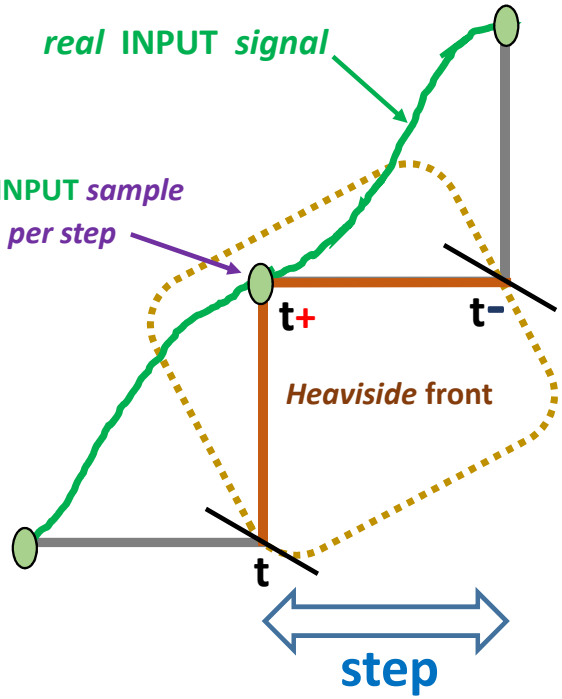


2 OUTPUT data per step

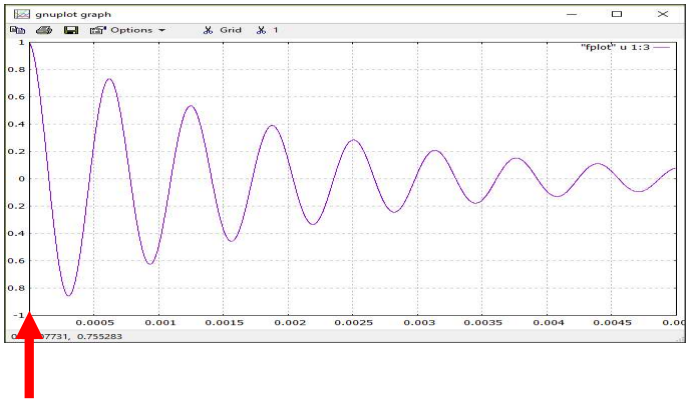
t+ instantaneous response

t- time constants response

step



step



shock ..... *recovery* .....▶

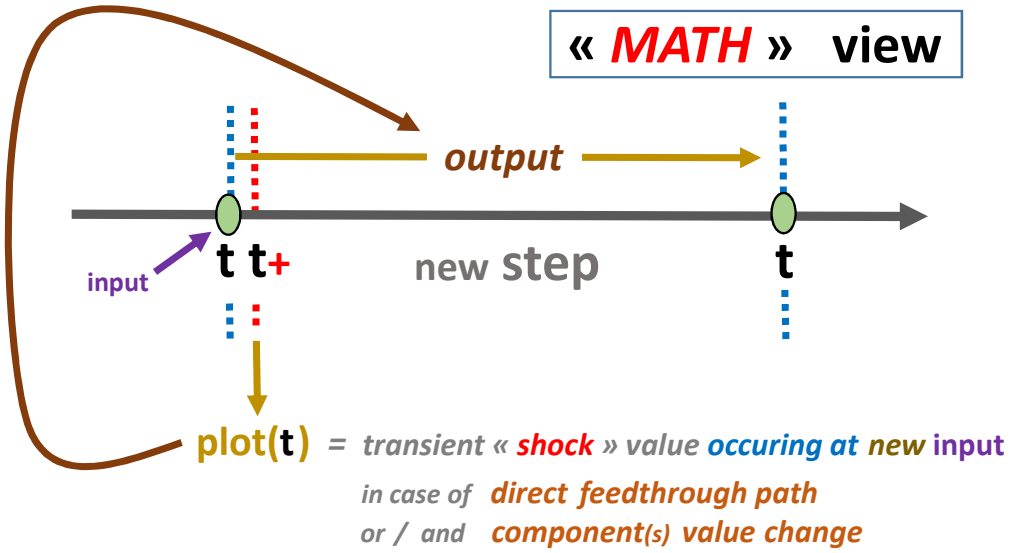
SARC SIMULATION

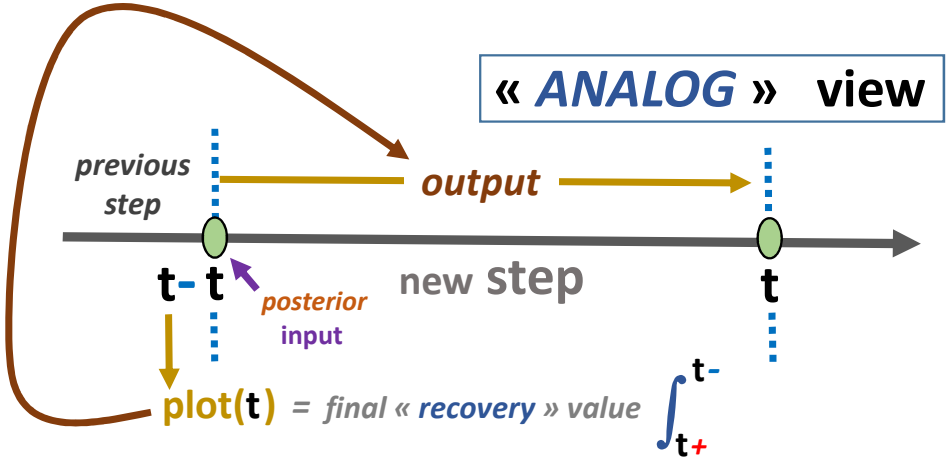
1 plot per step

The **VIEW** *is a* ***user choice*** *that* ***does not affect*** *the overall* ***accuracy of the simulation*** *which remains based on the* ***consecutive processing*** *of* ***both*** **t+** *and* **t-**

However, **this is only true** when the ***entire simulated circuit*** has been **edited** as a ***single SARC schematic***

ANALOG **view** is required to simulate ***assembly of blocks***

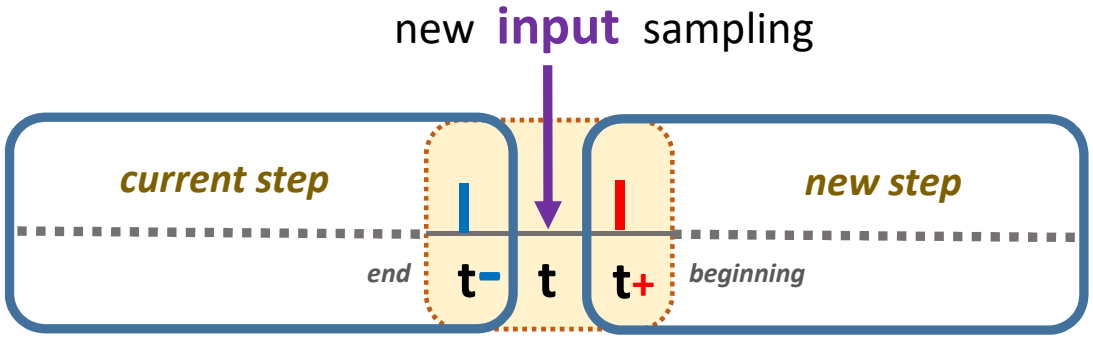




$$Y = C.X + D.U \quad \Leftarrow \int_{\Delta t} \quad \dot{X} = A.X + B.U$$

integration delay

direct feedthrough path ⇔ $D \neq 0$



if feedthrough **and** input changing ⇨ t+ ≠ t-

and / or **if** component percussions ⇨ t+ ≠ t-

otherwise input changing or unchanged ⇨ t+ = t-

because **SARC** *has its intrinsic* ***integration delay***

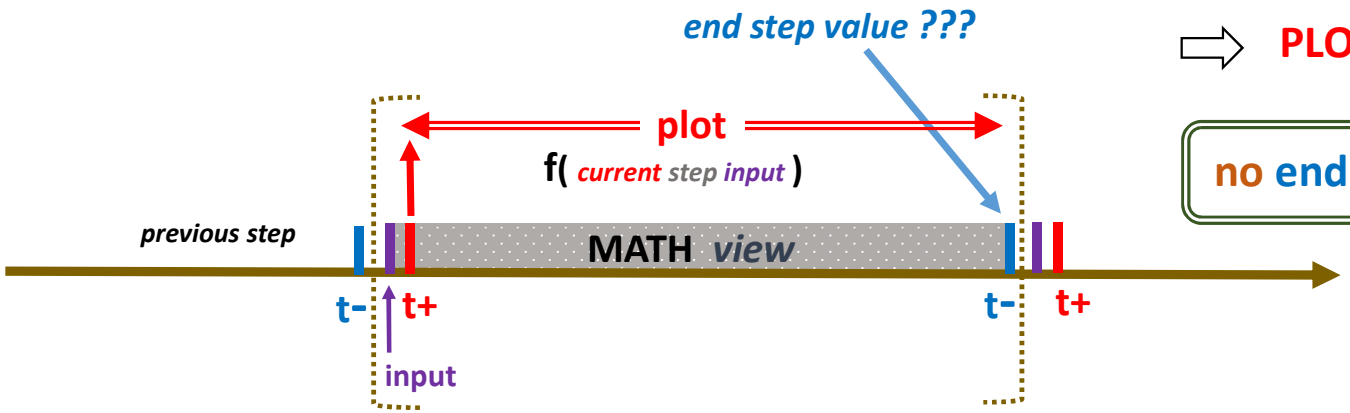
MATH = ANALOG

SARC uncertainty

PLOTS(t) = f(INPUTS[t + ε])

⇨ PLOTS are concomitant with INPUTS

no end value to enable assembly of blocks



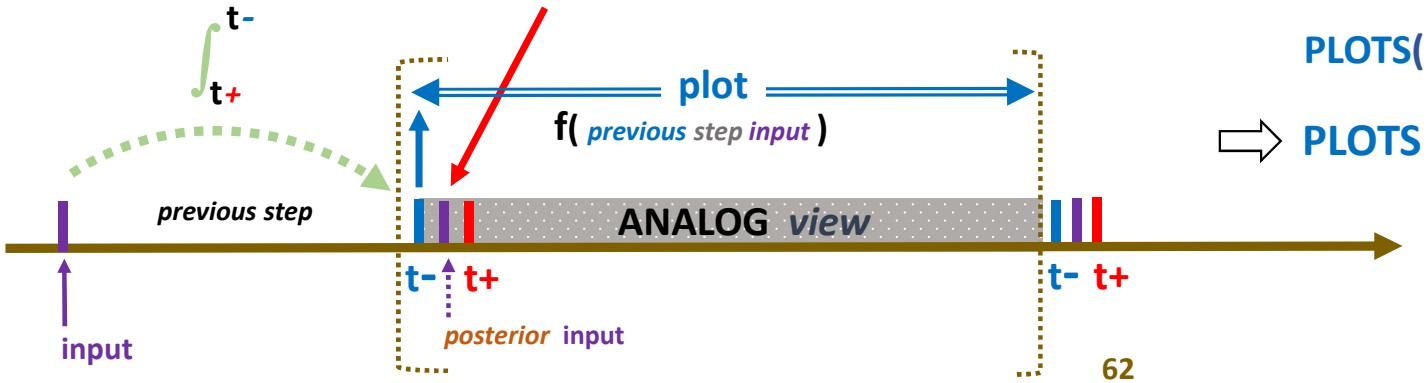
start step value ???

feedthrough ???

percussion ???

PLOTS(t) = f(INPUTS[t - ε])

⇨ PLOTS are postdated versus INPUTS

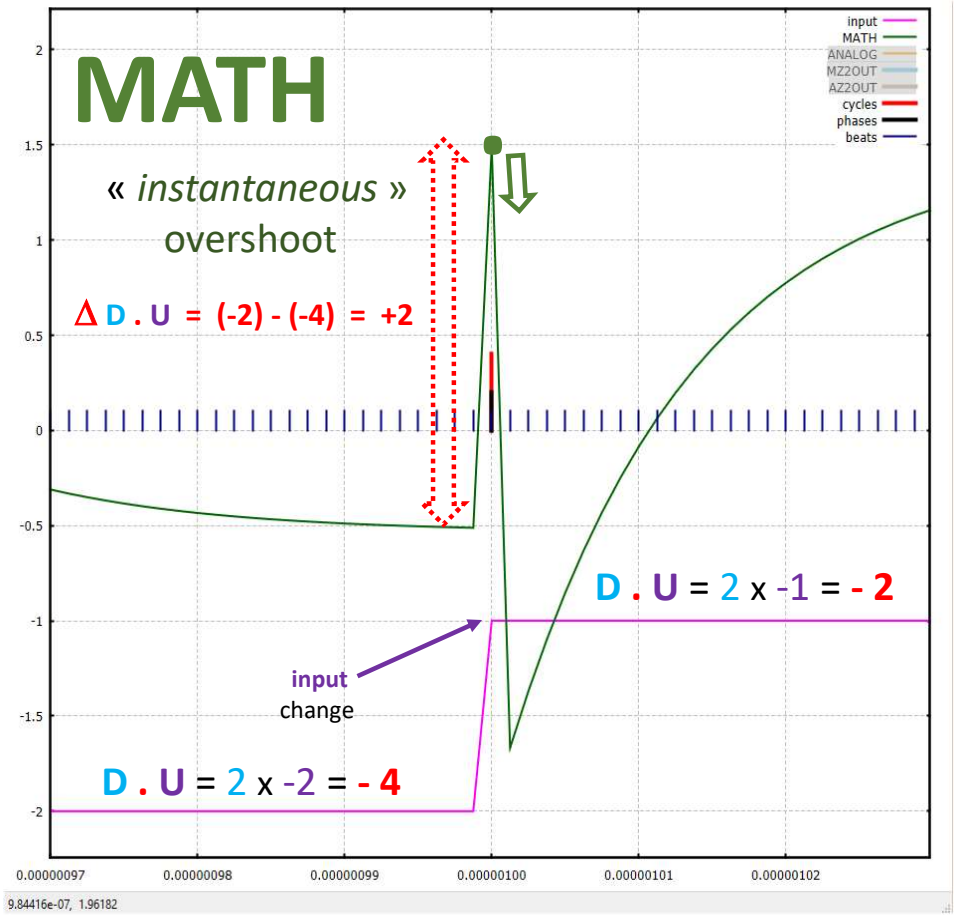


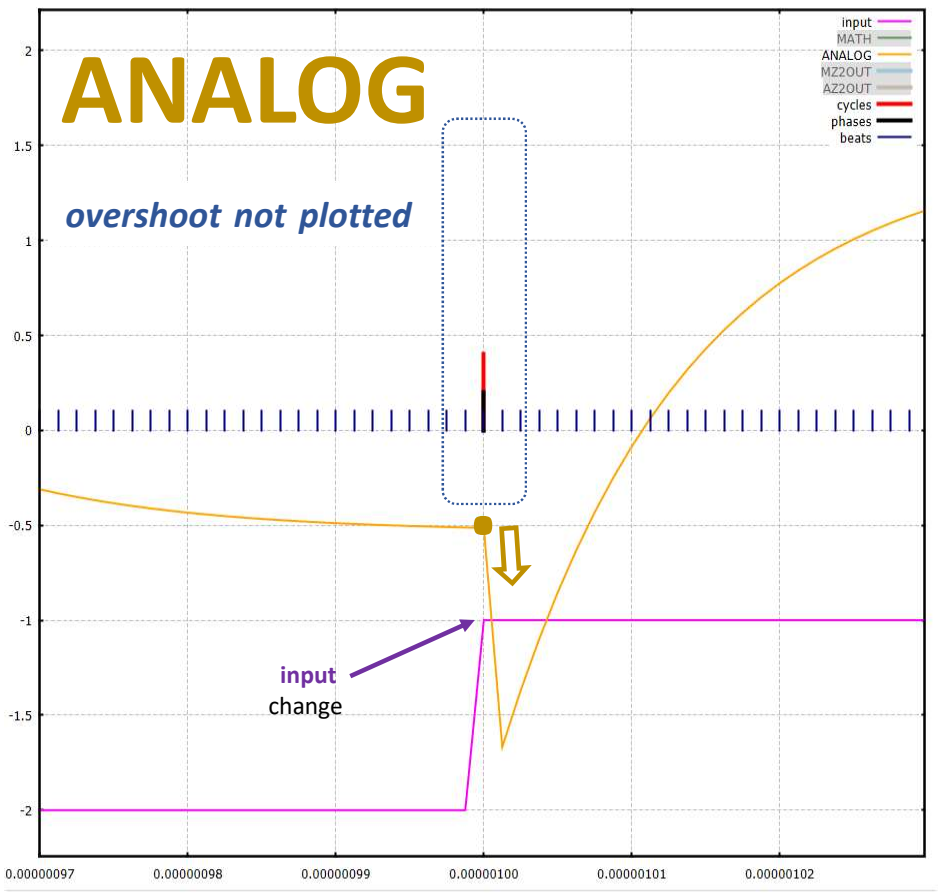
SARC uncertainty

$$Y = C \cdot X + D \cdot U$$

direct feedthrough path matrix $D = [\,2\,,\,0\,] \neq 0$

inputs vector $U = \begin{bmatrix} -2 \\ 0 \end{bmatrix}$ *followed by* $\begin{bmatrix} -1 \\ 0 \end{bmatrix}$





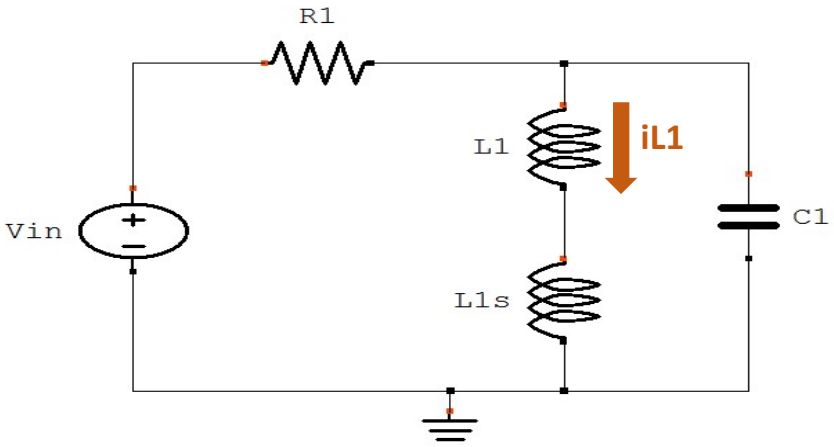
SARC uncertainty

$$Y = C \cdot \boxed{X} + D \cdot U$$

state

component value change

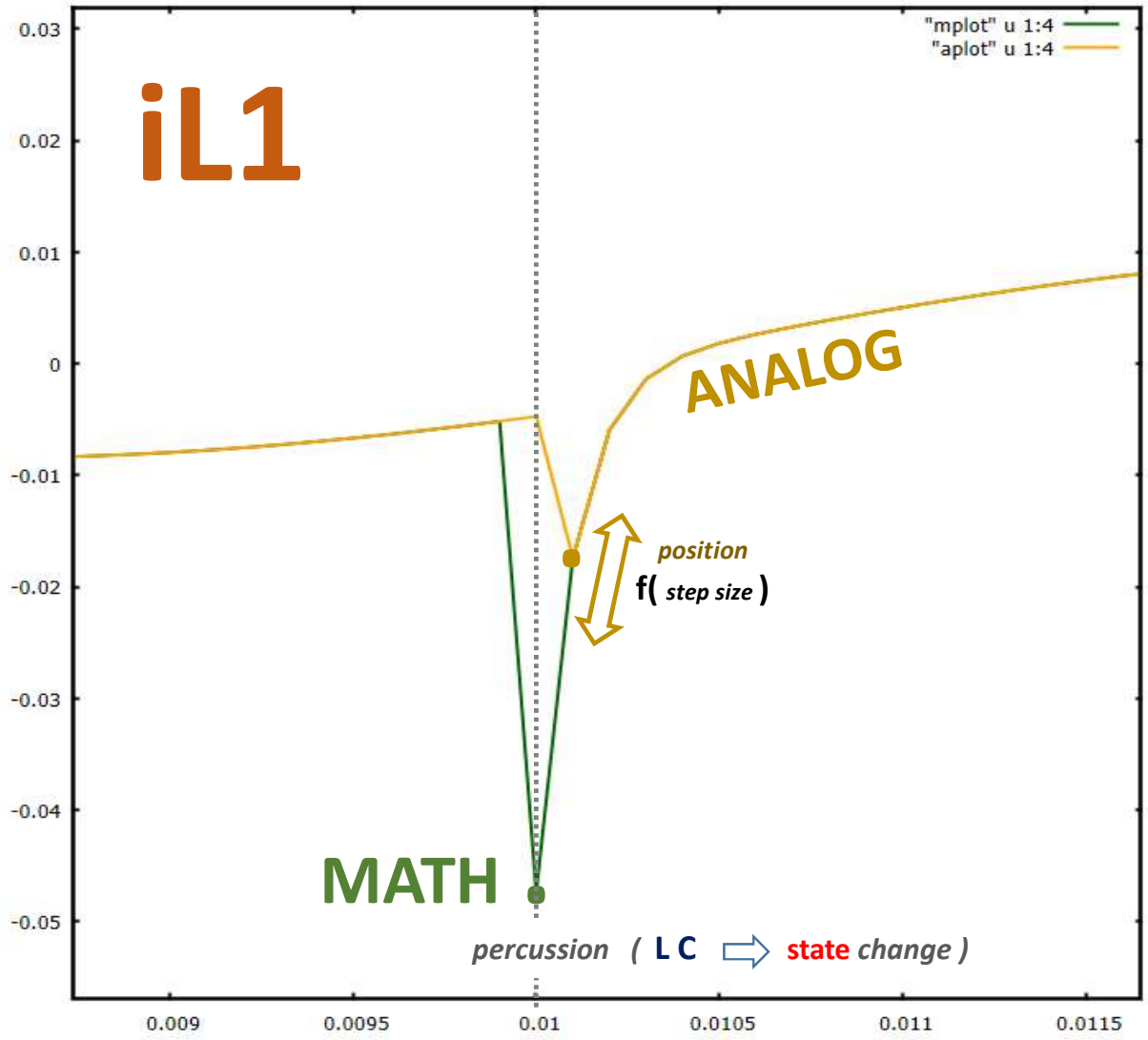
could affect **C** *or/and* **D** (and **X** if **L C**)



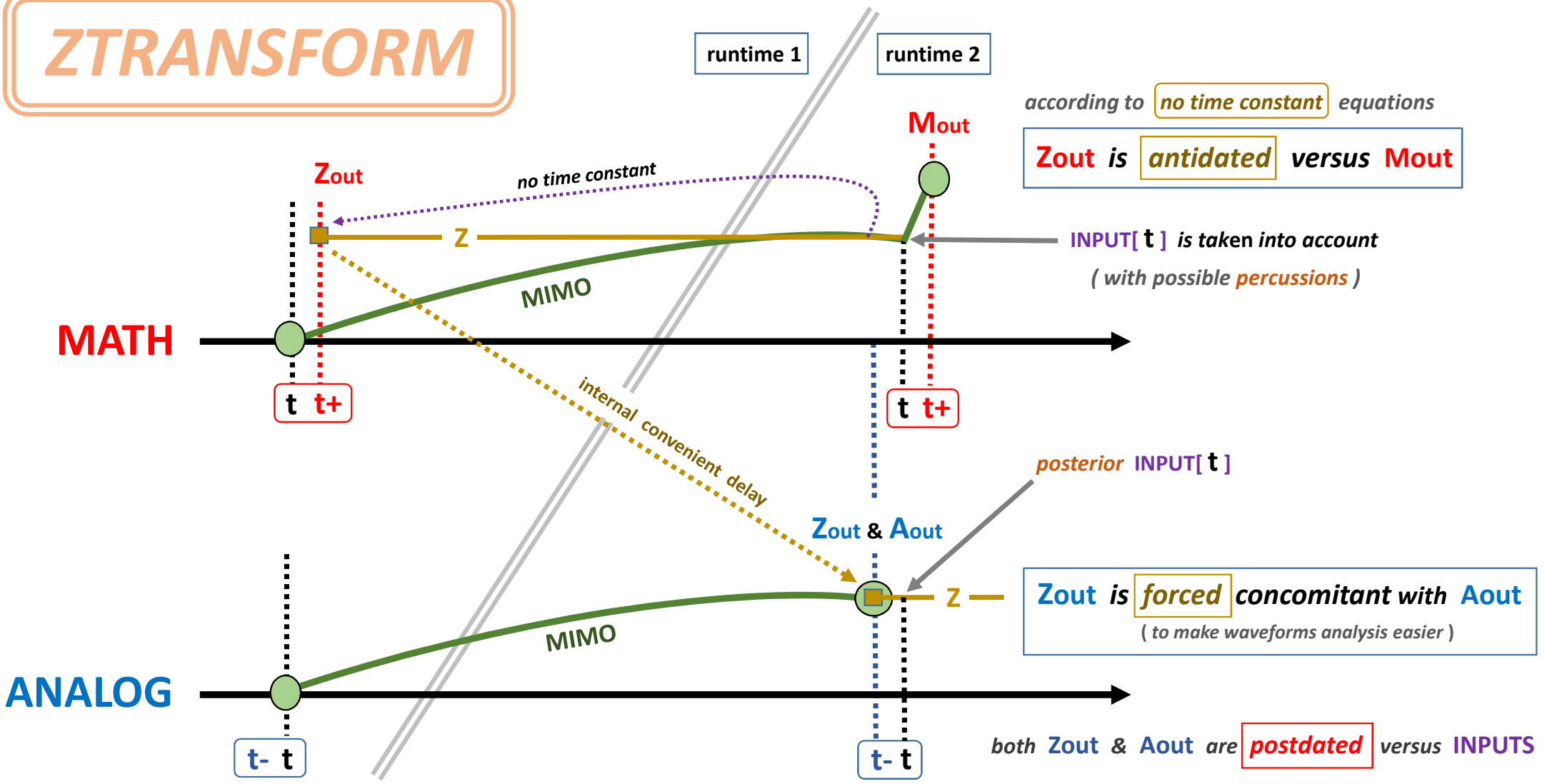
L1 = 90 mH
L1s = 10 mH

at t = **0.01**

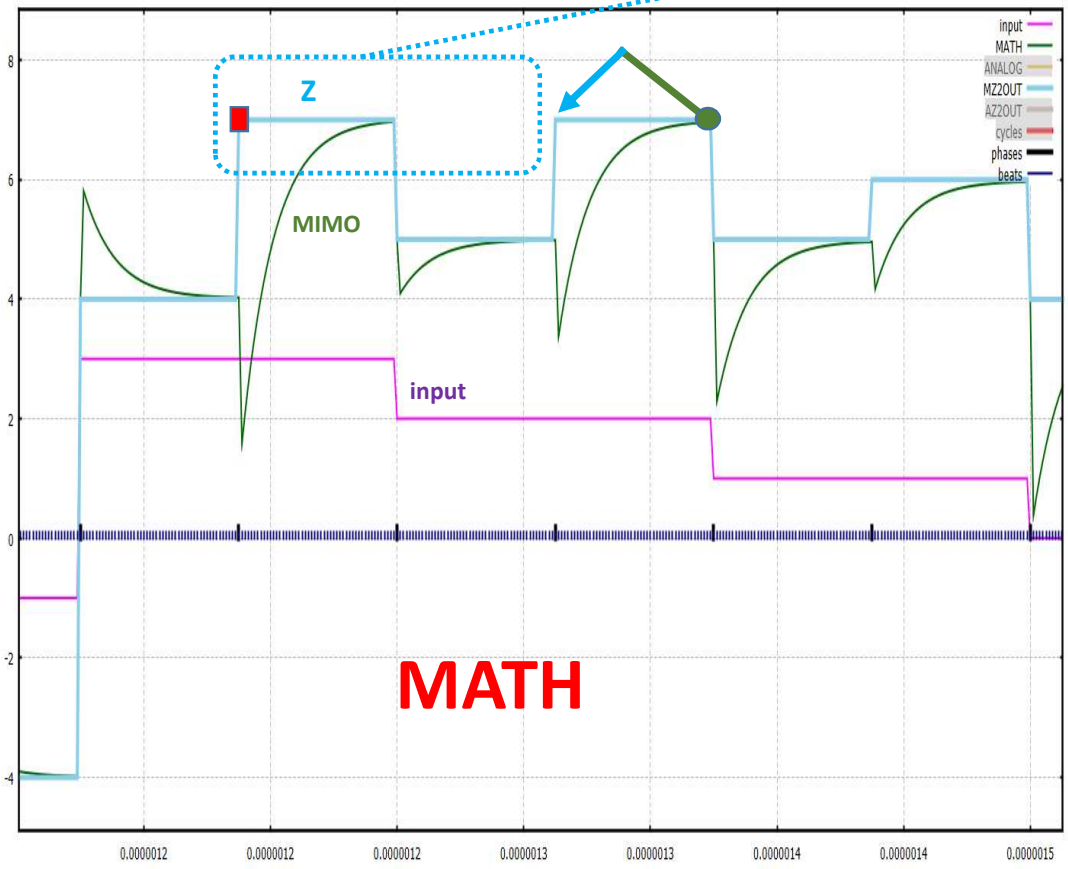
L1 = 6 mH
L1s = 4 mH



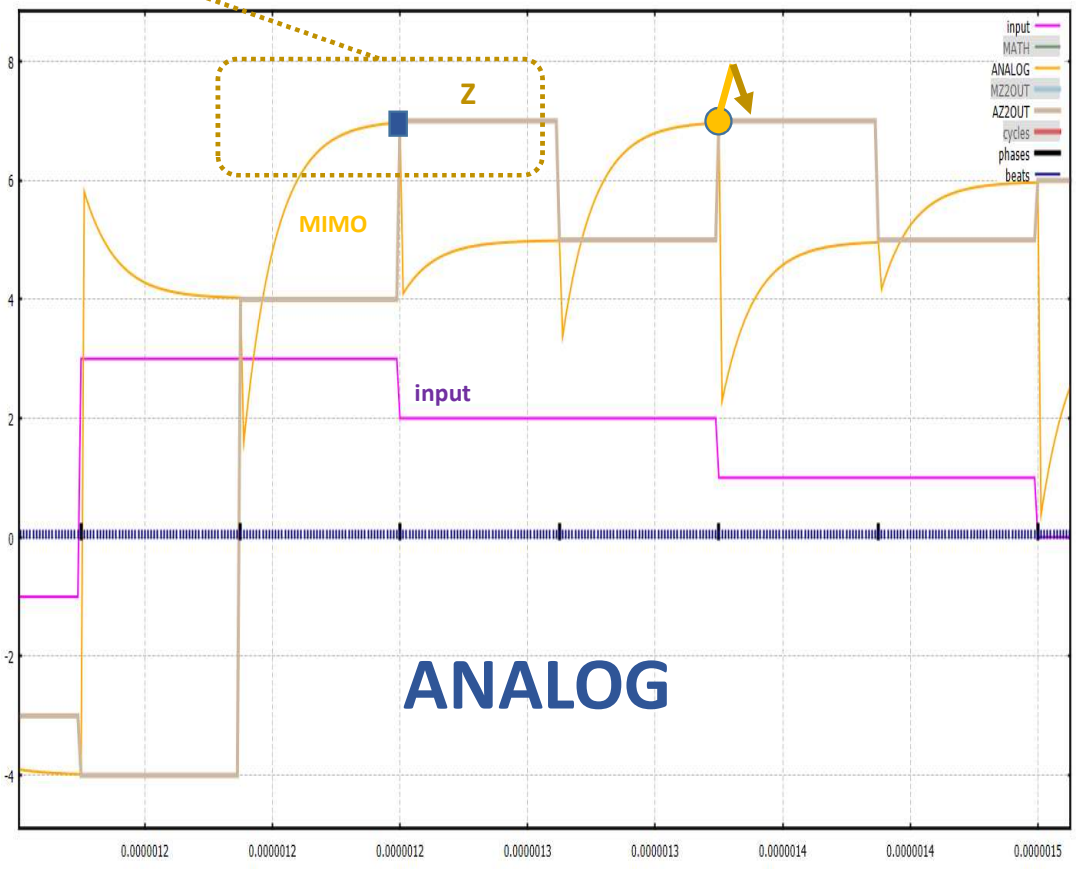
ZTRANSFORM


runtime 1
runtime 2
according to no time constant equations
Mout
Zout is antidated versus Mout
Zout
no time constant
Z
INPUT[t] is taken into account
(with possible percussions)
MIMO
MATH
t t+
internal convenient delay
t t+
posterior INPUT[t]
Zout & Aout
Z
Zout is forced concomitant with Aout
(to make waveforms analysis easier)
MIMO
ANALOG
t- t
t- t
both Zout & Aout are postdated versus INPUTS

Z *earlier than* **MIMO**



Z & **MIMO** *concomitant*

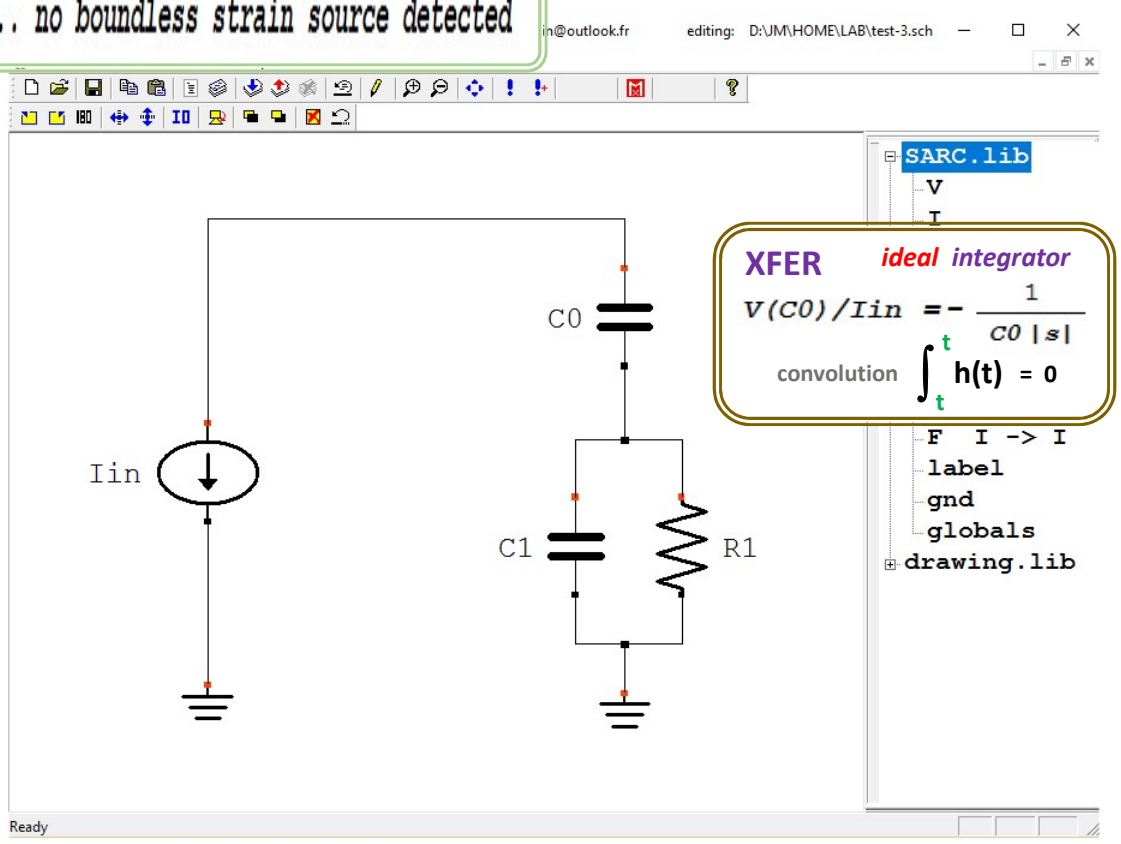


runtime WARNINGS

WARNING

Y = 0

... no boundless strain source detected



conversion MIMO ⇨ XFER

1 warning $V(C0)/Iin = 0$

2 proper $V(C1)/Iin = - \frac{R1}{C1\,R1\,|s| + 1}$

MIMO simulation

Warning : OUTPUT(V(C0)) = 0

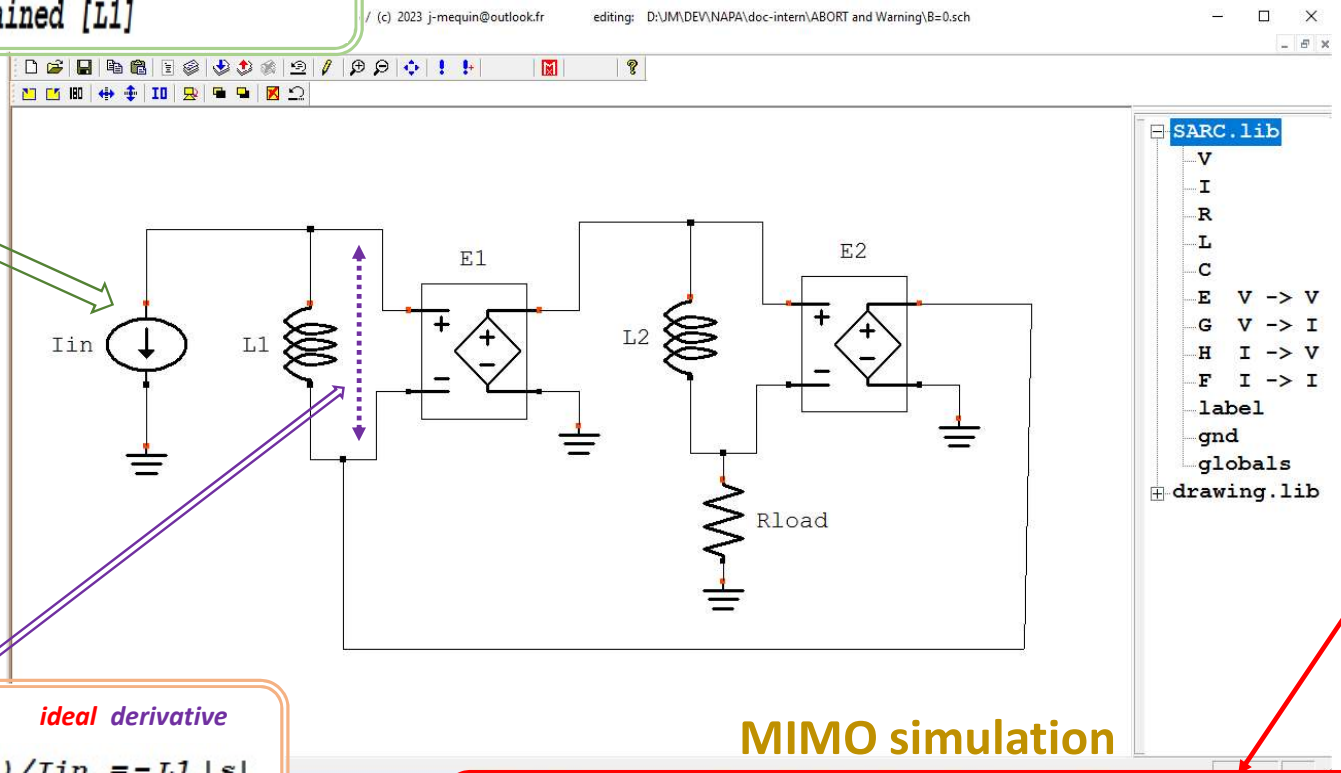
please note : the fact that **V(C0)** *is flagged does not prevent* **V(C1)** *to be correct*

WARNING

B = 0

```
### Warning : boundless strain sources [Iin]
==> LC boundless strained [L1]
```

boundless source



$$STATES = \begin{bmatrix} I(L2) \end{bmatrix}$$

A B C D

$$A = \begin{bmatrix} -\frac{Rload}{L2} \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 \\ -E1\,Rload \end{bmatrix}$$

$$D = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

XFER *ideal derivative*

```
improper  cV(E1)/Iin  = -L1 |s|
```

MIMO simulation

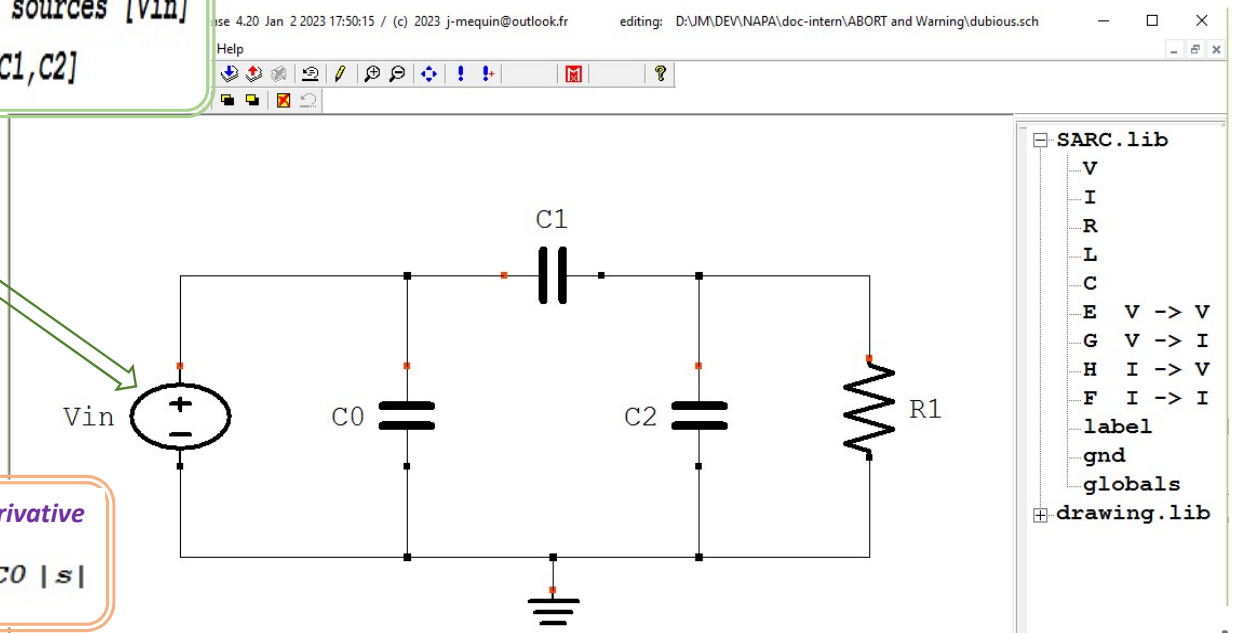
```
### Warning : OUTPUT( cV(E1) ) bad since B = 0
### Warning : OUTPUT( I(Rload) ) bad since B = 0
```

WARNING

$Y \neq 0$

```
### Warning : boundless strain sources [Vin]
==> LC boundless strained [C0,C1,C2]
```

boundless source



XFER *ideal derivative*

```
improper I(C0)/Vin =C0 |s|
```

MIMO simulation dubious output $\neq 0$

```
### Warning : OUTPUT( I(C1) ) D[dubious states]
```

conversion MIMO ⇒ XFER

biproper

$$\frac{C1^{2}\,|s|}{(C2+C1)^{2}\,R1\,|s|+C2+C1}$$

$\neq$

BUT corresponding XFER

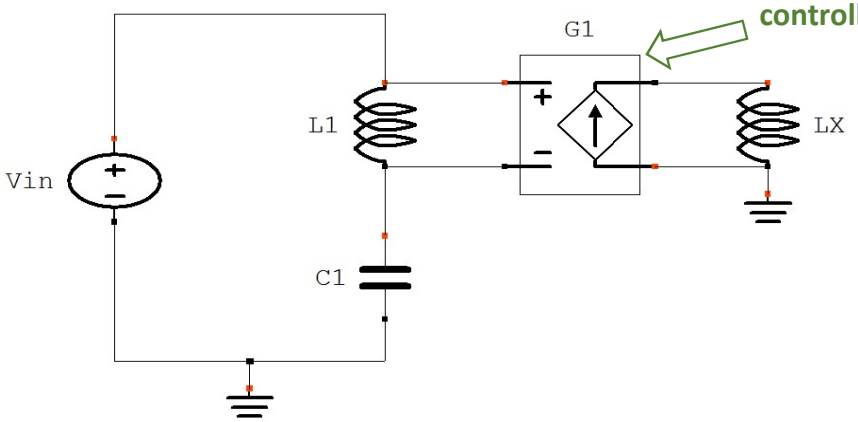
```
improper I(C1)/Vin
```

$$= \frac{C1\,C2\,R1\,|s|^{2}+C1\,|s|}{(C2+C1)\,R1\,|s|+1}$$

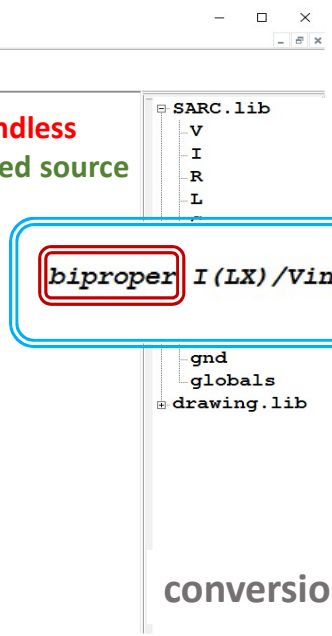
WARNING

$Y \neq 0$

```
### Warning : boundless strain sources [G1]
==> LC boundless strained [LX]
```



boundless controlled source



$$\text{biproper}\quad I(LX)/Vin = \frac{C1\,G1\,L1\,|s|^2}{C1\,L1\,|s|^2+1}$$

conversion MIMO ➡ XFER

MIMO simulation dubious output $\neq 0$

```
### Warning : OUTPUT( V(LX) ) C[dubious states]
```

$$\text{proper}\quad -\frac{G1\,LX\,|s|}{C1\,L1\,|s|^2+1}$$

$$\neq$$

BUT corresponding XFER

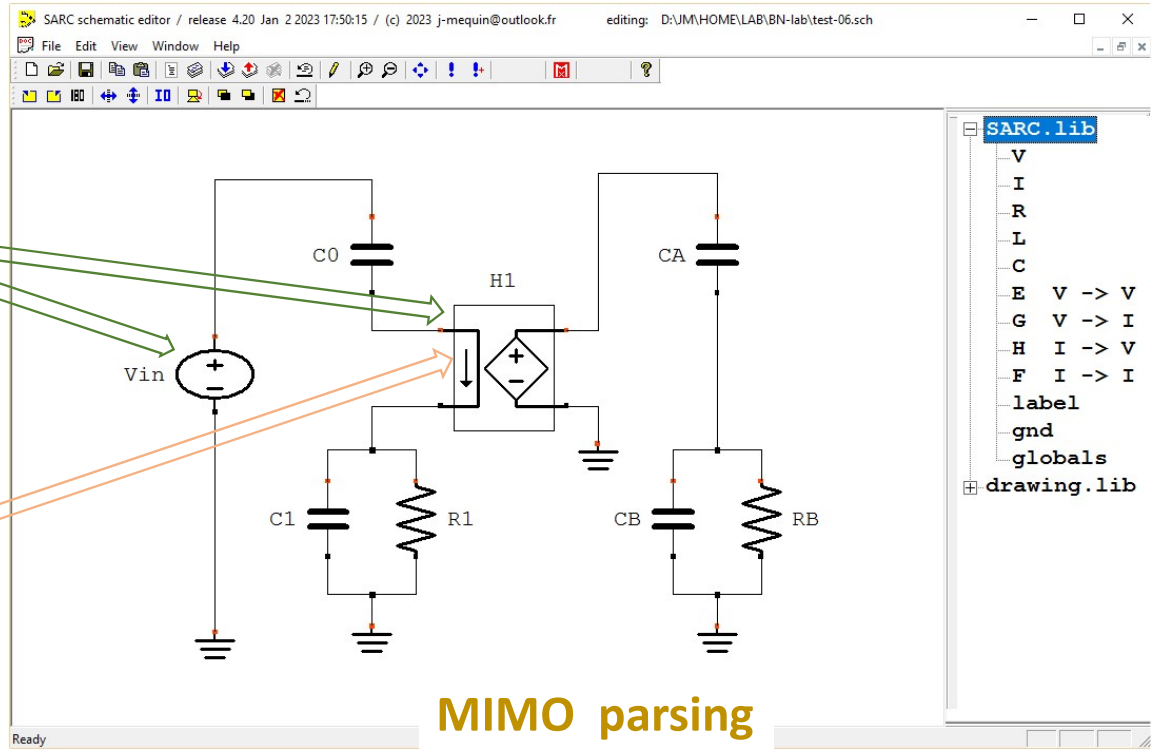
$$\text{improper}\quad V(LX)/Vin = \frac{C1\,G1\,L1\,LX\,|s|^3}{C1\,L1\,|s|^2+1}$$

BAD SCHEMATIC

ABORT

```
### Warning : boundless strain sources [Vin,H1]
==> LC boundless strained [C0,C1,CA,CB]
```

boundless sources



MIMO parsing

XFER

$$\text{improper}\ cI(H1)/Vin = \frac{C0\,C1\,R1\,|s|^2 + C0\,|s|}{(C1+C0)\,R1\,|s| + 1}$$

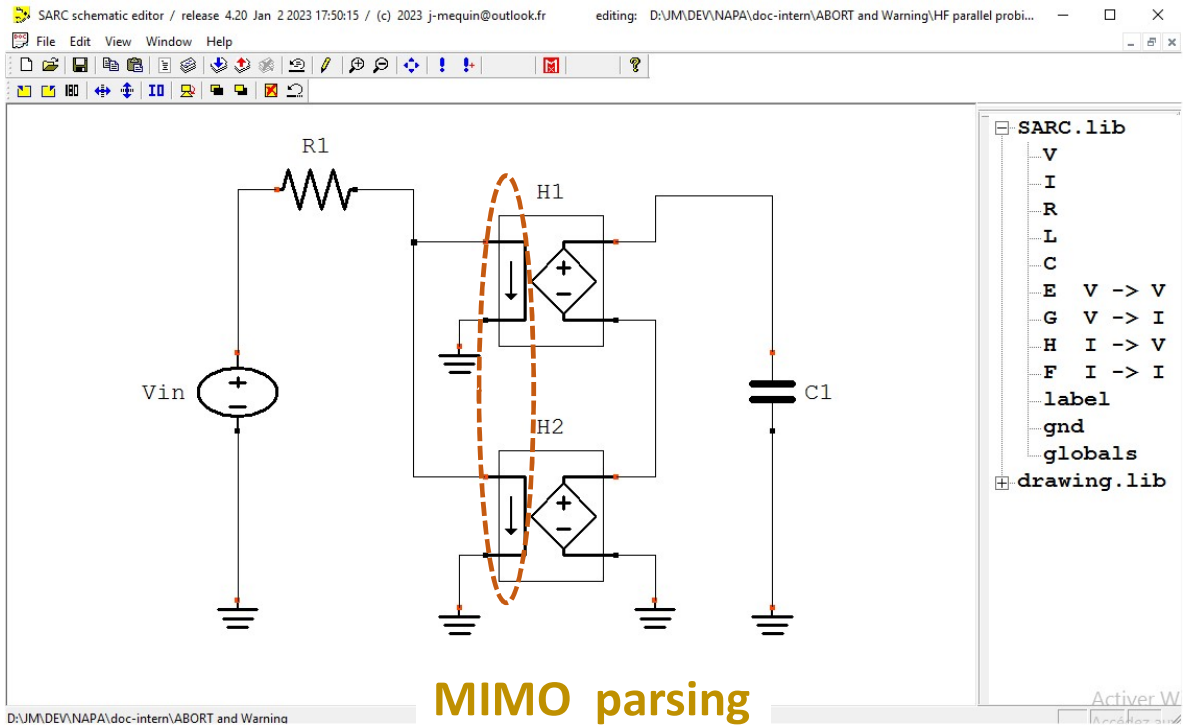
$$\left[\left[U\ X\ Vin, CA, \frac{C0\,C1\,CB\,H1\,|s|}{(C1+C0)\,(CB+CA)}\right], \left[U\ X\ Vin, CB, \frac{C0\,C1\,CA\,H1\,|s|}{(C1+C0)\,(CB+CA)}\right]\right]$$

*** ERROR: improper STATES ["CA","CB"]

BAD SCHEMATIC

ABORT

schematic may look good but may not be simulable



MIMO parsing

```
*** ERROR: parallel CURRENT probing for CONTROL side [["H1","H2"]]
```